

ON  $\gamma$ -CONVERGENCY AND  $\psi$ -CONVERGENCY  
IN GENERALIZED TOPOLOGICAL SPACES

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**Abstract:** The aim of this article is to investigate  $\gamma$ -convergency and  $\psi$ -convergency in generalized topologies.

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### 1. Introduction

Á. Császár [3], [4], [5] defined generalized open sets in generalized topological spaces. Semi-convergency and pre-convergency were introduced and studied in [1] and [7], respectively. Convergency which is one of the most important concepts in general topology is examined in generalized topologies in this paper. Two concepts named  $\gamma$ -convergency and  $\psi$  convergency are introduced. Furthermore,  $\mu$ -convergency which is a more generalized one is introduced.

### 2. Preliminaries

Let  $X$  be a non-empty set and  $\gamma : \wp(X) \rightarrow \wp(X)$  be a monotonic mapping

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(i.e.  $A \subset B$  implies  $\gamma A \subset \gamma B$ ), see [2], [3], [4]. The collection of all mappings having the property monotonic is denoted by  $\Gamma(X)$  (see [2]). A set  $A \subset X$  is said to be  $\gamma$ -open iff  $A \subset \gamma A$  (see [2]). A collection  $g$  of subsets of  $X$  is said to be generalized topology (briefly, GT) on  $X$  iff  $\emptyset \in g$  and  $G_i \in g$  for  $i \in I \neq \emptyset$  implies  $G = \bigcup_{i \in I} G_i \in g$  (see [2]). The collection of all GT's on  $X$  is denoted by  $\mathcal{B}(X)$ . It is obvious that  $\gamma$ -open sets constitute a GT. If  $\tau$  is a topology on  $X$  in usual sense and we write  $c$  for  $cl$ ,  $i$  for  $int$  with respect to  $\tau$  the  $c$  and  $i$  are all elements of  $\Gamma(X)$ .

A subset of a topological space  $(X, \tau)$  is semi-open [5] (rep. pre-open, see [6]) if  $A \subset (cl(intA))$  (resp.  $A \subset int(clA)$ ), where  $intA$  denotes the interior of  $A$  and  $clA$  denotes the closure of  $A$ . A sequence  $x_n$  is said to be semi-converges [1] (resp. pre-converges, see [7]) to a point  $x$  in  $X$  if  $x_n$  is eventually in every semi-open (resp. pre-open) set containing  $x$ .

Let  $\psi : X \rightarrow \wp(\wp(X))$  satisfy  $x \in V$  for  $V \in \psi(x)$ . Then we say that  $V \in \psi(x)$  is a generalized neighbourhood (briefly, GN) of  $x \in X$  and  $\psi$  is a generalized neighbourhood system (briefly, GNS) on  $X$  (see [3]). Let  $\Psi(X)$  denote the collection of all GNS's on  $X$ . In [3], Á. Császár gave a way for obtaining GT's as follows; let  $g \in \mathcal{B}(X)$  and  $\gamma \in \Gamma(X)$  be such that  $A \subset \gamma A$  for  $A \in X$ . Then we have  $V \in \Psi(\gamma, g)(x)$  for  $x \in X$  iff  $V = \gamma G$  for some  $G \in g$  such that  $x \in G$ . It is clear that  $\psi(\gamma, g) \in \Psi(X)$ .

Let  $g$  and  $g'$  be two generalized topologies on  $X$  and  $X'$  respectively.  $f : X \rightarrow X'$  is said to be as  $(g, g')$ -continuous iff  $G' \in g'$  then  $f^{-1}(G') \in g$  (see [3]).

### 3. $\gamma$ -Convergency and $\psi$ -Convergency

**Definition 2.1.** Let  $X$  be a non-empty set and  $\gamma \in \Gamma(X)$ . A sequence  $(x_n)$  is said to  $\gamma$ -converge to a point  $x$  in  $X$  if  $(x_n)$  is eventually in every  $\gamma$  open set containing  $x$ . Denoted by  $(x_n) \rightarrow^\gamma x$ .

