

## GENERALIZED SOLUTION OF A MIXED PROBLEM FOR LINEAR HYPERBOLIC SYSTEM

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**Abstract:** In the first part of this article, we will prove an existence-uniqueness result for generalized solutions of a mixed problem for linear hyperbolic system in the Colombeau algebra. In the second part, we apply the result to a wave propagation problem in a discontinuous environment.

**AMS Subject Classification:** 35L03, 46F30

**Key Words:** generalized functions, hyperbolic system

### 1. Introduction

In this paper, we interested to study the existence and uniqueness of the mixed problem for a linear hyperbolic system in the case of a bounded domain, where the initial data is not smooth.

To complete the work already made in the global case by M. Oberguggenberger [4], we Consider the mixed problem in  $\Omega = [0, +\infty[ \times [0, +\infty[$  for the linear hyperbolic system in two variables

$$\left\{ \begin{array}{l} \left( \partial_t + \Lambda(x, t) \partial_x \right) U = F(x, t)U + A(x, t) \quad (x, t) \in (\mathbb{R}_+^*)^2, \\ U(x, 0) = U_0(x) \quad x \in \mathbb{R}_+, \\ U_i(0, t) = \sum_{k=r+1}^n v_{ik}(t) U_k(0, t) + H_i(t) \quad i = 1, \dots, r \quad t \geq 0 \\ + \text{Compatibility conditions,} \end{array} \right. \quad (1)$$

where  $\Lambda$ ,  $F$  and  $V$  are  $(n \times n)$  matrices whose terms are discontinuous functions.

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Received: April 16, 2014

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The matrix  $\Lambda$  is real and diagonal such that

$$\Lambda_1 > \Lambda_2 > \dots > \Lambda_r > 0 > \Lambda_{r+1} > \dots > \Lambda_n$$

In the case where  $\Lambda \in L^\infty(\mathbb{R}_+^2)$  and  $F \in W_{\text{loc}}^{-1,\infty}(\mathbb{R}_+^2)$ , multiplicative products of distributions appear in system (1), and so there is no general way of giving a meaning to system (1) in the sense of distribution. This hyperbolic system even when it is in the form of a system of conservation laws does not admit any solutions distributions in general see [3]. Our approach is to study (1) in Colombeau's algebra [1, 2], and under some hypotheses on  $\Lambda$ ,  $F$ ,  $\nu$  and  $H$ , the system (1) admits an unique solution in  $\mathcal{G}(\mathbb{R}_+^2)$ .

The second part of this article, we will apply this result to the wave propagation problem in a discontinuous environment. the following system

$$\left\{ \begin{array}{ll} \left( \partial_t + c(x) \partial_x \right) u(x, t) = 0 & (x, t) \in (\mathbb{R}_+^*)^2 \\ \left( \partial_t - c(x) \partial_x \right) v(x, t) = 0 & (x, t) \in (\mathbb{R}_+^*)^2 \\ u(x, 0) = u_0(x) & x \geq 0 \\ v(x, 0) = v_0(x) & x \geq 0 \\ u(0, t) = h(t) v(0, t) + b(t) & t \geq 0 \\ + \text{Compatibility conditions} \end{array} \right. \quad (2)$$

with

$$c(x) = \begin{cases} c_R & \text{if } x > x_0 \\ c_L & \text{if } 0 < x < x_0 \end{cases}$$

$c_R$  and  $c_L$  are real constants,  $u_0$  and  $v_0$  are continuous almost everywhere.

For this problem one can find a classical solution on  $\{0 \leq x < x_0 : t \geq 0\}$  and  $\{x > x_0 : t \geq 0\}$ , so imposing a transmission condition in  $x = x_0$  : the continuity of  $u$  and  $v$ , one will have a classical solution on  $\{x \geq 0, t \geq 0\}$ .

Further if  $(u_0, v_0)$  are generalized functions, one can show that the problem (2) has a unique solution  $(U, V) \in \mathcal{G}(\mathbb{R}_+^2) \times \mathcal{G}(\mathbb{R}_+^2)$ , without having us need of the passage conditions, in the same way one shows that this solution admits an associated distribution that is equal to the classical solution by adjusting.

## 2. Existence and Uniqueness

We recall some definitions from the theory of generalized functions which we need in the sequel.

