

ON HYPERBOLIC SECOND-ORDER QUASI-LINEAR
INITIAL BOUNDARY-VALUE PROBLEMS

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Abstract: The paper deals with the existence and uniqueness of a non-trivial classical solution to a initial boundary-value problem for a quasi-linear second-order system, with homogeneous boundary conditions, in the space $H^{s'}(\bar{\Omega} \times [0, T])$, where Ω is the half-space $\Omega = \mathbf{R}^{d-1} \times (0, \infty)$, $s > d/2 + 3$ and $s' \in (0, s)$. The proof of the main theorem relies on the existence of the solution in $H^s(\bar{\Omega} \times [0, T])$, to the boundary-value problem, for linear second-order systems with smooth coefficients in the variables x and t . The main result is achieved by defining a suitable iteration scheme that approximates the solution.

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1. Introduction

Let A be the second-order quasi-linear differential operator

$$A[\cdot] = \partial_t^2 + S(\cdot, \nabla_x)\partial_t + \sum_{\alpha=1}^d T^\alpha(\cdot, \nabla_x)\partial_t\partial_\alpha + \sum_{\alpha=1}^d \sum_{\beta=1}^d E^{\alpha,\beta}(\cdot, \nabla_x)\partial_\alpha\partial_\beta + \sum_{\alpha=1}^d F^\alpha(\cdot, \nabla_x)\partial_\alpha + G(\cdot, \nabla_x), \quad (1)$$

where t is a real variable and the variable x belongs to the half-space $\Omega = \mathbf{R}^{d-1} \times (0, \infty)$, with $d > 1$; moreover, for all $\alpha, \beta = 1, \dots, d$, the functions $S, T^\alpha, E^{\alpha,\beta}, F^\alpha, G$; are defined in $\mathbf{R}^d \times \mathbf{R}^{d^2}$ with values in the space of $d \times d$

real matrices and have smooth coefficients; in addition, we shall assume that $E^{d,d}$ is the null-matrix. Let us define the first-order boundary operator B as follows:

$$B[\cdot] = T^d(\cdot, \nabla_x)\partial_t + 2 \sum_{\beta=1}^{d-1} E^{d,\beta}(\cdot, \nabla_x)\partial_\beta + F^d(\cdot, \nabla_x). \tag{2}$$

I shall be concerned with the well-posedness of the following hyperbolic boundary-value problem with homogeneous boundary conditions

$$\begin{cases} A[u] = 0, & \text{in } \Omega \times (0, T), \\ B[u] = 0, & \text{on } \partial\Omega \times (0, T), \end{cases} \tag{3}$$

where $u = u(x, t)$ is the unknown function with values in \mathbf{R}^d . I shall study the problem under the assumption that for every $\alpha, \beta = 1, \dots, d$, the matrix-valued functions $S, T^\alpha, E^{\alpha,\beta}, F^\alpha, G$ belong to $C^\infty(\mathbf{R}^d \times \mathbf{R}^{d^2})$ and are bounded as well as their derivatives. Moreover, I shall assume that $E^{d,d}$ is the null matrix, in order for the boundary-value problem to be well-posed in the half-space $\Omega = \mathbf{R}^{d-1} \times (0, \infty)$.

The main result will be achieved by proving the existence of the solution of the following linear boundary-value problem, in the space $H^s(\bar{\Omega} \times [0, T])$

$$\begin{cases} \partial_t^2 u + \bar{S}(x, t)\partial_t u + \sum_{\alpha=1}^d \bar{T}^\alpha(x, t)\partial_t \partial_\alpha u + \sum_{\alpha=1}^d \sum_{\beta=1}^d \bar{E}^{\alpha,\beta}(x, t)\partial_\alpha \partial_\beta u \\ + \sum_{\alpha=1}^d \bar{F}^\alpha(x, t)\partial_\alpha u + \bar{G}(x, t)u = 0, & \text{in } \Omega \times (0, T), \\ 2 \sum_{\beta=1}^{d-1} \bar{E}^{d,\beta}(x, t)\partial_\beta u + \bar{T}^d(x, t)\partial_t u + \bar{F}^d(x, t)u = 0, & \text{on } \partial\Omega \times (0, T); \end{cases} \tag{4}$$

where the functions $\bar{S}, \bar{T}^\alpha, \bar{E}^{\alpha,\beta}, \bar{F}^\alpha, \bar{G}$, for all $\alpha, \beta = 1, \dots, d$, take values in the space of $d \times d$ real matrices, belong to $C^\infty(\bar{\Omega} \times [0, T])$ and are bounded with their derivatives.

