

**SOME FIXED POINT THEOREMS OF  
MULTI-VALUED MAPPINGS IN  $G$ -METRIC SPACE**

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**Abstract:** In this paper, we prove some fixed point theorems concerning multi-valued mappings using  $A$  -type contraction in complete symmetric  $G$ -metric space.

Our results generalizes and improved many results in the existing literature.

**AMS Subject Classification:** 47H10, 54H25

**Key Words:**  $G$ -metric,  $A$  -type contraction, symmetric  $G$ -metric, weakly commuting mappings

## 1. Introduction

The simplicity and usefulness of fixed point theory has inspired many re-

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searchers to analyze it in multi-valued mappings. The work of B. Fisher and K. Iseiki [5] and Rhodes [11] is worth mentioning. M. S. Khan and I. Kubiacyk [6] generalized the results of Chang [4], Singh and Whitefield [13] and Khan [6]. F. U. Rehman and B. Ahmed [12] presents some fixed point results on fixed point theorems which improves the results of M. S. Khan and I. Kubiacyk [6].

In 2005, Mustafa and Sims [9] introduced a new structure of generalized metric space which are called  $G$ -metric as a generalization of metric space.

M. Akram, A. A. Siddiqui and A. A. Zafar in [1] introduced a general class of contractions, called  $A$ -contractions. This class properly contains contractions originally studied by R. Kannan [8], M. S. Khan [7], Bianchini [3] and Reich [10] for detail see [1].

In 2003, M. Akram, A. A. Siddiqui, and A. A. Zafar have proved some fixed point theorem concerning multi-valued mappings using  $A$ -contractions in metric space, for detail see [2]. Here, we prove some fixed point theorems concerning multi-valued mappings using  $A$ -type contraction in  $G$ -metric space.

Throughout sequel  $X$  will denote a complete symmetric  $G$ -metric space,  $\mathbb{R}_+$  denote the set of non-negative real numbers.

## 2. Preliminaries

**Definition 2.1.** [9] Let  $X$  be a nonempty set, and let  $G : X \times X \times X \rightarrow \mathbb{R}_+$  be a function satisfying the following properties,

- (i)  $G(x, y, z) = 0$  if  $x = y = z$ ,
- (ii)  $0 < G(x, x, y)$  for all  $x, y \in X$  with  $x \neq y$ ,
- (iii)  $G(x, x, y) \leq G(x, y, z)$  for all  $x, y, z \in X$ , with  $z \neq y$ ,
- (iv)  $G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$ , (symmetry in all three variables),
- (v)  $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$  for all  $x, y, z, a \in X$ , (rectangular inequality).

Then the function  $G$  is called a generalized metric or more specifically, a  $G$ -metric on  $X$ , and the pair  $(X, G)$  is called a  $G$ -metric space.

**Definition 2.2.** [9] A  $G$ -metric space  $(X, G)$  is called symmetric  $G$ -metric if  $G(x, y, y) = G(y, x, x)$  for all  $x, y \in X$ .

**Proposition 2.3.** [9] Let  $(X, G)$  be a  $G$ -metric space, then the following are equivalent,

- (i)  $\{x_n\}$  is  $G$ -convergent to  $x$ ,
- (ii)  $G(x_n, x_n, x) \rightarrow 0$ , as  $n \rightarrow \infty$ ,
- (iii)  $G(x_n, x, x) \rightarrow 0$ , as  $n \rightarrow \infty$ ,
- (iv)  $G(x_m, x_n, x) \rightarrow 0$ , as  $m, n \rightarrow \infty$ .

**Proposition 2.4.** [9] Let  $(X, G)$  be a  $G$ -metric space, then the following are equivalent,

- (i)  $\{x_n\}$  is  $G$ -Cauchy,
- (ii) for  $\epsilon > 0$ , there exist  $N \in \mathbb{N}$  such that  $G(x_n, x_m, x_m) < \epsilon$ , for all  $n, m \geq N$ .

