

**A COUPLED SYSTEM OF FUNCTIONAL DIFFERENTIAL  
EQUATIONS IN REFLEXIVE BANACH SPACES**

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**Abstract:** We present an existence theorem for at least one weak solution for the coupled system of functional differential equations

$$x'(t) = f_1(t, y'(t)), t \in (0, T],$$

$$y'(t) = f_2(t, x'(t)), t \in (0, T]$$

in reflexive Banach spaces.

**AMS Subject Classification:** 35D30, 34Gxx

**Key Words:** weak solution, functional differential equations, O'Regan fixed point theorem, coupled system

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**1. Introduction and Preliminaries**

Let  $E$  be a reflexive Banach space with norm  $\| \cdot \|$  and dual  $E^*$ , and  $L^1(I)$  be the space of Lebesgue integrable functions on the interval  $I = [0, T]$ . Denote by  $C[I, E]$  the Banach space of strongly continuous functions  $x : I \rightarrow E$  with sup-norm  $\| \cdot \|_0$ .

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Received: October 8, 2016

Revised: December 7, 2016

Published: February 28, 2017

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url: [www.acadpubl.eu](http://www.acadpubl.eu)

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Such systems appear in many problems of applied nature (see [1],[3], [4],[9]-[11] and [13]). Su [18] discussed a two-point boundary value problem for a coupled system of fractional differential equations. Gafiychuk et al. [11] analyzed the solutions of coupled nonlinear fractional reaction-diffusion equations. The solvability of the coupled systems of integral equations in reflexive Banach space was proved in (see [5]-[7]).

In [15], O'Regan studied, in the reflexive Banach space, the existence of weak solutions of the initial value problem

$$\frac{d}{dt}x(t) = f(t, x(t)), \quad t \in (0, T].$$

Recently, the authors studied the existence of weak solutions of the initial value problem

$$\frac{d}{dt}x(t) = f(t, \frac{d}{dt}x(t)), \quad t \in (0, T].$$

in reflexive and nonreflexive Banach spaces (see [8]).

In this paper we study the existence of weak solutions for the coupled system of the functional differential equations

$$\frac{dx}{dt} = f_1(t, \frac{dy}{dt}), \quad x(0) = x_0, \quad t \in (0, T] \quad (1)$$

$$\frac{dy}{dt} = f_2(t, \frac{dx}{dt}), \quad y(0) = y_0, \quad t \in (0, T] \quad (2)$$

in the reflexive Banach space  $E$ . For this aim we study, firstly, the existence of weak solutions for the coupled system of the functional equations

$$u(t) = f_1(t, v(t)), \quad t \in I \quad (3)$$

$$v(t) = f_2(t, u(t)), \quad t \in I \quad (4)$$

in the reflexive Banach space  $E$ .

Now, we shall present some auxiliary results that will be needed in this work.

- (1) A function  $h : E \rightarrow E$  is said to be weakly Lipschitz if for every  $\phi \in E^*$  there exists a positive constant  $K$  such that

$$\phi(h(x(\cdot)) - h(y(\cdot))) \leq K \phi(x(\cdot) - y(\cdot)).$$

- (2)  $h(\cdot)$  is said to be weakly continuous if for every  $\phi \in E^*$ ,  $\phi(h(\cdot))$  is continuous see ([12] and [14]).

- (3) A function  $h : E \rightarrow E$  is said to be weakly sequentially continuous if  $h$  maps weakly convergent sequences in  $E$  to weakly convergent sequences in  $E$ .

It is clear that (1) implies (2) and (2) implies (3). If  $h$  linear, then (2) and (3) are equivalent. The relation between weak and weak sequentially continuous of mapping is studied in details in [2].

Now, we have the following theorem due to Rubin (see [16]) and some propositions which will be used in the sequel (see [7] and [17]).

**Theorem 1.** *If  $E$  is metrizable (i.e., the topology is induced by a metric). Then the weakly sequentially continuous functions are weakly continuous.*

**Proposition 1.** *A subset of a reflexive Banach space is weakly compact if and only if it is closed in the weak topology and bounded in the norm topology.*

The following result follows directly from the Hahn-Banach theorem.

**Proposition 2.** *Let  $E$  be a normed space with  $x_0 \neq 0$ . Then there exists a  $\phi \in E^*$  with  $\|\phi\| = 1$  and  $\phi(x_0) = \|x_0\|$ .*

Also, we have the following fixed point theorem, due to O'Regan, in reflexive Banach space (see [14]).

**Theorem 2.** *(O'Regan fixed point theorem) Let  $E$  be a Banach space and let  $Q$  be a nonempty, bounded, closed and convex subset of the space  $E$  and let  $F : Q \rightarrow Q$  be a weakly sequentially continuous and assume that  $FQ(t)$  is relatively weakly compact in  $E$  for each  $t \in I$ . Then,  $F$  has a fixed point in the set  $Q$ .*

## 2. Coupled System of Functional Equations

Here, we discuss the existence of weak solutions for the coupled system (3)-(4) in the reflexive Banach space  $E$ .