In the paper [3], a linear evolution boundary-value problem in a half-space has been studied in the case where the second-order differential operator has coefficients that depend only on the space-variable. The linear problem has been discussed by studying operators with constant coefficients, through a Fourier-Laplace analysis and subsequently, by applying Hille-Yosida Theorem to prove the well-posedness of the variable-coefficients boundary-value problem in the space $C^1([0, T], H^1(\Omega))$.

The following paper [4] deals with the initial boundary-value problem, in a half-space, for a quasi-linear second-order system, whose coefficients de-

pend on the unknown vector field u and where the functions S, T^α are null-matrices. The main result of [4] states existence and uniqueness in the spaces $C^1([0, T], H^{s'}(\bar{\Omega}))$ as $s' \in (0, s)$ and $s > d/2 + 2$, of the solution to the initial boundary-value problem, with homogeneous boundary conditions and initial values $u(x, 0) = 0$ and $\partial_t u(x, 0) = g(x)$, where g belongs to $H^s(\mathbf{R}^d)$. Similarly to the procedure that was introduced in [1] to study Cauchy problems for first-order systems, one of the result of [4] concerns the well-posedness of a boundary-value problem for a linear second-order operator with coefficients which depend on the space-variable x and on the time-variable t . This result was applied subsequently to obtain the existence of a non-null solution of the quasi-linear problem.

In proving existence of the solutions to problems (3) and (4), as well as in the case of the problem treated in [4], I shall assume that the second-order differential operator (3) and the adjoint satisfy suitable conditions, which are analogous to the energy estimates derived in [1] for linear Cauchy problems for first-order symmetrizable systems. Consider, for instance, a linear second-order operator of the form

$$K[u] = \partial_t^2 u + \bar{S}(x, t)\partial_t u + \sum_{\alpha=1}^d \bar{T}^\alpha(x, t)\partial_t \partial_\alpha u.$$

Assume that the family of first-order operators $K(t) = \bar{S}(\cdot, t) + \sum_{\alpha=1}^d \bar{T}^\alpha(\cdot, t)\partial_\alpha$,

admits a functional symmetrizer, in the sense of the definition given in [1] and that the matrices \bar{S}, \bar{T}^α belong to $C^\infty(\Omega \times (0, T))$ and are bounded with their derivatives. Because of the a priori estimates proved in [1] the second-order operator K turns out to satisfy the assumptions of Proposition 2.1, for $K[u]$ can be regarded as a first-order operator with respect to $\partial_t u$.

As a consequence of the existence of a non-trivial solution of problem (4), in the space $H^s(\bar{\Omega} \times [0, T])$, I shall deduce the well-posedness of the initial boundary-value problem in the case where the dependence on the variables x and t of the matrix-valued functions $\bar{S}, \bar{T}^\alpha, \bar{E}^{\alpha, \beta}, \bar{F}^\alpha, \bar{G}$ occurs through a function $v \in H^s(\bar{\Omega} \times [0, T])$. Then I shall define a sequence of initial boundary-value problems, which in accordance with this existence result, admits a solution in the space $H^s(\bar{\Omega} \times [0, T])$. Passing to the limit in the iteration scheme, I shall state the main theorem, concerning the existence and uniqueness of a non-trivial solution to (3) in the spaces $H^{s'}(\bar{\Omega} \times [0, T])$, with $s' \in (0, s)$, $s > d/2 + 3$.