**Remark 2.2.** If  $\gamma$  is chosen as  $ic$ ,  $\gamma$ -convergency coincides with pre-convergency; if  $\gamma = ci$   $\gamma$ -convergency coincides with semi-convergency.

**Remark 2.3.** Let  $\psi \in \Psi(X)$ . According to Lemma 1.2 in [3], we know that  $\psi$  generates a GT  $g$  on  $X$ , denoted by  $g = g_\psi$ . Since  $g_\psi$  is a GT on  $X$ , then there is a  $\gamma \in \Gamma(X)$  such that  $g_\psi$  is the collection of all  $\gamma$ -open sets. Hence we can define  $g_\psi$ -convergency with respect to Definition 2.1.

**Definition 2.4.** Let  $X$  be a non-empty set and  $\gamma \in \Gamma(X)$ . A sequence  $(x_n)$  is said to  $\psi$ -converge to a point  $x$  in  $X$  if  $(x_n)$  is eventually in every set  $V$  in  $\psi(x)$ . Denoted by  $(x_n) \rightarrow^\psi x$ .

**Lemma 2.5.** *Let  $(x_n)$  be a sequence in the set  $X$ ,  $\psi$  be a GNS and  $g = g_\psi$  is a GT generated by  $\psi$ . If  $(x_n) \rightarrow^\psi x$ , then  $(x_n) \rightarrow^{g_\psi} x$ .*

*Proof.*  $(x_n) \rightarrow^\psi x$  implies that  $(x_n)$  is eventually in every set  $V$  in  $\psi(x)$ . Since  $\psi$  construct a GT as  $g = g_\psi$ , then  $G \in g$  iff  $G \subset X$  satisfies:  $x \in G$ , then there is  $V \in \psi(x)$  such that  $V \subset G$ . Hence  $(x_n)$  is eventually in every  $G$ .  $\square$

The converse of Lemma 2.5 need not to be hold in general.

**Example 2.6.** Let  $X = \{a, b, c\}$ ,  $g = \{\emptyset, X, \{a\}, \{b\}, \{a, b\}\}$ ,  $\psi = \psi(c_g, g)$  and for  $k \in Z$  ( $Z$  is a set of all integers number)

$$(x_n) = \begin{cases} c, & n = 2k \\ a, & n = 2k + 1 \end{cases}$$

be a sequence in  $X$ .

We have  $\psi(b) = \{X, \{b, c\}\}$  and  $g_\psi = \{\emptyset, X\}$ . It is obvious that  $(x_n)$  is eventually in  $X$  but not eventually in  $\{b, c\}$ . Hence,  $(x_n)$   $g_\psi$ -converges to  $b$  while  $(x_n)$  does not  $\psi$ -converges to  $b$ .

#### 4. Sequentially Continuity in Generalized Topologies and $\mu$ -Convergency

**Definition 3.1.** A function  $f : X \rightarrow Y$  is said to be sequentially  $(g, g')$ -continuous if for each point  $x$  in  $X$  and each sequence  $(x_n)$  in  $X$   $g$ -converging to  $x$ , then  $(f(x_n))$  in  $Y$   $g'$ -converging to  $f(x)$ .

**Theorem 3.2.** *Let  $f : X \rightarrow Y$  be a  $(g, g')$ -continuous function. Then  $f$  is sequentially  $(g, g')$ -continuous.*

*Proof.* Let  $x \in X$  and  $(x_n)$  be a sequence in  $X$   $g$ -converging to  $x$ . Then  $(x_n)$  is eventually in every  $\gamma$ -open set  $V$  containing  $x$ . Since  $f$  is  $(g, g')$ -continuous, we can take  $V = f^{-1}(N)$  for  $\gamma'$ -open set  $N$  in  $Y$ . Then  $(x_n) \in f^{-1}(N)$ . This implies  $f(x_n) \in f(f^{-1}(N)) \subset N$  which means  $(f(x_n))$  is eventually in every  $g'$ -open set  $N$  containing  $f(x)$ .  $\square$

If for every  $n \in I$  ( $I = \{1, 2, \dots, n, \dots\}$ ) there exists a  $\gamma$ -open set  $U$  such that  $x \in U \subset E_n$ , then we denote the collection of all  $E_n$  for every  $n \in I$  by  $\varepsilon(x)$ , i.e.  $\varepsilon(x) = \{E_n : n \in I\}$ .