We define the algebra  $\mathcal{G}(\mathbb{R}^m)$  as follows

$$A_q(\mathbb{R}) = \left\{ \chi \in \mathcal{D}(\mathbb{R}) : \int_{\mathbb{R}} \chi(x) dx = 1 \text{ and } \int_{\mathbb{R}} x^k \chi(x) dx = 0 \text{ for } 1 \leq k \leq q \right\}$$

and

$$A_q(\mathbb{R}^m) = \left\{ \varphi(x_1, \dots, x_m) = \prod_{j=1}^m \{\chi(x_j)\} \right\}$$

Let  $\mathcal{E}[\mathbb{R}^m]$  be the set of functions on  $\mathcal{A}_1(\mathbb{R}^m) \times \mathcal{C}^\infty(\mathbb{R}^m)$  with values in  $\mathbb{C}$  with are  $\mathcal{C}^\infty$  to seconde variable. Obviously  $\mathcal{E}[\mathbb{R}^m]$  with point wise multiplication is an algebra but  $\mathcal{C}^\infty(\mathbb{R}^m)$  is not a subalgebra.

Then given  $\varphi \in \mathcal{A}_1(\mathbb{R}^m)$  and  $\varepsilon \in ]0, 1[$ , we define a function  $\varphi_\varepsilon$  by

$$\varphi_\varepsilon(x) = \varepsilon^{-m} \varphi\left(\frac{x}{\varepsilon}\right) \text{ for } x \in \mathbb{R}^m$$

An element of  $\mathcal{E}[\mathbb{R}^m]$  is called "moderate" if for every compact subset  $K$  of  $\mathbb{R}^m$  and every differential operator  $D = \partial_{x_1}^{k_1}, \dots, \partial_{x_m}^{k_m}$  there is  $N \in \mathbb{N}$  such that the following holds

$$\begin{cases} \forall \varphi \in \mathcal{A}_N(\mathbb{R}^m), \exists C, \exists \eta > 0 \text{ such that} \\ \sup_{x \in K} |D u(\varphi_\varepsilon, x)| \leq C \varepsilon^{-N} \text{ if } 0 < \varepsilon < \eta \end{cases} \quad (3)$$

$\mathcal{E}_M[\mathbb{R}^m]$  denotes the subset of moderate elements where the index  $M$  stands for "Moderate". We define an ideal  $\mathcal{N}[\mathbb{R}^m]$  of  $\mathcal{E}_M[\mathbb{R}^m]$  as follows:

$$u \in \mathcal{N}[\mathbb{R}^m]$$

if for every compact subset  $K$  of  $\mathbb{R}^m$  and every differential operator  $D$ , there is  $N \in \mathbb{N}$  such that

$$\begin{cases} \forall q \geq N, \forall \varphi \in \mathcal{A}_q(\mathbb{R}^m), \exists C, \exists \eta > 0 \text{ such that} \\ \sup_{x \in K} |D u(\varphi_\varepsilon, x)| \leq C \varepsilon^{q-N} \text{ if } 0 < \varepsilon < \eta \end{cases} \quad (4)$$

Finally the algebra  $\mathcal{G}(\mathbb{R}^m)$  is defined as the quotient of  $\mathcal{E}_M[\mathbb{R}^m]$  with respect to  $\mathcal{N}[\mathbb{R}^m]$ .

In what follows, the elements of  $\mathcal{G}(\mathbb{R}^2)$  will be written with capital letters and their representatives in  $\mathcal{E}_M[\mathbb{R}^2]$  with small letters. Furthermore we use the following simplified notations :

$$u(\varphi_\varepsilon, x) = u^\varepsilon(x).$$

In our work we need a subset of  $\mathcal{E}_M[\mathbb{R}_+^2]$  that contains elements  $u$  satisfying the following properties:

(a)  $\exists N \in \mathbb{N}$  such that for all  $\varphi \in \mathcal{A}_N(\mathbb{R}_+^2)$

$$\exists c > 0 \quad \eta > 0 : \sup_{y \in \mathbb{R}_+^2} |u(\varphi_\varepsilon, y)| \leq c \quad \text{if } 0 < \varepsilon < \eta$$

(b) For every compact subset  $K$  of  $\mathbb{R}_+^2$ ,  $\exists N \in \mathbb{N}$  such that  $\forall \varphi \in \mathcal{A}_N(\mathbb{R}_+^2)$

$$\exists c > 0 \quad \exists \eta > 0 : \sup_{y \in K} |u(\varphi_\varepsilon, y)| \leq N \log\left(\frac{c}{\varepsilon}\right) \quad \text{if } 0 < \varepsilon < \eta$$

**Definition 1.** A generalized function  $U \in \mathcal{G}(\mathbb{R}_+^2)$  admitting a representative  $u$  with the property (a) (respectively (b)) is called globally bounded (respectively locally logarithmic growth).

