

**FIXED POINT THEOREMS AND STABILITY FOR  
SEVERAL CLASSES OF MULTI-VALUED MAPPINGS**

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**Abstract:** In this paper several fixed point theorems and a stability theorem for some new classes of multi-valued contractive type and nonlinear mappings are given. The results presented in this paper improve and generalize some results in literatures.

**AMS Subject Classification:** 54H25

**Key Words:** multi-valued contractive type mapping, multi-valued nonlinear mapping, fixed point, stability

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Received: July 20, 2006

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### 1. Introduction

Let  $(X, d)$  be a metric space and  $CL(X)$  (respectively,  $CB(X)$ ,  $C(X)$ ) denote the family of all nonempty closed (nonempty closed bounded, nonempty compact) subsets of  $X$ . For  $c \in X$ ,  $A, B \in CL(X)$  and  $T : X \rightarrow CL(X)$ , define

$$\begin{aligned} F(T) &= \{x \in X : x \in Tx\}, \quad d(c, B) = \inf_{y \in B} d(c, y), \\ H_-(A, B) &= \sup_{x \in A} d(x, B), \quad H_+(A, B) = H_-(B, A), \\ H(A, B) &= \max\{H_-(A, B), H_+(B, A)\}. \end{aligned}$$

Obviously,

$$\begin{aligned} d(x, y) &= H_-(\{x\}, \{y\}) = H_+(\{x\}, \{y\}), \\ H_-(\{x\}, A) &= d(x, A), \quad \forall x, y \in X, A \in CL(X). \end{aligned}$$

In 1969, Nadler [10] first studied the existence and stability of fixed points for the multi-valued contraction mapping and proved the following nice result.

**Theorem 1.1.** (see [10]) *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow CB(X)$  be a multi-valued contraction mapping, that is, there exists a constant  $r \in [0, 1)$  satisfying*

$$H(Tx, Ty) \leq rd(x, y), \quad \forall x, y \in X. \quad (1.1)$$

*Then  $T$  has a fixed point in  $X$ .*

Afterwards, many researchers gave various generalizations of Nadler's results, for example, see [1-11] and the references cited therein. In particular, Lim [3] extended Nadler's Stability Theorem from  $CB(X)$  to  $CL(X)$  and Wang [11] obtained a few extensions of Nadler and Lim's results from the class of multi-valued contraction mappings (1.1) to the larger class of multi-valued mappings (1.2) below: there exist there exist constants  $\alpha, \beta \in [0, 1)$  with  $\alpha + 2\beta < 1$  satisfying

$$H_-(Tx, Ty) \leq \alpha d(x, y) + \beta[d(x, Tx) + d(y, Ty)], \quad \forall x, y \in X. \quad (1.2)$$

On the other hand, Liu [4] proved some periodic point results for the following single-valued mappings:

$$\begin{aligned} d(x, y) &> a[d(x, T^m x) + d(y, T^m y)] + bd(T^m x, T^m y), \\ &\forall x, y \in \overline{O(x_0, T^m)} \text{ with } x \neq y, \quad (1.3) \end{aligned}$$

where  $a$  and  $b$  are constants with  $2a + b > 1$ ,  $a \leq 1$ ,  $b > 0$ ,  $m$  is a positive integer and  $O(x_0, T^m) = \{T^{nm}x_0\}_{n \geq 0}$ .

Motivated and inspired by the work [1-4, 10, 11], in this paper, we introduce a new class of multi-valued contractive type mappings and a few classes of multi-valued nonlinear mappings in complete metric spaces and show several fixed point theorems and a stability theorem for the multi-valued contractive type mappings and multi-valued nonlinear mappings. The results presented in this paper extend and improve some known results in [1, 3, 10, 11].

### 2. Preliminaries and Lemmas

**Lemma 2.1.** (see [11]) *Let  $(X, d)$  be a metric space and  $A, B \in CL(X)$ . Then:*

- (a)  $H_-(A, B) \geq 0$ ;
- (b)  $H_-(A, B) = 0$  if and only if  $A \subseteq B$ ;
- (c)  $H_-(A, B) \leq H_-(A, C) + H_-(C, B)$  for any  $A, B, C \in CL(X)$ .

**Remark 2.1.** If  $H_-$  is replaced by  $H_+$ , then Lemma 2.1 holds also.

**Lemma 2.2.** *Let  $(X, d)$  be a metric space and  $A, B \in CL(X)$ . Then:*

- (a) for any  $\varepsilon > 0$  and  $a \in A$ , there exists  $b \in B$  such that

$$d(a, b) < H_-(A, B) + \varepsilon;$$

- (b) for any  $\varepsilon > 0$ ,  $r > 1$  and  $a \in A$ , there exists  $b \in B$  such that

$$d(a, b) \leq rH_-(A, B).$$

*Proof.* (a) Let  $\varepsilon > 0$  and  $a \in A$  be arbitrary. It follows that there exists some  $b \in B$  with  $d(a, b) < d(a, B) + \varepsilon$ . Note that  $d(a, B) \leq H_-(A, B)$ . Thus  $d(a, b) < H_-(A, B) + \varepsilon$ .

