

**GROUP THEORETICAL JUSTIFICATION OF  
A “SIMPLE” COSMOLOGICAL MODEL**

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**Abstract:** We have found a group theoretical justification of a simple cosmological model that describes a spherically symmetrical expansion of the Universe in the case of equality of the initial and critical densities of matter.

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## 1. Introduction

Many exact analytical solutions of linear and nonlinear equations in mathemat-

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ical physics are invariant under certain groups of transformations of dependent and independent variables allowed by the mathematical model [1, 2]. Knowledge of the full symmetry group of the mathematical model (this group is algorithmically computed [1, 2]) allows us to formulate a program for SUBMODELS, with the aim of obtaining a “full set” of invariant and partially invariant solutions of the original “big model” [3]. Among invariant solutions, “simple” solutions play a crucial role. To find “simple” solutions, you need to solve algebraic equations instead of differential ones [4]. In [5], the program SUBMODELS was formulated to model Newtonian cosmology. In the study, we consider a “simple” solution for a spherically symmetrical submodel within the domain of Newtonian cosmology, which would be of interest to astrophysics.

## 2. Model and it’s “simple” invariant solution

The system of differential equations describing the model of spherically symmetrical motion of an ideal nonrelativistic self-gravitating fluid with zero pressure is as follows:

$$\begin{aligned} U_t + UU_r + \Phi_r &= 0, \\ \rho_t + U\rho_r + \rho \left( \frac{2U}{r} + U_r \right) &= 0, \\ \frac{2\Phi_r}{r} + \Phi_{rr} &= \rho, \end{aligned} \tag{1}$$

where  $\Phi$  is the gravitational potential,  $\rho$  is the density,  $U$  is the radial velocity,  $r$  is the polar radius,  $t$  is time. All variables are dimensionless [5].

This system admits an infinite-dimensional Lie algebra with a three-dimensional subalgebra  $L_3$  with basic generators

$$\begin{aligned} \hat{X}_1 &= 2\Phi\partial_\Phi + U\partial_U + r\partial_r, \\ \hat{X}_2 &= -2\rho\partial_\rho + r\partial_r + t\partial_t, \\ \hat{X}_3 &= \partial_t, \end{aligned} \tag{2}$$

and an infinite-dimensional subalgebra with generator  $\hat{X} = F_1(t)\partial_\Phi$ , where  $F_1(t)$  is an arbitrary function of time  $t$ . To obtain simple solutions to system (1), it is necessary to know the optimal system of two-dimensional subalgebras of the algebra  $L_3$ . In [5], it was established that the optimal system consists of subalgebras  $\langle X_1, X_2 \rangle$ ,  $\langle X_1, X_3 \rangle$ ,  $\langle aX_1 + X_2, X_3 \rangle$ ,  $a \geq 0$ .

Consider the subalgebra  $\langle X_1, X_2 \rangle$ ; invariants are to be found from the conditions  $X_1\psi = 0, X_2\psi = 0$  [1]. In other words, the invariant of this two-dimensional subalgebra is the function that satisfies the overdetermined system of equations:

$$\begin{aligned} 2\Phi\psi_\Phi + U\psi_U + r\psi_r &= 0, \\ -2\rho\psi_\rho + r\psi_r + t\psi_t &= 0. \end{aligned} \quad (3)$$

The system of characteristic equations for the first equation of the system (2) has the form

$$\frac{d\Phi}{2\Phi} = \frac{dU}{U} = \frac{dr}{r}.$$

Hence, we find the basic invariants  $J_1 = \Phi/r^2$  and  $J_2 = U/r, t, \rho$ . Consequently,  $\psi = \psi(J_1, J_2, t, \rho)$ . Substituting  $\psi$  in the second equation of the system (3) gives

$$2\rho\psi_\rho + 2J_1\psi_{J_1} + J_2\psi_{J_2} - t\psi_t = 0. \quad (4)$$

The system of characteristic equations for equation (4) has the form

$$\frac{d\rho}{2\rho} = \frac{dJ_1}{2J_1} = \frac{dJ_2}{J_2} = \frac{dt}{-t}.$$

Hence, we find the following list of basic invariants of subalgebra  $\langle X_1, X_2 \rangle$ :  $\rho t^2, J_1 t^2, J_2 t$ . Finally, we have

$$\begin{aligned} \rho &= \frac{C_1}{t^2}, \\ \Phi &= C_2 \left(\frac{r}{t}\right)^2, \\ U &= C_3 \frac{r}{t}, \end{aligned} \quad (5)$$

where  $C_1, C_2,$  and  $C_3$  are undefined constants. Substituting (5) in (1), we obtain the system for determining the constants:

$$\begin{aligned} -C_3 + C_3^2 + 2C_2 &= 0, \\ C_1(-2 + 3C_3) &= 0, \\ C_1 &= 6C_2. \end{aligned}$$

This system has three solutions:

$$(a) \quad C_1 = C_2 = C_3 = 0;$$

(b)  $C_1 = C_2 = 0, C_3 = 1$ ;

(c)  $C_1 = 2/3 = C_3, C_2 = 1/9$ .

Case (a) leads to the trivial solution  $U = 0, \rho = 0, \Phi = 0$ .

In case (b), we obtain a solution with no physical meaning.

In case (c), we obtain a nontrivial solution:

$$\begin{aligned}\rho &= \frac{2}{3} \frac{1}{t^2}, \\ U &= \frac{2}{3} \frac{r}{t}, \\ \Phi &= \frac{1}{9} \left( \frac{r}{t} \right)^2.\end{aligned}$$

This solution describes (in terms of Newtonian approximation) the spherically symmetrical expansion of the Universe in the case of equality of the initial and critical densities of matter [6]. The group theoretical nature of this solution has not been previously addressed in physical literature. The study also shows that the solutions, which are invariant under the subalgebras  $\langle X_1, X_3 \rangle$  and  $\langle aX_1 + X_2, X_3 \rangle$ , are either trivial solutions  $U = 0, \rho = 0, \Phi = 0$  or reduced to trivial solutions by an appropriate choice of gravitational potential calibrations.

### 3. Conclusion

In the framework of the SUBMODELS program, which was originally formulated for modeling Newtonian cosmology, we found “simple” solutions of spherically symmetrical submodels. In this assessment, we demonstrated that a unique nontrivial simple invariant solution coincides with the solution itself, which is derived from physical plane considerations. The search for simple solutions of the original “big model” is a subject of future research.

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