**Definition 2.** the system (1) satisfies the compatibility conditions in  $\mathcal{G}(\mathbb{R}_+^2)$  if there exist  $u_0^\varepsilon, \lambda^\varepsilon, f^\varepsilon, h^\varepsilon, v^\varepsilon$  et  $a^\varepsilon$  the representatives of  $U_0, \Lambda, F, H, V$  and  $A$  that satisfy to the classic conditions compatibility in order to have a  $C^\infty$  solution for the classic problem.

**Theorem 3.** Let  $F, \Lambda$  and  $A$  be  $n \times n$  matrices with coefficients in  $\mathcal{G}(\mathbb{R}_+^2)$ , suppose that: there exists  $r$  as :

$$\Lambda_1 > \Lambda_2 > \cdots > \Lambda_r > 0 > \Lambda_{r+1} > \cdots > \Lambda_n$$

$\Lambda_i$  ( $i = 1, \dots, n$ ) are globally bounded,  $\partial_x \Lambda_i$  and  $F_i$  are locally logarithmic growth, so for an initial data  $U_0$  in  $\mathcal{G}(\mathbb{R}_+)$ ,  $V_i$  an element in  $\mathcal{G}(\mathbb{R}_+)$  globally bounded and  $H_i$  in  $\mathcal{G}(\mathbb{R}_+)$ , then the problem 1 has an unique solution in  $\mathcal{G}(\mathbb{R}_+^2)$ .

*Proof.* The proof of the theorem is an adaptation to the demonstration of the Theorem 1.2 in [4], therefore one is going to give the big lines rightly.

Let  $\lambda$  a representative of  $\Lambda$  in  $\mathcal{G}(\mathbb{R}_+^2)$  such that

$$\lambda_1 > \lambda_2 > \cdots > \lambda_r > 0 > \lambda_{r+1} > \cdots > \lambda_n$$

with  $\lambda_i$  satisfies the property (a) and  $\partial_x \lambda_i$  satisfies the property (b).

Let  $f$  and  $a$  are any representatives of  $F$  and  $A$  in  $\mathcal{G}(\mathbb{R}_+^2)$  with  $f$  satisfies (b).

$v, h$  and  $u_0$  are any representatives of  $V, H$  and  $U_0$  in  $\mathcal{G}(\mathbb{R}_+)$  with  $v$  satisfies (a).

So Let's consider the following problem

$$\begin{cases} \left( \partial_t + \lambda_i^\varepsilon(x, t) \partial_x \right) u_i^\varepsilon = \sum_{k=1}^n f_{ik}^\varepsilon(x, t) u_k^\varepsilon(x, t) + a_i^\varepsilon(x, t) & (x, t) \in (\mathbb{R}_+^*)^2 \\ u_i^\varepsilon(x, 0) = u_{0_i}^\varepsilon(x) & i = 1, \dots, n \quad x \in \mathbb{R}_+ \quad (\mathbf{I}_\varepsilon) \\ u_i^\varepsilon(0, t) = \sum_{k=r+1}^n v_{ik}^\varepsilon(t) u_k^\varepsilon(0, t) + h_i^\varepsilon(t) & i = 1, \dots, r \quad t \geq 0 \end{cases}$$

if we denote  $\gamma_i^\varepsilon$  the corresponding characteristic curve to  $\lambda_i^\varepsilon$  then the problem  $(\mathbf{I}_\varepsilon)$  admits an unique solution  $u^\varepsilon$ ,  $u_i^\varepsilon \in \mathcal{C}^\infty(\mathbb{R}_+^2)$  given by for  $i = r + 1, \dots, n$