**Definition 2.5.** Let  $G$  be a  $G$ -metric on a set  $X$ . For subsets  $A$  and  $B$  of a  $G$ -metric space  $X$ ,

$$D(A, B, B) = \inf\{G(a, b, b) : a \in A, b \in B\}.$$

$$\delta(A, B, B) = \sup\{G(a, b, b) : a \in A, b \in B\}.$$

$$H(A, B, B) = \max\{\sup\{D(a, a, B) : a \in A\}, \sup\{D(A, b, b) : b \in B\}\}.$$

**Definition 2.6.** A mapping  $T : X \rightarrow Y$  associating with each element  $x$  of  $X$ , a subset  $T(x)$  of set  $Y$ , that is, if for each  $x \in X$  the subset  $T(x)$  of set  $Y$  is called a multi-valued mapping.

**Definition 2.7.** Let  $T : X \rightarrow CB(X)$  be a mapping, a point  $x \in X$  is said to be a fixed point of a multi-valued mapping  $T$  provided  $x \in Tx$ .

**Definition 2.8.** In a  $G$ -metric space  $X$ , the mapping  $f : X \rightarrow X$  and  $T : X \rightarrow CB(X)$  are said to be weakly commuting if for each  $x$  in  $X$  and  $fTx$  in  $CB(X)$ ,

$$H(fTx, Tfy, Tfy) \leq D(Tx, fy, fy).$$

**Definition 2.9.** [2] Let  $A$  stands for the set of all functions  $\alpha : \mathbb{R}_+^3 \rightarrow \mathbb{R}_+$  satisfying,

- (i)  $\alpha$  is continuous on the set  $\mathbb{R}_+^3$  of all triplets of nonnegative reals (with respect to the Euclidean  $G$ -metric on  $\mathbb{R}_+^3$ ).
- (ii)  $\alpha$  is non-decreasing in each coordinate variable.
- (iii)  $a \leq kb$ , for some  $k \in [0, 1)$  whenever  $a \leq \alpha(a, b, b)$  or  $a \leq \alpha(b, a, b)$  or  $a \leq \alpha(b, b, a)$ , for all  $a, b \in \mathbb{R}_+$ .

**Definition 2.10.** *A -type Contraction.* A map  $T : X \rightarrow 2^X$  is said to be  $A$  -type contraction of  $X$  if there exists  $\alpha \in A$  such that

$$\delta(Tx, Ty, Ty) \leq \alpha(\delta(x, y, y), \delta(x, Tx, Tx), \delta(y, Ty, Ty)),$$

for all  $x, y$  in  $X$ .

### 3. Some fixed point theorems

**Theorem 3.1.** *Let  $S, T : X \rightarrow B(X)$  are mappings such that*

$$\delta(Sx, Ty, Ty) \leq \alpha(\delta(x, y, y), \delta(x, Sx, Sx), \delta(y, Ty, Ty)) \dots (1),$$

where  $\alpha \in A$ , then  $S$  and  $T$  have a common fixed point.

*Proof.* Let  $x_0 \in X$ . Choose a point  $x_{2n-1}$  in  $X_{2n-1} = Sx_{2n-2}$  and  $x_{2n}$  in  $X_{2n} = Tx_{2n-1}$ , for  $n = 1, 2, 3, \dots$

Now,

$$\delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) = \delta(Sx_{2n}, Tx_{2n+1}, Tx_{2n+1}).$$

Using (1), we get

$$\begin{aligned} \delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) &\leq \alpha(\delta(x_{2n}, x_{2n+1}, x_{2n+1}), \delta(x_{2n}, Sx_{2n}, Sx_{2n}) \\ &\quad , \delta(x_{2n+1}, Tx_{2n+1}, Tx_{2n+1})), \\ &\leq \alpha(\delta(x_{2n}, x_{2n+1}, x_{2n+1}), \delta(x_{2n}, X_{2n+1}, X_{2n+1}) \\ &\quad , \delta(x_{2n+1}, X_{2n+2}, X_{2n+2})), \\ &\leq \alpha(\delta(X_{2n}, X_{2n+1}, X_{2n+1}), \delta(X_{2n}, X_{2n+1}, X_{2n+1}) \\ &\quad , \delta(X_{2n+1}, X_{2n+2}, X_{2n+2})). \end{aligned}$$

