

ON THE SOLVABILITY OF EVOLUTION  
EQUATIONS WITH VARIABLE  
OPERATOR COEFFICIENTS

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**Abstract:** In this paper we study nonlinear (linear) evolution equations in a Banach space with linear unbounded nondensely defined operator coefficients, for which the Cauchy problem is well-posed solvable.

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1. In this paper the solvability of the Cauchy problem for the evolution equation

$$\frac{du(t)}{dt} = A(t)u(t) + f(t) \quad (0 < t \leq T), \quad u(0) = u_0 \quad (1)$$

in a Banach space  $E$  is studied. Here,  $A(t)$  is a linear operator for each fixed  $t \in [0, T]$  with the domain of definition  $D(A(t))$ , and  $f(t)$ ,  $t > 0$  is a given

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function from  $E$ ;  $u_0$  is an element of  $E$ . A function  $u(t)$  is called the solution of (1) if:

- 1)  $u(t)$  is continuous on  $[0, T]$  and continuously differentiable on  $(0, T]$ .
- 2)  $u(t)$  satisfies (1) and the initial condition  $u(0) = u_0$ .
- 3) the function  $A(t)u(t)$  is continuous on  $(0, T]$ .

The Cauchy problem for evolution equations of the form (1) is studied in various aspects by many authors (see, for example, [1-2] and references therein). The theory of evolution equations with variable operators, which generate an analytic semigroup was developed by Sobolevski [3] and H. Tanabe [4]. The evolution equation with a nonanalytic semigroup in the case of the nonconstant domain  $D(A(t))$  was considered by S.Y. Yakubov in [2].

In [5], problem (1) was investigated under the condition that the set  $D(A(t))$  is not dense in  $E$ . Moreover, it was assumed in [5] that the operator-function  $A(t)$  is continuously differentiable, and the properties of the resolvent of  $A(t)$ , are used. In [6], this problem was studied in the case when  $A^{-1}(t)$  is not differentiable, and the properties of the resolvent of  $A(t)$  are not used. However, it was assumed in [6] that the domain of definition of the operator-function  $A(t)$  is constant.

In [7], problem (1) was investigated for a variable domain of definition  $D(A(t))$  of the operator  $A(t)$  without using properties of the resolvent of this operator and the differentiability of  $A^{-1}(t)$ . We note that in the above-mentioned papers, it was assumed that the operator-function  $A(t)A^{-1}(s)$  is uniformly continuous in the sense of Hölder with respect to  $t$  in the uniform operator topology.

In [8], a new condition on the continuity of the operator-function  $A(t)A^{-1}(s)$  was introduced, which is weaker than previous ones. However, in this paper it is assumed that the domain of definition  $D(A(t))$  of the positive operator  $A(t)$  is everywhere dense in  $E$  and does not depend on  $t$ .

In this paper problem (1) is studied in the case of a variable domain of definition  $D(A(t))$  of the operator  $A(t)$ , which is not dense in  $E$ . Moreover, we introduce a new weak condition on the continuity of the operator-function  $A(t)A^{-1}(s)$ ,  $s \leq t$  and of the function  $f(t)$ .

In order to study problem (1) we assume that the operator  $A(t)$  satisfies the following conditions:

1<sup>0</sup>. The linear operator  $A(t)$ ,  $t \in [0, T]$  with the domain of definition  $D(A(t))$  satisfies the condition

$$\| R(\lambda, A(t)) \| \leq c |\lambda|^{-\beta} \quad , \quad | \arg \lambda | \leq \frac{\pi}{2} + \eta \quad ,$$

for a certain

$$\beta \in \left( \frac{1}{2} \quad , \quad 1 \right] \quad , \quad \eta > 0.$$

2<sup>0</sup>. The embedding  $D(A(\tau)) \subset D(A(t))$  holds for  $0 \leq \tau \leq t \leq T$  and the inequality

$$\| [A(t) - A(\tau)A^{-1}(s)] \| \leq cw(|t - \tau|) \quad ,$$

holds for  $0 \leq s \leq \tau, t \leq T$ , where the function  $w(t)$  is positive, monotonically increasing on the interval  $(0, \infty)$ , and

$$\int_0^T \frac{w^p(r)}{r^p} dr < \infty \quad , \tag{2}$$

for a certain  $p \in \left[ \frac{1}{2\beta - 1}, \infty \right)$  (for  $\beta = 1, p = 1$ , see [8]).

For example, condition (2) is satisfied for the functions:

- 1)  $w(r) = c |\log r|^\alpha$ , for  $\alpha < -2, p = 1$ .
- 2)  $w(r) = c \frac{\log(1+r)}{r^{\frac{1}{p}} |\log r|^\alpha}$ , for  $\alpha > \frac{p+1}{p}, p \geq 1$ .

We note that these functions are not uniformly continuous in the sense of Hölder in a neighbourhood of  $r = 0$ .