Let  $g$  be a GT on  $X$ . From Lemma 1.1 in [2], for  $x \in X$  we can construct a class  $\varepsilon(x)$  whose elements are  $g$ -open sets. Hence we denote this as  $\varepsilon(x) = \varepsilon_g(x)$ .

**Definition 3.3.** Let  $X$  be a set and  $g$  be a GT on  $X$ . Then  $X$  is called

as generalized first countable space ( $g$  first countable space) if for each  $x$  in  $X$  and  $\varepsilon(x) = \{E_n | n \in I\}$ , the elements of  $\varepsilon(x)$  can be written as

$$E_1 \supset E_2 \supset \dots \supset E_n \supset \dots$$

**Lemma 3.4.** *Let  $g$  be a GT on  $X$ . For all  $x \in X$ , there is a class  $\varepsilon(x)$  whose elements are also elements of  $g$ .*

*Proof.* If  $g$  is a GT on  $X$ , then there is a  $\gamma : \wp(X) \rightarrow \wp(X)$  such that  $g$  is the collection of all  $\gamma$ -open sets (see [2]). Also we know that the elements of  $\varepsilon(x)$  are  $\gamma'$ -open sets, for some  $\gamma'$ . We can choose  $\gamma' = \gamma$  and they become elements of  $g$ .  $\square$

Let us write  $\varepsilon(x) = \varepsilon_g(x)$  in this manner.

**Definition 3.5.** A function  $f$  is said to be sequentially  $(\psi, \psi')$ -continuous if for each sequence  $(x_n)$  in  $X$   $\psi$ -converging to  $x$ ,  $(f(x_n))$   $\psi'$ -converges to  $f(x)$ .

**Theorem 3.6.** *Let  $X$  be a  $g$  first countable space and  $f : X \rightarrow Y$  be a sequentially  $(\psi_g, \psi_{g'})$ -continuous function. Then  $f$  is  $(\psi_g, \psi_{g'})$ -continuous function.*

*Proof.* Let  $x$  in  $X$  and  $\varepsilon(x) = \{V_n : n \in I\}$  which satisfies the property

$$V_1 \supset V_2 \supset \dots \supset V_n \supset \dots$$

Assume that  $f$  is not  $(\psi_g, \psi_{g'})$ -continuous function in  $x$ . Then for a  $V' \in \psi_g(x)$  and all  $V \in \psi_g(x)$ ,  $f(V) \not\subset V'$  is hold.

In this manner, we can write  $f^{-1}(f(V')) \not\subset f^{-1}(V)$ . This may imply that  $V \not\subset f^{-1}(V')$ . It is obvious that  $\varepsilon(x) = \varepsilon_g(x)$  is contained by  $\psi_g(x)$ . Hence we can say that for each  $n \in I$ ,  $V \not\subset f^{-1}(V')$ . Then for each  $n \in I$ , there exists a  $x_n$  in  $V_n$  such that  $x_n \notin f^{-1}(V')$ . This implies  $f(x_n) \notin V'$ . This is a contradiction. Hence  $f$  is  $(\psi_g, \psi_{g'})$ -continuous.  $\square$

**Definition 3.7.** (see [4]) Define a mapping  $\lambda : \wp(X) \rightarrow \wp(X)$ .  $\lambda$  is called as an envelope operation satisfying the following conditions:

$$(3.7.1) \quad A \subset \lambda A \text{ for } A \subset X.$$

$$(3.7.2) \quad \text{For } A, B \subset X, A \subset B \text{ implies } \lambda A \subset \lambda B.$$

$$(3.7.3) \quad \text{For } A \subset X, \lambda \lambda A = \lambda A.$$

**Definition 3.8.** (see [4]) Let  $\mu \subset \wp(X)$  be arbitrary. For  $A \subset X$ ,  $x \in \kappa A$  iff  $K \in \mu$  satisfying  $x \in K$  fulfills  $K \cap A \neq \emptyset$ . We write  $\kappa = \kappa A$ .