Using definition of  $\alpha$ , we get

$$\delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) \leq k(\delta(X_{2n}, X_{2n+1}, X_{2n+1})),$$

for some  $k \in [0, 1)$ . Proceeding on the same line, we get

$$\begin{aligned}\delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) &\leq k(k\delta(X_{2n-1}, X_{2n}, X_{2n})), \\ &\leq k^2\delta(X_{2n-1}, X_{2n}, X_{2n}).\end{aligned}$$

Continuing in this way, we have

$$\delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) \leq k^{2n}\delta(X_0, X_1, X_1),$$

for all  $n \in N$ .

Which in fact gives

$$\delta(X_n, X_{n+1}, X_{n+1}) \leq k^n\delta(X_0, X_1, X_1) \dots (2).$$

Using the relation between  $G$  and  $\delta$  and applying (2), we get

$$\begin{aligned}G(x_n, x_{n+1}, x_{n+1}) &\leq \delta(X_n, X_{n+1}, X_{n+1}). \\ &\leq k^n\delta(X_0, X_1, X_1).\end{aligned}$$

Now, for  $n > m \geq 0$ , using rectangular property of  $G$ -metric space, we get

$$\begin{aligned}G(x_m, x_n, x_n) &\leq G(x_m, x_{m+1}, x_{m+1}) + G(x_{m+1}, x_{m+2}, x_{m+2}) \\ &\quad + G(x_{m+2}, x_{m+3}, x_{m+3}) \\ &\quad + \dots + G(x_{n-1}, x_n, x_n), \\ &\leq k^m\delta(X_0, X_1, X_1) + k^{m+1}\delta(X_0, X_1, X_1) + k^{m+2}\delta(X_0, X_1, X_1) \\ &\quad + \dots + k^{n-1}\delta(X_0, X_1, X_1), \\ &\leq \delta(X_0, X_1, X_1)\{k^m + k^{m+1} + k^{m+2} + \dots + k^{n-1}\}, \\ &\leq \delta(X_0, X_1, X_1)k^m\{1 + k + k^2 + \dots + k^{n-m-1}\}, \\ &\leq \delta(X_0, X_1, X_1)k^m \left( \frac{1 - k^{n-m}}{1 - k} \right).\end{aligned}$$

As  $k < 1$ ,  $G(x_m, x_n, x_n) \rightarrow 0$  as  $m \rightarrow \infty$ .

Thus  $\{x_n\}$  is a Cauchy sequence in  $X$ . Since  $X$  is complete,  $x_n \rightarrow x$  in  $X$ .

Next  $D(Sx, x_{2n}, x_{2n}) \leq \delta(Sx, Tx_{2n-1}, Tx_{2n-1})$ , using inequality (1), we get

$$\begin{aligned}D(Sx, x_{2n}, x_{2n}) &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(x, Sx, Sx), \delta(x_{2n-1}, Tx_{2n-1}, Tx_{2n-1})), \\ &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(x, Sx, Sx), \delta(x_{2n-1}, X_{2n}, X_{2n})), \\ &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(x, Sx, Sx), \delta(X_{2n-1}, X_{2n}, X_{2n})), \\ &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(x, Sx, Sx), k^{2n-1}\delta(X_0, X_1, X_1)),\end{aligned}$$

Taking limit as  $n \rightarrow \infty$  and using the fact that  $X$  is symmetric  $G$ -metric space, we have

$$\begin{aligned} D(Sx, x, x) &\leq \alpha(\delta 0, (Sx, x, x), 0), \\ &\leq k0, \\ &= 0. \end{aligned}$$

This implies,  $D(Sx, x, x) = 0$ , which finally gives that  $x \in Sx$ .

Similarly, we can show that  $x \in Tx$ .

Thus  $x$  is common fixed point of  $S$  and  $T$ .