2. Linear Second-Order Hyperbolic BVP

Let us consider the boundary-value problem (4) and denote by L the linear second-order differential operator associated with (4)

$$L = \partial_t^2 + \bar{S}(x, t)\partial_t + \sum_{\alpha=1}^d \bar{T}^\alpha(x, t)\partial_t\partial_\alpha + \sum_{\alpha=1}^d \sum_{\beta=1}^d \bar{E}^{\alpha,\beta}(x, t)\partial_\alpha\partial_\beta + \sum_{\alpha=1}^d \bar{F}^\alpha(x, t)\partial_\alpha + \bar{G}(x, t). \quad (5)$$

If we assume that for every $\alpha, \beta = 1, \dots, d$, $\bar{E}^{\alpha,\beta} = \bar{E}^{\beta,\alpha}$, the corresponding adjoint operator turns out to be defined by

$$L^* = \partial_t^2 - \partial_t\bar{S}^T - \bar{S}^T\partial_t + \sum_{\alpha=1}^d (\partial_t\partial_\alpha\bar{T}^{\alpha T} + \partial_t\bar{T}^{\alpha T}\partial_\alpha + \partial_\alpha\bar{T}^{\alpha T}\partial_t + \bar{T}^{\alpha T}\partial_t\partial_\alpha) + \sum_{\alpha=1}^d \sum_{\beta=1}^d (\partial_\beta\partial_\alpha\bar{E}^{\alpha,\beta T} + 2\partial_\alpha\bar{E}^{\alpha,\beta T}\partial_\beta + \bar{E}^{\alpha,\beta T}\partial_\beta\partial_\alpha) - \sum_{\alpha=1}^d (\bar{F}^{\alpha T}\partial_\alpha + \partial_\alpha(\bar{F}^{\alpha T})) + \bar{G}^T. \quad (6)$$

Let us denote by $H_{\bar{\Omega} \times [0, T]}^s(\mathbf{R}^{d+1})$ the closed subspace of $H^s(\mathbf{R}^{d+1})$ formed by the functions with support in $\bar{\Omega} \times [0, T]$ and by $H^s(\bar{\Omega} \times [0, T])$ the space of distributions admitting an extension in the space $H^s(\mathbf{R}^{d+1})$.

Proposition 2.1. *Let us consider the boundary value problem (4). Let $s \in \mathbf{R}$, $s > d/2 + 2$, and $T > 0$. If the operator L satisfies the following conditions:*

- (i) *for all $\alpha, \beta = 1, \dots, d$, $\bar{S}, \bar{T}^\alpha, \bar{E}^{\alpha,\beta}, \bar{F}^\alpha, \bar{G} \in C^\infty(\bar{\Omega} \times [0, T])$ and are bounded as well as their derivatives;*
- (ii) *for all $\alpha, \beta = 1, \dots, d$, $\bar{E}^{\alpha,\beta} = \bar{E}^{\beta,\alpha}$ in $\bar{\Omega} \times [0, T]$ and $\bar{E}^{d,d}$ is the null-matrix;*
- (iii) *there exists a positive real constant c such that for every $\phi \in C_0^\infty(\Omega \times [0, T])$,*

$$\|L^* \phi\|_{H_{\bar{\Omega} \times [0, T]}^{-s}(\mathbf{R}^d)}^2 \geq c \|\phi(t)\|_{H_{\bar{\Omega}}^{-s}(\mathbf{R}^d)}^2, \quad (7)$$

with $t \in [0, T]$.

Then there exists a non-null function $u \in H^s(\bar{\Omega} \times [0, T])$ which provides a

solution to problem (4).

The result can be proved similarly to Proposition 2.1 in [4]. For the sake of completeness, let us outline the proof.

Proof. Let k be the largest integer so that $d/2 < k + 1 < s$. Let $g \in H^s(\mathbf{R}^d)$ be a non-null function which satisfies the following compatibility conditions: the function $\bar{T}^d g$ and the derivatives of order less than or equal to k , with respect to the time variable t , of the boundary operator

$$B[u] = 2 \sum_{\beta=1}^{d-1} \bar{E}^{d,\beta} \partial_\beta u + \bar{T}^d \partial_t u + \bar{F}^d u,$$

vanish when evaluated at $t = 0$ and $x \in \partial\Omega$.