$$u_i^\varepsilon(x, t) = u_{0_i}^\varepsilon(\gamma_i^\varepsilon(x, t, 0)) + \int_0^t \left[ \sum_{k=1}^n f_{ik}^\varepsilon(\gamma_i^\varepsilon(x, t, \tau), \tau) u_k^\varepsilon(\gamma_i^\varepsilon(x, t, \tau), \tau) + a_i^\varepsilon(\gamma_i^\varepsilon(x, t, \tau), \tau) \right] d\tau$$

for  $i = 1, \dots, r$

$$u_i^\varepsilon(x, t) = \sum_{k=r+1}^n v_{ik}^\varepsilon(t_0) \int_0^{t_0} \sum_{s=1}^n \left[ f_{ks}^\varepsilon(\gamma_k^\varepsilon(0, t_0, \tau), \tau) u_s^\varepsilon(\gamma_k^\varepsilon(0, t_0, \tau), \tau) \right] d\tau + \int_{t_0}^t \sum_{k=1}^n \left[ f_{ik}^\varepsilon(\gamma_i^\varepsilon(x, t, \tau), \tau) u_k^\varepsilon(\gamma_i^\varepsilon(x, t, \tau), \tau) \right] d\tau + \int_{t_0}^t a_i^\varepsilon(\gamma_i^\varepsilon(x, t, \tau), \tau) d\tau + \sum_{k=r+1}^n v_{ik}^\varepsilon(t_0) \int_0^{t_0} a_k^\varepsilon(\gamma_k^\varepsilon(0, t_0, \tau), \tau) d\tau + \sum_{k=r+1}^n v_{ik}^\varepsilon(t_0) u_{0_k}^\varepsilon(\gamma_k^\varepsilon(0, t_0, 0)) + h_i^\varepsilon(t_0)$$

where  $t_0$  is such that the curve  $\gamma_i$  cuts the axis  $(0t)$  at a point  $P_i(0, t_0)$ .  $u_i^\varepsilon$  is  $\mathcal{C}^\infty$  function, so it remains to show therefore that  $u_i^\varepsilon$  is moderate growth.

From assumptions, we have

$$\begin{aligned} \exists M > 0 \quad \text{such that : } & \left| \frac{d\gamma_i^\varepsilon(x, t, \tau)}{d\tau} \right| < M \quad \forall (x, t) \in \mathbb{R}_+^2 \quad \forall i = 1, \dots, n \\ \exists M_1 > 0 \quad \text{such that : } & \max_{i,j} |v_{i,j}^\varepsilon(y)| < M_1 \quad \forall y \in \mathbb{R}_+ \end{aligned}$$

Let  $K_0$  be a compact in  $\mathbb{R}_+$ , we draw the straight line with a slope  $-M$ , the determination domain  $K_T$  of the solution  $u_i^\varepsilon$  does not depend on  $\varepsilon$ .

**Lemma 4.** *Let  $u^\varepsilon$  a solution of problem  $(\mathbf{I}_\varepsilon)$  then  $u_i^\varepsilon$  verified*

$$\begin{aligned} \sup_{(x,t) \in K_T} |u_i^\varepsilon(x, t)| \leq M_2 & \left[ \sup_k \sup_{(x,t) \in K_T} |a_k^\varepsilon(x, t)| . T \right. \\ & \left. + \sup_k \sup_{x \in K_0} |u_{0_k}^\varepsilon(x)| + \sup_k \sup_{t \in [0, T]} |h_k^\varepsilon(t)| \right] \times \exp \left( n M_2 \sup_{i,k} \sup_{(x,t) \in K_T} |f_{ik}^\varepsilon(x, t)| . T \right) \end{aligned}$$

with  $M_2 = \max(nM_1, 1)$

*Proof.* for  $i = 1, \dots, r$ , and from the integral equation that verified by  $u_i^\varepsilon$  we have