**Corollary 3.2.** *Let  $T : X \rightarrow B(X)$  is mapping such that*

$$\delta(Tx, Ty, Ty) \leq \alpha(\delta(x, y, y), \delta(x, Tx, Tx), \delta(y, Ty, Ty)),$$

where  $\alpha \in A$ , then  $T$  have a fixed point.

*Proof.* The proof follows by taking  $S = T$  in above theorem.

**Corollary 3.3.** *Let  $S, T : X \rightarrow B(X)$  are mapping satisfying any one of the following contractive conditions,*

(i) *There exist a number  $a \in [0, \frac{1}{2})$  such that for all  $x, y$  in  $X$ ,*

$$\delta(Sx, Ty, Ty) \leq a(\delta(x, Sx, Sx) + \delta(y, Ty, Ty)).$$

(ii) *There exist a number  $h \in [0, 1)$  such that for all  $x, y$  in  $X$ ,*

$$\delta(Sx, Ty, Ty) \leq h\sqrt{\delta(x, Sx, Sx)\delta(y, Ty, Ty)}.$$

(iii) *There exist a number  $h \in [0, 1)$  such that for all  $x, y$  in  $X$ ,*

$$\delta(Sx, Ty, Ty) \leq h\max\{\delta(x, Sx, Sx), \delta(y, Ty, Ty)\}.$$

(iv) *There exist numbers  $a, b, c \in [0, 1)$  such that  $a + b + c < 1$  and for all  $x, y$  in  $X$ ,*

$$\delta(Sx, Ty, Ty) \leq a\delta(x, y, y) + b\delta(x, Sx, Sx) + c\delta(y, Ty, Ty).$$

(v) *There exist a number  $h \in [0, 1)$  such that for all  $x, y, z$  in  $X$ ,*

$$G(Sx, Ty, Tz) \leq k\max\{G(x, Sx, Sx), G(y, Ty, Ty), G(z, Tz, Tz)\}.$$

Then  $S$  and  $T$  have a common fixed point in  $X$ .

*Proof.* By defining an appropriate  $\alpha$ , it is not difficult to show that above contractions are  $A$ -type contraction. Also, we have proved that  $A$ -type contraction has fixed point in complete symmetric  $G$ -metric space, hence it follows that the above contractions have fixed point.

**Theorem 3.4.** Let  $f : X \rightarrow X$  and  $S, T : X \rightarrow B(X)$  be mappings such that

- (i)  $f, S$  or  $T$  are continuous.
- (ii)  $Sx \subseteq f(X)$  and  $Tx \subseteq f(X)$ .
- (iii)  $f$  weakly commutes with  $S$  and  $T$ .
- (iv)  $\delta(Sx, Ty, Ty) \leq \alpha(\delta(x, y, y), \delta(x, Sx, Sx), \delta(y, Ty, Ty))$  for all  $x, y$  in  $X$  and for some  $\alpha \in A$ .

Then  $f, S$  and  $T$  have a common fixed point.

*Proof.* Let  $x_0 \in X$ , define a sequence  $\{x_n\}$  in  $X$  as  $x_{2n+1} = fx_{2n} \in X_{2n+1} = Sx_{2n}$  and  $x_{2n+2} = Tx_{2n+1} \in X_{2n+2} = Tx_{2n+1}$ .

Now, using the relation between  $G$  and  $\delta$  and applying the definition of  $\alpha$ , we have

$$\begin{aligned} G(fx_{2n}, fx_{2n+1}, fx_{2n+1}) &\leq \delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) = \delta(Sx_{2n}, Tx_{2n+1}, Tx_{2n+1}), \\ \delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) &\leq \alpha(\delta(x_{2n}, x_{2n+1}, x_{2n+1}), \delta(x_{2n}, Sx_{2n}, Sx_{2n}), \\ &\quad \delta(x_{2n+1}, Tx_{2n+1}, Tx_{2n+1})), \\ &\leq \alpha(\delta(x_{2n}, x_{2n+1}, x_{2n+1}), \delta(x_{2n}, X_{2n+1}, X_{2n+1}), \\ &\quad \delta(x_{2n+1}, X_{2n+2}, X_{2n+2})), \\ &\leq \alpha(\delta(X_{2n}, X_{2n+1}, X_{2n+1}), \delta(X_{2n}, X_{2n+1}, X_{2n+1}), \\ &\quad \delta(X_{2n+1}, X_{2n+2}, X_{2n+2})). \end{aligned}$$

Using definition of  $\alpha$ , we get  $\delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) \leq k\delta(X_{2n}, X_{2n+1}, X_{2n+1})$ , for some  $k \in [0, 1)$ .