**Lemma 3.9.**  $\kappa = \kappa(\mu)$  is an envelope on  $X$  for an arbitrary  $\mu \subset \wp(X)$ .

In [4], the separation axioms were formulated by replacing open sets by an arbitrary family of subsets of the space  $X$ .

**Definition 3.10.** (see [4]) Assume  $\mu \subset \wp(X)$ .  $(T_2)$   $x, y \in X, x \neq y$  imply the existence of  $K, K' \in \mu$  such that  $x \in K, y \in K'$  and  $K \cap K' = \emptyset$ .

**Definition 3.11.**  $x_0$  is a  $\psi$ -cluster point of  $(x_n)$  if for each  $U \in \psi(x_0)$  there is a  $m \in I$  such that  $x_n \in U$  for some  $n$  bigger than  $m$ .

**Definition 3.12.**  $x_0$  is a  $\gamma$ -cluster point of  $(x_n)$  if for each  $\gamma$ -open set  $U$  that contains  $x_0$ , there is a  $m \in I$  such that  $x_n \in U$  for some  $n$  bigger than  $m$ .

As expressed Remark 2.2, we can introduce  $g_\psi$ -cluster point.

**Theorem 3.13.** Let  $(x_n)$  be a sequence in the set  $X$ ,  $\psi$  be a GNS and  $g = g_\psi$  be a GT generated by  $\psi$ . If  $x_0$  is a  $\psi$ -cluster point for  $(x_n)$  then it is a  $g_\psi$ -cluster point for  $(x_n)$ .

*Proof.* The proof is similar with the proof of Lemma 2.5. □

**Theorem 3.14.** Let  $(x_n)$  be a sequence in  $X$ ,  $x_0 \in X$  and  $\kappa = \kappa(\psi(x_0))$ .  $x_0$  is a  $\psi$ -cluster point of  $(x_n)$  if and only if  $x_0 \in \kappa\{x_n, x_{n+1}, \dots\}$  for all  $n \in I$ .

*Proof.* ( $\Rightarrow$ ): Since  $x_0$  is a  $\psi$ -cluster point of  $(x_n)$ , for all  $V \in \psi(x_0)$  there exists a  $m \in I$  such that  $x_n \in V$  for some  $n$  bigger than  $m$ . Hence  $\{x_n, x_{n+1}, \dots\} \cap V \neq \emptyset, n > m$ . This implies  $x_0 \in \kappa\{x_n, x_{n+1}, \dots\}$  for all  $n \in I$ .

( $\Leftarrow$ ): Since  $x_0 \in \kappa\{x_n, x_{n+1}, \dots\}$  for all  $n \in I$ ;  $V \cap \{x_n, x_{n+1}, \dots\} \neq \emptyset$  is hold for all  $V \in \psi(x_0)$  and for all  $n \in I$ . This implies  $x_0$  is a cluster point of  $(x_n)$ . □

**Definition 3.15.** Assume  $\mu \subset \wp(X)$ . A sequence  $(x_n)$  is said to  $\mu$ -converge to a point  $x$  in  $X$  if  $(x_n)$  is eventually in every set  $V$  in  $\mu$  containing  $x$  and denoted by  $(x_n) \rightarrow^\mu x$ .

**Theorem 3.16.** Let  $\mu \subset \wp(X)$ . If  $X$  satisfies  $(T_2)$  then  $(x_n)$   $\mu$ -converges to one point in  $X$ .

*Proof.* Let  $(x_n)$   $\mu$ -converges to both  $x$  and  $y$ . Since  $(x_n)$   $\mu$ -converges to  $x$ , it is eventually in every set  $U$  in  $\mu$  containing  $x$  and since  $(x_n)$   $\mu$ -converges to  $y$  it is eventually in every set  $V$  in  $\mu$  containing  $y$ . This implies  $(x_n)$  is eventually in  $U \cap V$ . Hence  $U \cap V \neq \emptyset$  and this is a contradiction. □

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