The coupled system (3)-(4) will be investigated under the following assumptions :

$f_i : I \times E \rightarrow E$ ,  $i = 1, 2$  such that

- (i) For each  $u \in C[I, E]$ ,  $f_i(\cdot, u(\cdot))$  are continuous on  $I$ ;
- (ii) For each  $t \in I$ ,  $f_i(t, \cdot)$  are weakly Lipschitz with Lipschitz constants  $K_i$ ,

where  $a_i = \sup\{\phi(f_i(t, 0)) : t \in I\}$ .

Now, let  $X$  be the class of all ordered pairs  $(u, v)$ ,  $u, v \in C[I, E]$  with the norm

$$\|(u, v)\| = \|u\| + \|v\|.$$

**Definition 1.** By a solution to the coupled system (3)-(4), we mean the pair of functions  $(u, v) \in X$ ,  $u, v \in C[I, E]$  which satisfies (3)-(4) weakly. This is equivalent to finding  $(u, v) \in X$ ,  $u, v \in C[I, E]$  with

$$\phi(u(t)) = \phi(f_1(t, v(t))), \quad t \in I$$

$$\phi(v(t)) = \phi(f_2(t, u(t))), \quad t \in I$$

for all  $\phi \in E^*$ .

Now, we can prove the following existence theorem.

**Theorem 3.** Under the assumptions (i)-(ii), the coupled system (3)-(4) has at least one weak solution  $(u, v) \in X$ ,  $u, v \in C[I, E]$ .

*Proof.* Define the operator  $A$  by

$$A(u(t), v(t)) = (A_1v(t), A_2u(t))$$

where

$$A_1v(t) = f_1(t, v(t)), \quad t \in I$$

$$A_2u(t) = f_2(t, u(t)), \quad t \in I.$$

Now, define the set  $\Omega$  by

$$\Omega = \{(u, v), \quad u, v \in C[I, E] : \|v\|_0 \leq r_1, \quad \|u\|_0 \leq r_2, \quad r = r_1 + r_2\}.$$

The remainder of the proof will be given in four steps.

**Step 1:** The operator  $A$  maps  $X$  into itself. For this, let  $u, v \in C[I, E]$ . Let  $t_1, t_2 \in I$ ,  $t_2 > t_1$ , (without loss of generality assume that  $A(u, v)(t_2) - A(u, v)(t_1) \neq 0$ ), then

$$\begin{aligned} A_1v(t_2) - A_1v(t_1) &= f_1(t_2, v(t_2)) - f_1(t_1, v(t_1)) \\ &= f_1(t_2, v(t_2)) - f_1(t_1, v(t_1)) \\ &\quad - f_1(t_2, v(t_1)) + f_1(t_2, v(t_1)) \end{aligned}$$

by proposition 2 we have

$$\|A_1v(t_2) - A_1v(t_1)\| = \phi(A_1v(t_2) - A_1v(t_1))$$

$$\begin{aligned}
&\leq \phi(f_1(t_2, v(t_2)) - f_1(t_2, v(t_1))) \\
&+ \phi(f_1(t_2, v(t_1)) - f_1(t_1, v(t_1))) \\
&\leq K_1 \phi(v(t_2) - v(t_1)) \\
&+ \phi(f_1(t_2, v(t_1)) - f_1(t_1, v(t_1))) \\
&\leq K_1 \|v(t_2) - v(t_1)\| \\
&+ \|f_1(t_2, v(t_1)) - f_1(t_1, v(t_1))\|.
\end{aligned}$$

Similarity, we can show that

$$\begin{aligned}
\|A_2u(t_2) - A_2u(t_1)\| &\leq K_2 \|u(t_2) - u(t_1)\| \\
&+ \|f_2(t_2, u(t_1)) - f_2(t_1, u(t_1))\|.
\end{aligned}$$

Therefore,

$$\begin{aligned}
\|A(u, v)(t_2) - A(u, v)(t_1)\| &= \|(A_1v(t_2), A_2u(t_2)) \\
&- (A_1v(t_1), A_2u(t_1))\| \\
&= \|(A_1v(t_2) - A_1v(t_1), A_2u(t_2) \\
&- A_2u(t_1))\| \\
&= \|A_1v(t_2) - A_1v(t_1)\| \\
&+ \|A_2u(t_2) - A_2u(t_1)\| \\
&\leq K_1 \|v(t_2) - v(t_1)\| \\
&+ \|f_1(t_2, v(t_1)) - f_1(t_1, v(t_1))\| \\
&+ K_2 \|u(t_2) - u(t_1)\| \\
&+ \|f_2(t_2, u(t_1)) - f_2(t_1, u(t_1))\|.
\end{aligned}$$

Which prove that  $A : X \rightarrow X$ .