Continuing in the same way, we get

$$\delta(X_{2n+1}, X_{2n+2}, X_{2n+2}) \leq k^{2n}\delta(X_0, X_1, X_1).$$

In general

$$G(fx_{n-1}, fx_n, fx_n) \leq \delta(X_n, X_{n+1}, X_{n+1}) = k^n \delta(X_0, X_1, X_1) \dots (1).$$

Using the relation between  $G$  and  $\delta$  and applying (1), we get

$$\begin{aligned} G(x_n, x_{n+1}, x_{n+1}) &\leq \delta(X_n, X_{n+1}, X_{n+1}), \\ &\leq k^n \delta(X_0, X_1, X_1). \end{aligned}$$

Now, for  $n > m \geq 0$ , using rectangular property of  $G$ -metric space, we get

$$\begin{aligned} G(x_m, x_n, x_n) &\leq G(x_m, x_{m+1}, x_{m+1}) \\ &\quad + G(x_{m+1}, x_{m+2}, x_{m+2}) + G(x_{m+2}, x_{m+3}, x_{m+3}) \\ &\quad + \dots + G(x_{n-1}, x_n, x_n), \\ &\leq k^m \delta(X_0, X_1, X_1) + k^{m+1} \delta(X_0, X_1, X_1) + k^{m+2} \delta(X_0, X_1, X_1) \\ &\quad + \dots + k^{n-1} \delta(X_0, X_1, X_1), \\ &\leq \delta(X_0, X_1, X_1) \{k^m + k^{m+1} + k^{m+2} + \dots + k^{n-1}\}, \\ &\leq \delta(X_0, X_1, X_1) k^m \{1 + k + k^2 + \dots + k^{n-m-1}\}, \\ &\leq \delta(X_0, X_1, X_1) k^m \left( \frac{1 - k^{n-m}}{1 - k} \right). \end{aligned}$$

As  $k < 1$ , so when  $m \rightarrow \infty$  we get  $G(x_m, x_n, x_n) = G(fx_{m-1}, fx_{n-1}, fx_{n-1}) = 0$ .

Thus  $\{fx_n\}$  or  $\{x_n\}$  is a Cauchy sequence in  $X$ .

Since  $X$  is complete  $fx_n \rightarrow x$  in  $X$ .

Next, using the relation between  $D$  and  $\delta$  and applying the definition of  $\alpha$ , we have

$$\begin{aligned} D(Sx, fx_{2n-1}, fx_{2n-1}) &= D(Sx, x_{2n}, x_{2n}) \leq \delta(Sx, x_{2n}, x_{2n}) \\ &= \delta(Sx, Tx_{2n-1}, Tx_{2n-1}). \end{aligned}$$

$$\begin{aligned} D(Sx, x_{2n}, x_{2n}) &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(x, Sx, Sx), \delta(x_{2n-1}, Tx_{2n-1}, Tx_{2n-1})), \\ &= \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(x, Sx, Sx), \delta(x_{2n-1}, X_{2n}, X_{2n})), \\ &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(x, Sx, Sx), \delta(X_{2n-1}, X_{2n}, X_{2n})). \end{aligned}$$

Since  $X$  is symmetric  $G$ -metric space, we can write

$$\begin{aligned} D(Sx, x_{2n}, x_{2n}) &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(Sx, x, x), \delta(X_{2n-1}, X_{2n}, X_{2n})), \\ &\leq \alpha(\delta(x, x_{2n-1}, x_{2n-1}), \delta(Sx, x, x), k^{2n-1} \delta(X_0, X_1, X_1)). \end{aligned}$$

Taking limit as  $n \rightarrow \infty$ , we have

$$\begin{aligned} D(Sx, x, x) &\leq \alpha(0, \delta(Sx, x, x), 0), \\ &\leq k0, \\ &= 0. \end{aligned}$$

This implies that  $x \in Sx$ .