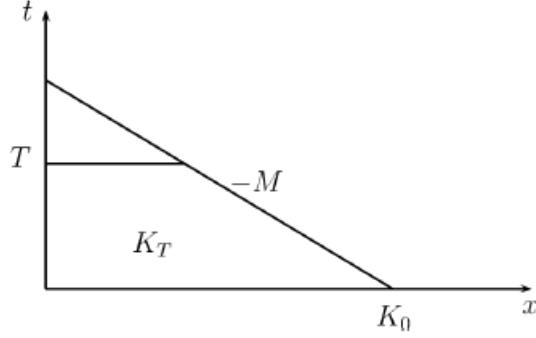


Figure 1

$$\begin{aligned} \sup_{(x,t) \in K_T} |u_i^\varepsilon(x,t)| &\leq M_2 \left[ T \sup_{(x,t) \in K_T} |a_k^\varepsilon(x,t)| + \sup_k \sup_{x \in K_0} |u_{0_k}^\varepsilon(x)| \right. \\ &\left. + \sup_k \sup_{t \in [0,T]} |h_k^\varepsilon(t)| \right] + nM_2 \int_0^T \sup_{(x,t) \in K_\tau} |f^\varepsilon(x,t)| \sup_k \sup_{(x,t) \in K_\tau} |u_k^\varepsilon(x,t)| d\tau \end{aligned}$$

and the proof is completed by applying the Gronwall's lemma to the function

$$s \rightarrow \max_k \sup_{(x,t) \in K_s} |u_k^\varepsilon(x,t)|$$

For  $i = r + 1, \dots, n$  it is the same way with  $t_0 = 0$ ,  $v = 0$ ,  $h = 0$ .  $\square$

the next of the proof of Theorem 1, we have:

$\exists N_1 \in \mathbb{N}$  such that :  $\forall \phi \in \mathcal{A}_{N_1}(\mathbb{R}_+)$

$$\exists C_1 > 0 \quad \exists \eta > 0 : \quad \sup_{(x,t) \in K_T} |a^\varepsilon(x,t)| \leq C_1 \varepsilon^{-N_1} \quad \text{if } 0 < \varepsilon < \eta$$

$\exists N_2 \in \mathbb{N}$  such that :  $\forall \phi \in \mathcal{A}_{N_2}(\mathbb{R}_+)$

$$\exists C_2 > 0 \quad \exists \eta > 0 : \quad \sup_{x \in K_0} |u_0^\varepsilon(x)| \leq C_2 \varepsilon^{-N_2} \quad \text{if } 0 < \varepsilon < \eta$$

$\exists N_3 \in \mathbb{N}$  such that :  $\forall \phi \in \mathcal{A}_{N_3}(\mathbb{R}_+)$

$$\exists C_3 > 0 \quad \exists \eta > 0 : \quad \sup_{t \in [0,T]} |h^\varepsilon(t)| \leq C_3 \varepsilon^{-N_3} \quad \text{if } 0 < \varepsilon < \eta$$

$\exists N_4 \in \mathbb{N}$  such that :  $\forall \phi \in \mathcal{A}_{N_4}(\mathbb{R}_+^2)$

$$\exists C_4 > 0 \quad \exists \eta > 0 : \quad \sup_{(x,t) \in K_T} |f^\varepsilon(x,t)| \leq N_4 \log \left( \frac{C_4}{\varepsilon} \right) \quad \text{if } 0 < \varepsilon < \eta$$

therefore according to the lemma, we have

$$\forall \phi \in \mathcal{A}_{N_5}, \quad \exists C > 0, \quad \eta > 0 : \quad \sup_{(x,t) \in K_T} |u_i^\varepsilon(x,t)| \leq C_5 \varepsilon^{-N_5} \quad \text{if } 0 < \varepsilon < \eta$$

with

$$N_5 = E(N_1 + N_2 + N_3 + NTC_4 N_4) + 1$$

for the other derivatives, differentiating the system  $(I_\varepsilon)$  for example with regard to  $x$ , one gets a system similar to the first. And because  $\partial_x \Lambda$  is locally logarithmic growth one gets the same estimation as before,  $\dots$ , then one has

$$u_i^\varepsilon \in \mathcal{E}_M(\mathbb{R}_+^2) \quad i = 1, \dots, n$$

either the existence of the solution for the problem (1) is in  $\mathcal{G}(\mathbb{R}_+^2)$ .

**Uniqueness.** Let  $U, V$  two solutions in  $\mathcal{G}(\mathbb{R}_+^2)$  of the problem  $(I_\varepsilon)$ , with the same initial data and the same boundary values. One must show that so  $u^\varepsilon$  is a representative of  $U$  and  $\mathcal{G}(\mathbb{R}_+^2)$  and if  $v^\varepsilon$  is a representative of  $V$  in  $\mathcal{G}(\mathbb{R}_+^2)$  then  $u^\varepsilon - v^\varepsilon \in \mathcal{N}(\mathbb{R}_+^2)$  see [2].