Let $\phi \in C_0^\infty(\Omega \times [0, T[)$ and define the linear functional f :

$$f(L^* \phi) = \langle g, \phi(0) \rangle_{H^s, H^{-s}} .$$

Due to the linearity and to condition (iii), the operator L^* is injective and the functional f turns out to be well-defined. Since f is a bounded linear functional, thanks to Hahn-Banach Theorem, there exists a continuous linear form F , defined in the space $H_{\bar{\Omega} \times [0, T]}^{-s}(\mathbf{R}^{d+1})$, which extends the functional f . Thanks to Riesz Representation Theorem, there exists a function $u \in H^s(\bar{\Omega} \times [0, T])$, such that $F(v) = \langle u, v \rangle_{H^s, H^{-s}}$, for all $v \in H_{\bar{\Omega} \times [0, T]}^{-s}(\mathbf{R}^{d+1})$. As a consequence of this property, the function u turns out to be a solution, in the sense of distributions, of the system $Lu = 0$, in $\Omega \times (0, T)$. \square

As far as the initial datum is concerned, let $\psi \in C_0^\infty(\Omega \times [0, T])$. Integrating by parts, we obtain

$$\begin{aligned} \langle g, \psi(0) \rangle_{L^2, L^2} &= \langle \partial_t u(0), \psi(0) \rangle_{L^2, L^2} - \langle u(0), \partial_t \psi(0) \rangle_{L^2, L^2} \\ &+ \langle \bar{S}u(0), \psi(0) \rangle_{L^2, L^2} + \langle \sum_{\alpha=1}^d \bar{T}^\alpha \partial_\alpha u(0), \psi(0) \rangle_{L^2, L^2} . \end{aligned} \quad (8)$$

By choosing suitable functions $\psi \in C_0^\infty(\Omega \times [0, T[)$ and applying a standard argument, we deduce that u satisfies the following initial conditions: $\partial_t u(x, 0) = g(x)$, $u(x, 0) = 0$.

Furthermore, let $\chi \in C_0^\infty(\mathbf{R}^{d-1} \times [0, +\infty[\times (0, T))$. Then $\langle Lu, \chi \rangle_{H^s, H^{-s}} = 0$; integrating by parts, we obtain

$$\int_0^T \int_{\mathbf{R}^{d-1}} \langle 2 \sum_{\beta=1}^{d-1} \bar{E}^{d,\beta} \partial_\beta u + \bar{F}^d u + \bar{T}^d \partial_t u, \chi \rangle (y, 0, \tau) dy d\tau = 0.$$

As a consequence, the function u satisfies the homogeneous boundary conditions.

The result proved above cannot be applied directly to state the main theorem, concerning the existence of a non-null solution to problem (3). We shall extend below the result of Proposition 2.1 by studying boundary-value problems for a class of more general operators.

Let $v \in H^s(\bar{\Omega} \times [0, T])$, with $s > d/2 + 3$, and denote by L_v the second-order linear differential operator

$$L_v = \partial_t^2 + S(v, \nabla_x v) \partial_t + \sum_{\alpha=1}^d T^\alpha(v, \nabla_x v) \partial_t \partial_\alpha + \sum_{\alpha=1}^d \sum_{\beta=1}^d E^{\alpha,\beta}(v, \nabla_x v) \partial_\alpha \partial_\beta + \sum_{\alpha=1}^d F^\alpha(v, \nabla_x v) \partial_\alpha + G(v, \nabla_x v), \quad (9)$$

and by L_v^* the corresponding adjoint operator.

Proposition 2.2. *Assume that $v \in H^s(\bar{\Omega} \times [0, T])$, with $s > d/2 + 3$ and consider the boundary-value problem*

$$\begin{cases} L_v u = 0, & \text{in } \Omega \times (0, T), \\ 2 \sum_{\beta=1}^{d-1} E^{d,\beta}(v, \nabla_x v) \partial_\beta u + T^d(v, \nabla_x v) \partial_t u + F^d(v, \nabla_x v) u = 0, & \text{on } \partial\Omega \times (0, T); \end{cases} \quad (10)$$

under the following assumptions:

(i) for every $\alpha, \beta = 1, \dots, d$, the matrix-valued functions $S, T^\alpha, E^{\alpha,\beta}, F^\alpha, G \in C^\infty(\mathbf{R}^d \times \mathbf{R}^{d^2})$ and are bounded with their derivatives; moreover, $E^{\alpha,\beta} = E^{\beta,\alpha}$ and $E^{d,d}$ is the null-matrix;

(ii) there exists a positive constant C , such that for every $\phi \in C_0^\infty(\Omega \times [0, T])$,

$$\|L_v^* \phi\|_{H_{\bar{\Omega} \times [0, T]}^{-s}(\mathbf{R}^d)}^2 \geq C \|\phi(t)\|_{H_{\bar{\Omega}}^{-s}(\mathbf{R}^d)}^2,$$

with $t \in [0, T]$.

Then there exists a non-null solution $u \in H^s(\bar{\Omega} \times [0, T])$ to the boundary-value problem (10).

The coefficients of the operators L_v and L_v^* , are continuous and bounded in $\bar{\Omega} \times [0, T]$ due to Sobolev embedding. By means of the same proof carried out to state the result of Proposition 2.1, we can prove there exists a non-null solution to the BVP (10), in the space $H^s(\bar{\Omega} \times [0, T])$.

3. Quasi-Linear Second-Order Hyperbolic Problems

I shall study below the well-posedness of the initial boundary-value problem (3) in the spaces $H^{s'}(\bar{\Omega} \times [0, T])$ with $s' \in (0, s)$, $s > d/2 + 3$, by means of the definition of a suitable iteration scheme, which yields a sequence of initial boundary-value problems, whose solutions turn out to approach the unique solution of (3).

Theorem 3.1. *Consider the boundary-value problem (3). Let $s > d/2 + 3$. Let $T > 0$ and $g \in H^s(\mathbf{R}^d)$. Suppose the following conditions are satisfied:*

(i) *for every $\alpha, \beta = 1, \dots, d$, $S, T^\alpha, E^{\alpha,\beta}, F^\alpha, G \in C^\infty(\mathbf{R}^d \times \mathbf{R}^{d^2})$ and are bounded as well as their derivatives; moreover, $E^{\alpha,\beta} = E^{\beta,\alpha}$ and $E^{d,d}$ is the null-matrix;*

(ii) *for every $\alpha, \beta = 1, \dots, d$, the matrices $S, T^\alpha, E^{\alpha,\beta}, F^\alpha, G$ vanish when evaluated at $(0, 0)$;*

(iii) *compatibility conditions are satisfied by the function g and the boundary operator*

$$B[u] = 2 \sum_{\beta=1}^{d-1} E^{d,\beta}(0, 0) \partial_\beta u + T^d(0, 0) \partial_t u + F^d(0, 0)u,$$

as $t = 0$ and $x \in \partial\Omega$.

(iv) *if $v \in H^s(\bar{\Omega} \times [0, T])$, there exists a positive constant C , so that for every $\phi \in C_0^\infty(\Omega \times [0, T])$,*

$$\|L_v^* \phi\|_{H_{\bar{\Omega} \times [0, T]}^{-s}(\mathbf{R}^d)}^2 \geq C \|\phi(t)\|_{H_{\bar{\Omega}}^{-s}(\mathbf{R}^d)}^2,$$

with $t \in [0, T]$;

(v) *if r is a positive real number with $2 \leq r \leq s'$ and $s' \in [2, s]$, there exists a positive constant Γ such that for every $v \in H^{s'}(\bar{\Omega} \times [0, T])$ and for every $\phi \in H^{s'}(\bar{\Omega} \times [0, T])$,*

$$\|\phi\|_{H^r(\bar{\Omega} \times [0, T])}^2 \leq \Gamma T \|L_v \phi\|_{H^{r-2}(\bar{\Omega} \times [0, T])}^2 + \|\phi(0)\|_{H^r(\bar{\Omega})}^2 + \|\partial_t \phi(0)\|_{H^{r-1}(\bar{\Omega})}^2. \tag{11}$$

Then there exists $\tilde{T} > 0$ and a function $u \in H^{s'}(\bar{\Omega} \times [0, \tilde{T}])$ with $s' \in (0, s)$, which provides a classical solution, to the initial boundary-value problem (3), with initial data $u(x, 0) = 0$ and $\partial_t u(x, 0) = g(x)$. Moreover, the solution turns out to be unique.