Let us introduce the functional space

$$F_{p,\mu}^\alpha((0, T); E) = \{ f(\cdot) : f \in C((0, T); E) \quad ,$$

$$\begin{aligned} & \| f \|_{F_{p,\mu}^\alpha((0, T); E)} \\ & = \sup_{t \in (0, T]} \| t^\mu f(t) \| + \sup_{0 \leq \tau < t \leq T} \int_\tau^t \frac{\| f(t) - f(s) \|^p}{|t - s|^{p\alpha}} s^{\mu p} ds \quad \} \quad , \quad \mu \geq 0. \end{aligned}$$

**Theorem 1.** *Let assumptions 1<sup>0</sup> and 2<sup>0</sup> hold. Then there exists an operator-function  $U(t, \tau) \in B(E)$ , defined for  $0 \leq \tau \leq t \leq T$ , with the following properties:*

- 1)  $U(t, s)$  is continuous for  $0 \leq \tau \leq t \leq T$ .

2) The equality  $U(t, \tau) = U(t, s)U(s, \tau)$  is valid for  $0 \leq \tau < s < t \leq T$ .

3) The range of  $U(t, \tau)$  belongs to  $D(A(t))$ , and the operator-function  $A(t)U(t, \tau)$  is continuous for  $0 \leq \tau \leq t \leq T$ .

4) For any  $0 \leq \tau \leq t \leq T$

$$\frac{\partial U(t, \tau)}{\partial t} = A(t)U(t, \tau).$$

5) For any  $0 \leq \tau \leq t < t + \Delta t \leq \xi \leq T$ , the following estimates hold

$$\| A^\alpha(t)U(t, \tau)A^{-\delta}(\tau) \| \leq c(\alpha, \beta, \delta) |t - \tau|^{\delta + \beta - \alpha - 1} \quad (0 \leq 1 - \beta \leq \delta \leq \alpha < 1 + \epsilon),$$

$$\| A^\alpha(\xi)[U(t + \delta t, \tau) - U(t, \tau)]A^{-\delta}(\tau) \| \leq c(\alpha, \beta, \delta, \nu)\Delta t^{2(\beta - 1) + \nu - \alpha} |t - \tau|^{\delta + \beta - \nu - 1} w(\Delta t)$$

$(0 \leq \alpha \leq 1), 0 \leq 1 - \beta \leq \delta \leq \nu < 1 + \epsilon, 0 \leq \nu - \alpha < 1$ .

If either  $\xi = t + \Delta t$  or  $\delta < \gamma$ , then in the last estimate, one can take  $\gamma - \alpha = 1$ .

**Theorem 2.** Let assumptions 1<sup>0</sup> and 2<sup>0</sup> hold, and let

3<sup>0</sup>.  $\| f(t + \Delta t) - f(t) \| \leq ct^{-\mu}w(|\Delta t|), \mu \in [0, \beta]$ .

4<sup>0</sup>.  $u_0 \in D(A^\delta(0))$  for a certain  $\delta \in (1 - \beta, 1]$ .

Then problem (1) has the unique solution  $u(t)$  defined by the formula

$$u(t) = U(t, 0)u_0 + \int_0^t U(t, s)f(s)ds. \tag{3}$$

In the case of  $w(t) = t^\alpha$  Theorems 1 and 2 partially intersect with results by S.Y. Yakubov [2], p. 134, and Y.T. Silchenko [7].

**Theorem 3.** Let assumptions 1<sup>0</sup> and 2<sup>0</sup> hold. Suppose that:

5<sup>0</sup>.  $f \in F_{p, \mu}^\alpha((0, T); E)$  for certain  $\mu \in [0, \frac{p-1}{p}), \alpha \in (\frac{p+1}{p} - \beta, 1]$  and  $p \in [\frac{1}{2\beta - 1}, \infty)$ .

6<sup>0</sup>.  $u_0 \in D(A^\delta(0))$  if  $D(A(0)) \neq E$ ,  $\delta \in (1 - \beta, 1]$ , and  $u_0 \in E$ , if  $\overline{D(A(0))} = E, \beta = 1, p = 1$ .

Then problem (1) has the unique solution  $u(t)$  defined by (3).

We note that if  $D(A(t)) = D(A), \overline{D(A)} = E$  and  $\beta = 1$ , Theorem 3 intersects with results by S. Kawatsu [8].

2. Let us consider the Cauchy problem for the nonlinear equation

$$\frac{du(t)}{dt} = A(t, u(t))u(t) + f(t, u(t)) \quad (0 < t \leq t_0), \quad t_0 \in (0, T], \quad (4)$$

$$u(0) = u_0, \quad (5)$$

in a Banach space  $E$ .