Indeed:  $u^\varepsilon - v^\varepsilon$  verifies the same problem that previously and therefore the demonstration is the same. Then one has

$$u^\varepsilon - v^\varepsilon = O(\varepsilon^q) \quad \forall q$$

□

**Remark 5.** To get the solution in the case where  $\Lambda \in \mathbf{L}^\infty(\mathbb{R}_+^2)$ ,  $F \in \mathbf{W}^{-1,\infty}(\mathbb{R}_+^2)$ , one uses the following result. see [4, Proposition 2]

**Proposition 6.** **a)** Let  $\omega \in \mathbf{W}_{loc}^{-1,\infty}(\mathbb{R}_+^2)$  then there exist  $U \in \mathcal{G}(\mathbb{R}^2)$  such that:  $U$  is associated to  $\omega$  and  $U$  is locally logarithmic growth.

**b)** Let  $\omega \in \mathbf{L}^\infty(\mathbb{R}^2)$  then there exist  $U \in \mathcal{G}(\mathbb{R}^2)$  such that:  $U$  is associated to  $\omega$  and  $U$  is globally bounded, and  $\partial^\alpha U$  is locally logarithmic growth.  $\alpha = (\alpha_1, \alpha_2)$  such that  $|\alpha| = \alpha_1 + \alpha_2 = 1$

**Remark 7.** For  $g \in \mathbf{L}^\infty(\mathbb{R}_+)$  one can find  $G \in \mathcal{G}(\mathbb{R}_+)$  such that  $G \approx g$ , and there exist a representative  $g^\varepsilon$  of  $G$  such that  $g^\varepsilon$  is nil at the neighborhood of 0 for all  $\varepsilon$ .

### 3. Application

Consider the problem ( 2 )

$$\left\{ \begin{array}{ll} \left( \partial_t + c(x) \partial_x \right) u(x, t) = 0 & (x, t) \in (\mathbb{R}_+^*)^2 \\ \left( \partial_t - c(x) \partial_x \right) v(x, t) = 0 & (x, t) \in (\mathbb{R}_+^*)^2 \\ u(x, 0) = u_0(x) & x \geq 0 \\ v(x, 0) = v_0(x) & x \geq 0 \\ u(0, t) = v(0, t) & t \geq 0 \\ + \text{Compatibility conditions} \end{array} \right.$$

with

$$c(x) = \begin{cases} c_R & \text{if } x > x_0 \\ c_L & \text{if } 0 < x < x_0 \end{cases}$$

For the initials data  $u_0, v_0$  continuous almost everywhere, and nil at neighborhood of 0.

The problem (2) admits a classic solution for

$$\{0 < x < x_0 : t \geq 0\} \quad \text{and} \quad \{x > x_0 : t \geq 0\}$$

and while imposing a passage condition on the  $x_0$  (continuity of  $u$  and  $v$  at the point  $x_0$  ) then one will have a solution on

$$\{x \geq 0 : t \geq 0\}$$

defined by

$$\begin{aligned} v(x, t) &= v_0(\gamma_2(x, t, 0)) \\ u(x, t) &= \begin{cases} u_0(\gamma_1(x, t, 0)) & \text{on (I)} \\ v(0, t) & \text{on (II)} \end{cases} \end{aligned}$$

so one designates by  $\Gamma$  the characteristic curve comes from of  $(0, 0)$  the part (I) designates the set of  $(x, t) \in \mathbb{R}_+^2$  below  $\Gamma$ . and the part (II) the set the points  $(x, t)$  over  $\Gamma$  (see the figure (2)).

$\gamma_1$  the connected curve characteristic corresponding to  $c$ .

$\gamma_2$  the connected curve characteristic corresponding to  $-c$ .