Similarly we can show that  $x \in Tx$ .

Now suppose  $f$  and  $S$  is continuous and since  $f$  weakly commutes with  $S$ , we have

$$\begin{aligned} G(x, fx, fx) &\leq G(x, ff x_{2n+1}, ff x_{2n+1}) + G(ff x_{2n+1}, fx, fx), \\ &\leq qH(Sx, fSx_{2n}, fSx_{2n}) + G(ff x_{2n+1}, fx, fx), \text{ where } q > 1, \\ &\leq q\{H(Sx, Sf x_{2n}, Sf x_{2n}) + H(Sf x_{2n}, fSx_{2n}, fSx_{2n})\} \\ &\quad + G(ff x_{2n+1}, fx, fx). \end{aligned}$$

Now by using definition of weakly commuting, we can write

$$\begin{aligned} G(x, fx, fx) &\leq q\{H(Sx, Sf x_{2n}, Sf x_{2n}) + D(fx_{2n}, Sx_{2n}, Sx_{2n})\} \\ &\quad + G(ff x_{2n+1}, fx, fx) \dots (2). \end{aligned}$$

Taking limit as  $n \rightarrow \infty$ , we have  $H(Sx, Sf x_{2n}, Sf x_{2n}) = H(x, x, x) = 0$ ,  $D(Sx_{2n}, fx_{2n}, fx_{2n}) = G(x, x, x) = 0$ , and  $G(ff x_{2n+1}, fx, fx) = G(x, x, x) = 0$ .

So equation (2) becomes,  $G(x, fx, fx) \leq 0$ .

That is,  $G(x, fx, fx) = 0$ .

This gives that  $x = f(x) \in Sx \cap Tx$

**Corollary 3.5.** *Let  $f : X \rightarrow X$  and  $S, T : X \rightarrow B(X)$  be mappings such that it satisfies conditions (i), (ii) and (iii) of Theorem 3.4 and condition (iv) is replaced by any of the following contractive conditions:*

(i) *There exist a number  $a \in [0, \frac{1}{2})$  such that for all  $x, y$  in  $X$ ,*

$$\delta(Sx, Ty, Ty) \leq a(\delta(x, Sx, Sx) + \delta(y, Ty, Ty)).$$

(ii) *There exist a number  $h \in [0, 1)$  such that for all  $x, y$  in  $X$ ,*

$$\delta(Sx, Ty, Ty) \leq h\sqrt{\delta(x, Sx, Sx)\delta(y, Ty, Ty)}.$$

(iii) There exist a number  $h \in [0, 1)$  such that for all  $x, y$  in  $X$ ,

$$\delta(Sx, Ty, Ty) \leq h \max\{\delta(x, Sx, Sx), \delta(y, Ty, Ty)\}.$$

(iv) There exist numbers  $a, b, c \in [0, 1)$  such that  $a + b + c < 1$  and for all  $x, y$  in  $X$ ,

$$\delta(Sx, Ty, Ty) \leq a\delta(x, y, y) + b\delta(x, Sx, Sx) + c\delta(y, Ty, Ty).$$

(v) There exist a number  $h \in [0, 1)$  such that for all  $x, y, z$  in  $X$ ,

$$G(Sx, Ty, Tz) \leq k \max\{G(x, Sx, Sx), G(y, Ty, Ty), G(z, Tz, Tz)\}.$$

Then  $f, S$  and  $T$  have a common fixed point.

*Proof.* By defining an appropriate  $\alpha$ , its not difficult to show that above contractions are  $A$ -type contraction. Also, we have proved that the mapping  $f, S$  and  $T$  satisfying the  $A$ -type contraction condition along with condition (i), (ii) and (iii) have common fixed point, hence it follows that  $f, S$  and  $T$  have common fixed point.

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