**Theorem 4.** *Let the following conditions be satisfied:*

7<sup>0</sup>. For any  $t \in [0, T]$ ,  $A_0(t) = A(t, u_0)$  is a linear closed operator with the domain of definition  $D(A_0(t))$ , which is not necessarily dense in  $E$ , and in  $E$ , the operator  $A_0(t)$  has the compact inverse operator  $A_0^{-1}(t)$ .

8<sup>0</sup>. For certain  $\eta > 0, \beta \in (\frac{1}{2}, 1], p \in [\frac{1}{2\beta-1}, \infty)$  and any  $t \in [0, T]$  the operator  $A(t, u_0) + \lambda I$  has the bounded inverse operator, and

$$\|R(\lambda, A(t, u_0))\| \leq c |\lambda|^{-\beta}, \quad |\arg \lambda| \leq \frac{\pi}{2} + \eta, \quad |\lambda| \rightarrow \infty.$$

9<sup>0</sup>. For  $\alpha \in [1 - \beta, 1), p \in (0, 1]$  and any  $0 \leq \tau \leq t \leq T$  and  $u, v \in E$  with  $\|u\| \leq R, \|v\| \leq R$  the following relation holds:  $D(A(\tau, A_0^{-\alpha}v)) \subset D(A(t, A_0^{-\alpha}v))$ . Moreover, for any  $0 \leq s < \tau, t \leq T$ ,

$$\| [A(t, A_0^{-\alpha}u) - A(t, A_0^{-\alpha}v)] A_0^{-1}(s) \| \leq c(R) [w(|t - \tau|) + \|u - v\|^\rho],$$

where  $A_0 = A(0, u_0)$  and the function  $w(t)$  satisfies (2).

10<sup>0</sup>. For any  $\tau, t \in [0, T], \|u\| \leq R, \|v\| \leq R$ ,

$$\| f(t, A_0^{-\alpha}u) - f(t, A_0^{-\alpha}v) \| \leq c(R) [w(|t - \tau|) + \|u - v\|^\rho],$$

11<sup>0</sup>.  $u_0 \in D(A_0^{-\rho})$ , for a certain  $\delta > \alpha$  and  $\|A_0^\alpha u_0\| \leq R$ .

Then in some interval  $[0, t_0]$ , there exists at least one solution of problem (4)-(5), which is continuous for  $t \in [0, t_0]$  and continuously differentiable for  $t > 0$ .

If  $\rho = 1$ , then even without the suggestion of compactness of the operator  $A_0^{-1}(s)$ , problem (4)-(5) has the unique solution, which can be found by the method of successive approximations.

We note that if  $D(A(t)) = D(A)$ ,  $\overline{D(A)} = E$  and  $\beta = 1$ ,  $w = t^\alpha$ , then Theorem 4 is due to P.E. Sobolevski [3].

**3.** There are numbers of examples of boundary value problems in various (with respect to  $t$ ) domains linear and nonlinear differential equations considered.

For example, let  $\Omega_t$  be a domain in  $R^n$  with a smooth boundary  $\Gamma_t$ , and let  $Q_t$  be a noncylindered variable domain in  $R^{n+1}$  of the form  $Q_t = \bigcup_{0 < t < T} \{t\} \times \Omega_t$ .

Denote by  $\sum_T = \bigcup_{0 < t < T} \{t\} \times \Gamma_t$  the lateral bound of  $Q_t$  (see [9]).

In  $Q_t$  we consider the boundary value problem

$$\frac{\partial u}{\partial t} = \sum_{i,k=1}^n a_{ik}(t, x, u, \frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n}) \frac{\partial^2 u}{\partial x_i \partial x_k} + f(t, x, u, \frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n}), \quad \text{in } Q_{t_0}, \quad (6)$$

$$u(t, x) = 0 \quad \text{in } \sum_{t_0}, \quad (7)$$

$$u(0, x) = 0 \quad \text{in } \Omega_0, \quad (8)$$

Let the following conditions be satisfied:

1) For any  $t_0 \in [0, T]$  and  $u_0(x)$  the operator

$$\sum_{i,k=1}^n a_{ik}(t, x, u, \frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n}) \frac{\partial^2 u}{\partial x_i \partial x_k}$$

is strongly elliptic.

$$2) | a_{ik}(t, x, u_0(t, x), \dots) - a_{ik}(\tau, x, v_0(t, x), \dots) | \leq c \left[ | \log | t - \tau | |^\alpha + \| u_0 - v_0 \|_{W_2^1(\Omega_0)}^\rho \right].$$

$$3) | f(t, x, u_0(t, x), \dots) - f(\tau, x, v_0(t, x), \dots) | \leq c \left[ | \log | t - \tau | |^\alpha + \| u_0 - v_0 \|_{W_2^1(\Omega_0)}^\rho \right]$$

Using Theorem 4 one can prove a theorem on existence and uniqueness of a generalized solution of problem (4)-(6) without any restrictions on the growth of nonlinearities.

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