**Proposition 8.** *given  $u_0, v_0$  two continuous functions nearly everywhere, bounded and nil at the neighborhood of 0 then the problem (2) admit an unique solution  $U, V$  in  $\mathcal{G}(\mathbb{R}_+^2)$  besides one has:*

$$U \approx u \quad \text{and} \quad V \approx v$$



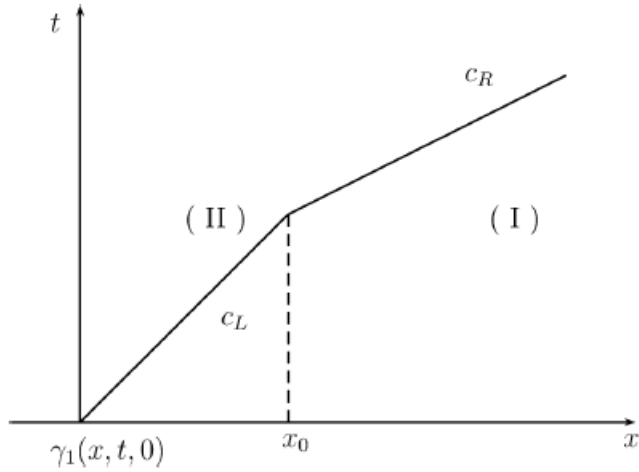


Figure 2

with  $u$  et  $v$  are the distributions solutions of the same problem obtained by imposing a passage condition.

*Proof.*  $c \in \mathbf{L}^\infty(\mathbb{R}_+)$ , from the proposition (1) there exists  $C \in \mathcal{G}(\mathbb{R}_+)$  such that  $C \approx c$ .

$c$  is globally bounded and  $\partial_x C$  is locally logarithmic growth. And so, from the theorem 1, there exists an unique solution  $U, V$  in  $\mathcal{G}(\mathbb{R}_+^2)$  of the problem (2).

To show that

$$U \approx u$$

we suppose that  $(x, t)$  belongs to the region limited by the broken characteristic curve  $\Gamma$  comes from the origin and the axis  $(ox)$  which we note (region I).

If  $(x, t)$  is over of this curve, the demonstration is identical but with reflection (region II) and for  $(x, t) \in \Gamma$  (the characteristic curve comes from the origin) this set is negligible.

Let:

$c^\varepsilon$  a representative of  $C$  in  $\mathcal{G}(\mathbb{R}_+)$ ,

$u_0^\varepsilon$  a representative of  $U_0$  in  $\mathcal{G}(\mathbb{R}_+)$ ,

$v_0^\varepsilon$  a representative of  $V_0$  in  $\mathcal{G}(\mathbb{R}_+)$ .

Considering then the following problem

$$\begin{cases} (\partial_t + c^\varepsilon \partial_x) u^\varepsilon = 0 & (x, t) \in (\mathbb{R}_+^*)^2 \\ (\partial_t - c^\varepsilon \partial_x) v^\varepsilon = 0 & (x, t) \in (\mathbb{R}_+^*)^2 \\ u^\varepsilon(x, 0) = u_0^\varepsilon(x) & x \in \mathbb{R}_+ \\ v^\varepsilon(x, 0) = v_0^\varepsilon(x) & x \in \mathbb{R}_+ \\ u^\varepsilon(0, t) = v^\varepsilon(0, t) & t \in \mathbb{R}_+ \end{cases}$$

This problem admits an unique solution  $u^\varepsilon, v^\varepsilon$  in  $\mathcal{C}^\infty(\mathbb{R}_+^2)$ .

Taking

$$\gamma_1^\varepsilon = \gamma_1 * \phi_{\eta_\varepsilon}$$

with  $\phi \in \mathcal{D}(\mathbb{R}^+)$  such that

$$\int_{\mathbb{R}^+} \phi(\lambda) d\lambda = 1 \quad \text{supp } \phi_{\eta_\varepsilon} \subset ]x_0 - \eta_\varepsilon, x_0 + \eta_\varepsilon[ \quad \eta_\varepsilon = |\log \varepsilon|^{-1}$$

it is evident that for all  $(x, t)$  in (region I)

$$u^\varepsilon(x, t) = u_0^\varepsilon(\gamma_1^\varepsilon(x, t, 0))$$

then to show that  $U \approx u$  it is necessary and sufficient to show that :

$$\forall \psi \in \mathcal{D}(\mathbb{R}_+^2)$$

$$\lim_{\varepsilon \rightarrow 0} \int_{\text{region I}} \left( u_0^\varepsilon(\gamma_1^\varepsilon(x, t, 0)) - u_0(\gamma_1(x, t, 0)) \right) \psi(x, t) dx dt = 0$$