Proof. Let δ be a positive real number, such that $\|g\|_{H^s(\mathbf{R}^d)} \leq \frac{\delta}{4}$.

According to the notation of the previous section, for every $k \in \mathbf{N}, k > 0$, let us denote by L_{k-1} the linear differential operator $L_{u^{k-1}}$ and by B_{k-1} the

corresponding boundary operator. We introduce the following iteration scheme

$$\begin{cases} L_{k-1}u^k = 0, & x \in \Omega, t \in [0, T], \\ B_{k-1}u^k = 0, & x \in \partial\Omega, t \in [0, T]; \end{cases} \quad (12)$$

as $k \in \mathbf{N}$. Let u^0 be a function belonging to the space $H^s(\bar{\Omega} \times [0, T])$ so that $\|u^0\|_{H^s(\bar{\Omega} \times [0, T])} \leq \delta$. If the function u^{k-1} belongs to $H^s(\bar{\Omega} \times [0, T])$, then the operator L_{k-1} satisfies the assumptions of Proposition 2.2. As a consequence of this property, the initial boundary-value problem (12), with initial data $u^k(x, 0) = 0$ and $\partial_t u^k(x, 0) = g(x)$, admits a unique solution $u^k \in H^s(\bar{\Omega} \times [0, T])$. We shall prove that the sequence of functions $(u^k)_{k \in \mathbf{N}}$ is convergent to a function u , in the space $H^2(\bar{\Omega} \times [0, T])$, which provides the solution of the BVP (3). Let us divide the proof in three steps.

Step 1. In accordance with the definition of u^0 , we have $\|u^0\|_{H^s(\bar{\Omega} \times [0, T])} \leq \delta$. Let us prove by induction that for all $k \in \mathbf{N}$, $\|u^k\|_{H^s(\bar{\Omega} \times [0, T])} \leq \delta$. We assume that for all $k \leq m$, $\|u^k\|_{H^s(\bar{\Omega} \times [0, T])} \leq \delta$, and prove that, as long as T is small enough, the estimate is true in the case where $k \geq m + 1$. Since $s > d/2 + 3$ and the functions $u^k \in H^s(\bar{\Omega} \times [0, T])$, there exists a positive constant μ , which depends on δ , so that for every $\alpha, \beta = 1, \dots, d$, for all $k \leq m$,

$$\begin{aligned} \|u^k\|_{L^\infty(\Omega \times [0, T])} &\leq \mu; & \|\nabla_x u^k\|_{L^\infty(\Omega \times [0, T])} &\leq \mu; \\ \|\partial_\alpha \partial_\beta u^k\|_{L^\infty(\Omega \times [0, T])} &\leq \mu; & & \\ \|\partial_t u^k\|_{L^\infty(\Omega \times [0, T])} &\leq \mu; & \|\partial_t \partial_\alpha u^k\|_{L^\infty(\Omega \times [0, T])} &\leq \mu. \end{aligned} \quad (13)$$

Let us denote by P_j^k the sum

$$\begin{aligned} P_j^k = & - \sum_{\alpha=1}^d \sum_{\beta=1}^d E^{\alpha, \beta}(u^{k-2}, \nabla_x u^{k-2}) \partial_\alpha \partial_\beta u^k - \sum_{\alpha=1}^d F^\alpha(u^{k-2}, \nabla_x u^{k-2}) \partial_\alpha u^k \\ & - G(u^{k-2}, \nabla_x u^{k-2}) u^k. \end{aligned} \quad (14)$$