**Step 2:** The operator  $A$  maps  $\Omega$  into itself. Let  $(u, v) \in \Omega$  then by proposition 2 we have

$$\begin{aligned}
\|A_1v(t)\| &= \phi(A_1v(t)) = \phi(f_1(t, v(t))) \\
&\leq \phi(f_1(t, 0)) + K_1 \phi(v(t)) \\
&\leq a_1 + K_1 \|v\|_0 \\
&\leq a_1 + K_1 r_1.
\end{aligned}$$

Then

$$\|A_1v\|_0 = \sup_{t \in I} \|A_1v(t)\| \leq a_1 + K_1 r_1 = r_1, \quad r_1 = \frac{a_1}{1 - K_1}.$$

Similarity, we can show that

$$\| A_2 u \|_0 \leq a_2 + K_2 r_2 = r_2, \quad r_2 = \frac{a_2}{1 - K_2}.$$

Now

$$\| A(u, v)(t) \| = \| (A_1 v(t), A_2 u(t)) \| \leq \| A_1 v(t) \| + \| A_2 u(t) \| \leq r.$$

Then

$$\| A(u, v) \|_0 \leq r.$$

Hence, for any  $(u, v) \in \Omega$  we have  $A(u, v) \in \Omega$ , consequently  $A\Omega \subset \Omega \Rightarrow A : \Omega \rightarrow \Omega$ .

**Step 3:**  $A\Omega(t)$  is relatively weakly compact in  $E$ . Note that  $\Omega$  is nonempty, closed, convex and bounded subset of  $X$ . According to proposition 1,  $A\Omega$  is bounded in  $X$  and closed in weak topology, hence  $A\Omega$  is relatively weakly compact in  $X$  implies  $A\Omega(t)$  is relatively weakly compact in  $E$  for each  $t \in I$ .

**Step 4:** The operator  $A$  is weakly sequentially continuous on  $\Omega$ . Let  $\{V_n\}$  be sequence in  $\Omega$  converges weakly to  $V$ , then we have the two sequences  $\{v_n(t)\}, \{u_n(t)\}$  converges weakly to  $v(t), u(t)$ , respectively for all  $t \in I$ . Since  $f_1(t, v(t)), f_2(t, u(t))$  are weakly Lipschitz, then  $f_1(t, v(t)), f_2(t, u(t))$  are weakly continuous, then we have that  $f_1(t, v(t)), f_2(t, u(t))$  are weakly sequentially continuous in the second argument. Thus  $f_1(t, v_n(t)), f_2(t, u_n(t))$  converges weakly to  $f_1(t, v(t)), f_2(t, u(t))$  respectively, then  $\phi(f_1(t, v_n(t))), \phi(f_2(t, u_n(t)))$  converges strongly to  $\phi(f_1(t, v(t))), \phi(f_2(t, u(t)))$  respectively. Thus

$$\phi(A_1 v_n(t)) \rightarrow \phi(A_1 v(t)), \quad \phi(A_2 u_n(t)) \rightarrow \phi(A_2 u(t)),$$

i.e.  $\| A_1 v_n(t) \| \rightarrow \| A_1 v(t) \|$  and  $\| A_2 u_n(t) \| \rightarrow \| A_2 u(t) \|$ .

Therefore,

$$\begin{aligned} \| AV_n(t) \| &= \| (A_1 v_n(t), A_2 u_n(t)) \| \\ &= \| A_1 v_n(t) \| + \| A_2 u_n(t) \| \\ &\rightarrow \| A_1 v(t) \| + \| A_2 u(t) \| \\ &\rightarrow \| (A_1 v(t), A_2 u(t)) \| \\ &\rightarrow \| AV(t) \| . \end{aligned}$$

This means that  $\phi(AV_n(t)) \rightarrow \phi(AV(t)), \forall \phi \in E^*, t \in I$ . Thus,  $A : \Omega \rightarrow \Omega$  is weakly sequentially continuous.

Since all conditions of Theorem 2 are satisfied, then the operator  $A$  has at least one fixed point  $(u, v) \in \Omega$ , then the coupled system (3)-(4) has at least one weak solution.  $\square$

### 3. Initial Value Problem

Consider now the coupled system of the initial value problems (1)-(2)

**Theorem 4.** *Under the assumptions of Theorem 3, the coupled system of the initial value problems (1)-(2) has at least one solution  $(x, y) \in X$ .*

*Proof.* Let  $\frac{dx}{dt} = u \in C[I, E]$  and  $\frac{dy}{dt} = v \in C[I, E]$ , then

$$x(t) = x_0 + \int_0^t u(s)ds \in C[I, E],$$

and

$$y(t) = y_0 + \int_0^t v(s)ds \in C[I, E],$$

are differentiable and  $(u(t), v(t))$  will be the solution of the coupled system of the functional equations

$$u(t) = f_1(t, v(t)), \quad t \in [0, T],$$

$$v(t) = f_2(t, u(t)), \quad t \in [0, T].$$

□

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