we have

$$\begin{aligned} \int \left( u_0^\varepsilon(\gamma_1^\varepsilon(x, t, 0)) - u_0(\gamma_1(x, t, 0)) \right) \psi(x, t) dx dt = \\ \int \left( u_0^\varepsilon(\gamma_1^\varepsilon(x, t, 0)) - u_0(\gamma_1^\varepsilon(x, t, 0)) \right) \psi(x, t) dx dt \\ + \int \left( u_0(\gamma_1^\varepsilon(x, t, 0)) - u_0(\gamma_1(x, t, 0)) \right) \psi(x, t) dx dt \end{aligned}$$

but

$$\begin{aligned} \int \left( u_0^\varepsilon(\gamma_1^\varepsilon(x, t, 0)) - u_0(\gamma_1^\varepsilon(x, t, 0)) \right) \psi(x, t) dx dt \\ = \int (u_0^\varepsilon - u_0)(\gamma_1^\varepsilon(x, t, 0)) \psi(x, t) dx dt \\ \leq \sup_{x \in \mathbb{R}_+} |u_0 * \phi_\varepsilon - u_0| \left| \int_{\mathbb{R}_+^2} \psi(x, t) dx dt \right| \end{aligned}$$

so  $\lim_{\varepsilon \rightarrow 0} \int (u_0^\varepsilon(\gamma_1^\varepsilon(x, t, 0)) - u_0(\gamma_1^\varepsilon(x, t, 0))) \psi(x, t) dx dt = 0$

to show that  $\lim_{\varepsilon \rightarrow 0} \int (u_0(\gamma_1^\varepsilon(x, t, 0)) - u_0(\gamma_1(x, t, 0))) \psi(x, t) dx dt = 0$

it is sufficient to show that  $\lim_{\varepsilon \rightarrow 0} (\gamma_1^\varepsilon(x, t, 0) - \gamma_1(x, t, 0)) = 0$

or  $c$  is globally bounded, then  $\exists M > 0 \quad \sup_{x \in \mathbb{R}_+} |c^\varepsilon(x)| < M$ .

So we can surround the curve  $\gamma_1^\varepsilon$  between two broken curves, (see Figure 3) and taking the intersection of these two curves with the axis ( $0x$ ), it gives us two points

$$x_1 = c_L \left( -\frac{2\eta_\varepsilon}{M} - \frac{x_0 + \eta_\varepsilon - x}{c_R} - t \right) - \eta_\varepsilon + x_0$$

$$x_2 = -c_L \left( -\frac{2\eta_\varepsilon}{M} + \frac{x_0 + \eta_\varepsilon - x}{c_R} + t \right) - \eta_\varepsilon + x_0$$

such that

$$x_1 \leq \gamma_1^\varepsilon(x, t, 0) \leq x_2$$

hence

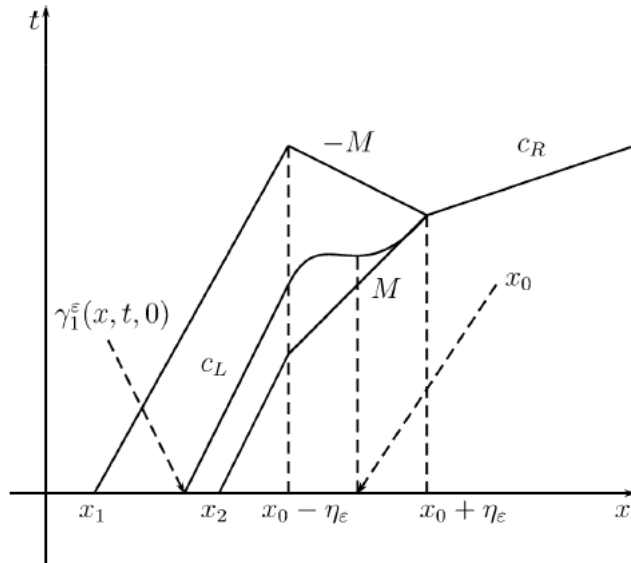


Figure 3

$$\lim_{\varepsilon \rightarrow 0} \gamma_1^\varepsilon(x, t, 0) = -c_L t + \frac{c_L}{c_R} (x - x_0) + x_0$$

$$= \gamma_1(x, t, 0)$$

then

$$U \approx u$$

for  $v$ , the demonstration is the same. □

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