Let $k = m + 1$. Thanks to Moser estimates (see [1]) and to the conditions satisfied by the matrices $E^{\alpha, \beta}, F^\alpha, G$, for all $\alpha, \beta = 1, \dots, d$, we obtain

$$\|P_j^k\|_{H^{s-2}(\bar{\Omega} \times [0, T])} \leq \zeta(s, \mu) \|u^k\|_{H^s(\bar{\Omega} \times [0, T])}, \quad (15)$$

where $\zeta(s, \mu)$ is a suitable positive constant that depends on s, μ and on the matrices $E^{\alpha, \beta}, F^\alpha, G$. Similarly,

$$\|S(u^{k-2}, \nabla_x u^{k-2}) \partial_t u^k\|_{H^{s-2}(\bar{\Omega} \times [0, T])} \leq \rho_1(s, \mu) \|\partial_t u^k\|_{H^{s-1}(\bar{\Omega} \times [0, T])}, \quad (16)$$

and

$$\|T^\alpha(u^{k-2}, \nabla_x u^{k-2}) \partial_t \partial_\alpha u^k\|_{H^{s-2}(\bar{\Omega} \times [0, T])} \leq \rho_2(s, \mu) \|\partial_t u^k\|_{H^{s-1}(\bar{\Omega} \times [0, T])}. \quad (17)$$

As a consequence of the previous estimates, we deduce

$$\begin{aligned} & \|L_{k-2} u^k\|_{H^{s-2}(\bar{\Omega} \times [0, T])} \\ & \leq \zeta(s, \mu) \|u^k\|_{H^s(\bar{\Omega} \times [0, T])} + \rho(s, \mu) \|\partial_t u^k\|_{H^{s-1}(\bar{\Omega} \times [0, T])}, \end{aligned} \tag{18}$$

where $\rho(s, \mu)$ is the sum of the positive constants $\rho_1(s, \mu)$, $\rho_2(s, \mu)$.

In view of the condition (v),

$$\begin{aligned} & \|u^k\|_{H^s(\bar{\Omega} \times [0, T])}^2 \\ & \leq \Gamma T \left(\zeta(s, \mu) \|u^k\|_{H^s(\bar{\Omega} \times [0, T])} + \rho(s, \mu) \|\partial_t u^k\|_{H^{s-1}(\bar{\Omega} \times [0, T])} \right)^2 + \|g^k\|_{H^s(\bar{\Omega})}^2 \\ & \leq 2\Gamma T \max(\zeta^2(s, \mu), \rho^2(s, \mu)) \|u^k\|_{H^s(\bar{\Omega} \times [0, T])}^2 + \frac{\delta^2}{4}. \end{aligned} \tag{19}$$

If $T < \frac{1}{4\Gamma \max(\zeta^2(s, \mu), \rho^2(s, \mu))}$, then $\|u^k\|_{H^s(\bar{\Omega} \times [0, T])}^2 \leq \delta^2$.

As a consequence of the previous estimate, by induction, we have for all $k \in \mathbf{N}$,

$$\|u^k\|_{H^s(\bar{\Omega} \times [0, T])} \leq \delta.$$

Step 2. By means of the properties proved above, we shall establish that the sequence $(u^k)_{k \in \mathbf{N}}$ is convergent in the space $H^2(\bar{\Omega} \times [0, T])$. Let us denote by W^k the difference $u^k - u^{k-1}$, for every $k \in \mathbf{N}$; thus, we have

$$L_{k-1} W^k = (L_{k-2} - L_{k-1}) u^{k-1}. \tag{20}$$

Let us set $\sigma = (u, \nabla_x u)$. Thanks to the mean value theorem

$$\begin{aligned} & \| (S(u^{k-2}, \nabla_x u^{k-2}) - S(u^{k-1}, \nabla_x u^{k-1})) \partial_t u^{k-1} \|_{H^1(\bar{\Omega} \times [0, T])} \\ & \leq 2 \|D_\sigma S(a, b) (u^{k-2} - u^{k-1}, \nabla_x u^{k-2} - \nabla_x u^{k-1})\|_{H^1(\bar{\Omega} \times [0, T])} \\ & \quad \times \|\partial_t u^{k-1}\|_{W^{1, \infty}(\bar{\Omega} \times [0, T])} \leq \text{const}(\delta) \|W^{k-1}\|_{H^2(\bar{\Omega} \times [0, T])}. \end{aligned} \tag{21}$$

Similar estimates can be computed for the other terms in the r.h.s. of (20). Thus, for all $k \in \mathbf{N}$,

$$\|L_{k-1} W^k\|_{H^1(\bar{\Omega} \times [0, T])} \leq \text{const}(\delta) \|W^{k-1}\|_{H^2(\bar{\Omega} \times [0, T])}. \tag{22}$$

Due to condition (v),

$$\|W^k\|_{H^2(\bar{\Omega} \times [0, T])}^2 \leq \Gamma T \left(\text{const}(\delta)^2 \|W^{k-1}\|_{H^2(\bar{\Omega} \times [0, T])}^2 \right); \tag{23}$$

whence, as $k \geq 1$,

$$\|W^k\|_{H^2(\bar{\Omega} \times [0, T])}^2 \leq T \left(\text{const} \|W^{k-1}\|_{H^2(\bar{\Omega} \times [0, T])}^2 \right). \tag{24}$$

If T is sufficiently small, then the sequence of functions $(u^k)_{k \in \mathbf{N}}$ turns out to be a Cauchy sequence in the space $H^2(\bar{\Omega} \times [0, T])$, since the constant in (24)

is independent of k . Let us denote by u the limit of $(u^k)_{k \in \mathbf{N}}$. Since the sequence $(u^k(t))_{k \in \mathbf{N}}$, as proved in Step 1, is bounded in $H^s(\bar{\Omega} \times [0, T])$, by interpolation, it turns out to be convergent to the function u in the space $H^{s'}(\bar{\Omega} \times [0, T])$ for every $s' \in (0, s)$. As a consequence, the function u belongs to the space $C^2(\bar{\Omega} \times [0, T])$.

Step 3. We discuss now the convergence of the iteration scheme (12).

For the sake of convenience, let us write the operators L_{k-1} and A in the following form

$$L_{k-1} = \partial_t^2 + Q_{k-1} + S(u^{k-1}, \nabla_x u^{k-1}) \partial_t + \sum_{\alpha=1}^d T^\alpha(u^{k-1}, \nabla_x u^{k-1}) \partial_t \partial_\alpha; \quad (25)$$

$$A[u] = \partial_t^2 u + Qu + S(u, \nabla_x u) \partial_t u + \sum_{\alpha=1}^d T^\alpha(u, \nabla_x u) \partial_t \partial_\alpha u. \quad (26)$$

Thanks to the convergence properties of the sequence $(u^k)_{k \in \mathbf{N}}$ proved in Step 2, the sequence $(L_{k-1} u^k)_{k \in \mathbf{N}}$ turns out to be convergent to $A[u]$, for every $(x, t) \in \Omega \times (0, T)$, as $k \rightarrow \infty$. Thus, the function u provides a classical solution to system (3), $A[u] = 0$.

Furthermore, passing to the limit, the solution u turns out to satisfy the boundary condition, i.e. $B[u] = 0$, $x \in \partial\Omega$, $t \in [0, T]$.

As far as the initial datum is concerned, we get $u(x, 0) = 0$ and $\partial_t u(x, 0) = g(x)$, where $x \in \Omega$. Since the function g is not null, u is a non-trivial solution to (3).

By means of the same estimates obtained for the sequence of functions $(W^k)_{k \in \mathbf{N}}$ in Step 2, we can prove the uniqueness of the solution u to the problem (3), with initial conditions $u(x, 0) = 0$ and $\partial_t u(x, 0) = g(x)$, $x \in \Omega$. Suppose that u_1 and u_2 are two distinct solutions of the initial boundary-value problem (3) and let $w = u_1 - u_2$. Consider the function $L_{u_1} w = (-L_{u_1} + L_{u_2})u_2$. The same estimates proved to find (22), applied to the function w , yield $\|L_{u_1} w\|_{L^2(\Omega \times]0, T])} \leq \text{const}(\delta) \|w\|_{H^2(\Omega \times]0, T])}$. Thus, because of (11),

$$\|w\|_{H^2(\Omega \times]0, T])}^2 \leq T \text{const} \|w\|_{H^2(\Omega \times]0, T])}^2.$$

If T is small enough, then $w = 0$, in $\Omega \times]0, T[$. □

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