(b) Let  $\varepsilon > 0, r > 1$  and  $a \in A$ . Suppose that  $H_-(A, B) = 0$ . Lemma 2.1 ensures that  $A \subseteq B$ . Consequently, for  $b = a \in A \subseteq B$ , we deduce that  $d(a, b) = 0 = rH_-(A, B)$ . Suppose that  $H_-(A, B) > 0$ . If (b) does not hold, it follows that there exist  $r_0 > 1$  and  $a_0 \in A$  with  $d(a_0, b) > r_0H_-(A, B), \forall b \in B$ . It is clear that

$$d(a_0, B) \geq r_0H_-(A, B) \geq r_0d(a_0, B), \tag{2.1}$$

which implies that  $(1 - r_0)d(a_0, B) \geq 0$ , that is,  $d(a_0, B) = 0$ . It follows from (2.1) that  $H_-(A, B) = 0$ , which is a contradiction. This completes the proof.  $\square$

**Remark 2.2.** Lemma 2.2 (a) is a generalization of Lemma 1 in [1].

**Lemma 2.3.** Let  $(X, d)$  be a metric space. Then:

- (a)  $|d(x, A) - d(x, B)| \leq H(A, B), \forall x, y \in X, A, B \in CL(X);$   
 (b)  $|d(x, A) - d(y, A)| \leq d(x, y), \forall x, y \in X, A \in CL(X).$

*Proof.* (a) Let  $A, B \in CL(X), x, y \in X, z \in B$ . It follows from Lemma 2.1 that

$$d(x, A) \leq d(x, z) + d(z, A) \leq d(x, z) + H_-(B, A),$$

which implies that

$$d(x, A) \leq d(x, B) + H_-(B, A).$$

Similarly,  $d(x, B) \leq d(x, A) + H_-(A, B)$ . Consequently, we get that

$$|d(x, A) - d(x, B)| \leq \max\{H_-(A, B), H_-(B, A)\} = H(A, B).$$

(b) Let  $A \in CL(X), x, y \in X, a \in A$ . Obviously,

$$d(x, a) \leq d(x, y) + d(y, a),$$

which implies that

$$d(x, A) \leq d(x, y) + d(y, A).$$

Similarly,  $d(y, A) \leq d(x, y) + d(x, A)$ . Therefore,  $|d(x, A) - d(y, A)| \leq d(x, y)$ . This completes the proof.  $\square$

### 3. Fixed Point Theorems

In this section, we first prove a fixed point theorem for multi-valued contractive type mapping (3.1), which extends the corresponding results of Nadler [10] and Wang [11]. Furthermore, we give an example to show that our result indeed generalizes Theorem 2.4 of [11]. Second, we prove a fixed point theorem for a few classes of multi-valued nonlinear mappings (3.5)-(3.8) in complete metric spaces.

**Theorem 3.1.** Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow CL(X)$  be a multi-valued mapping satisfying

$$H_-(Tx, Ty) \leq \alpha \max \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{1}{2}[d(x, Ty) + d(y, Tx)], \frac{[1 + d(y, Ty)]d(y, Tx)}{1 + d(x, Tx)} \right\}, \quad \forall x, y \in X, \quad (3.1)$$

where  $\alpha$  is a constant in  $[0, 1)$ . Then  $T$  has a fixed point in  $X$ .

*Proof.* Let  $\varepsilon > 0$  be arbitrary. We claim that there exists a sequence  $\{x_n\}_{n \geq 0}$  satisfying  $x_{n+1} \in Tx_n$  and

$$d(x_n, x_{n+1}) \leq \alpha^n d(x_0, x_1) + n\alpha^n \varepsilon \quad n \geq 0. \quad (3.2)$$

Pick an arbitrary point  $x_0 \in X$ . Choose a point  $x_1 \in Tx_0$ . Clearly, (3.2) holds for  $n = 0$ . Suppose that (3.2) holds for some  $n \geq 0$ . Lemma 2.1 implies that there exists some point  $x_{n+2} \in Tx_{n+1}$  such that

$$\begin{aligned} & d(x_{n+1}, x_{n+2}) \\ & \leq H_-(Tx_n, Tx_{n+1}) + \alpha(1 - \alpha)\varepsilon \\ & \leq \alpha \max\{d(x_n, x_{n+1}), d(x_n, Tx_n), d(x_{n+1}, Tx_{n+1}), \\ & \quad \frac{1}{2}[d(x_n, Tx_{n+1}) + d(x_{n+1}, Tx_n)], \\ & \quad \frac{[1 + d(x_{n+1}, Tx_{n+1})]d(x_{n+1}, Tx_n)}{1 + d(x_n, Tx_n)}\} + \alpha(1 - \alpha)\varepsilon \\ & \leq \alpha \max\left\{d(x_n, x_{n+1}), d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2}), \frac{1}{2}d(x_n, x_{n+2}), 0\right\} \\ & \quad + \alpha(1 - \alpha)\varepsilon \\ & = \alpha \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\} + \alpha(1 - \alpha)\varepsilon. \end{aligned} \quad (3.3)$$

Suppose that  $d(x_n, x_{n+1}) \leq d(x_{n+1}, x_{n+2})$ . It follows from (3.3) that

$$\begin{aligned} d(x_{n+1}, x_{n+2}) & \leq \alpha d(x_{n+1}, x_{n+2}) + \alpha(1 - \alpha)\varepsilon, \\ & \leq \alpha d(x_{n+1}, x_{n+2}) + \alpha(1 - \alpha)d(x_n, x_{n+1}) + \alpha(1 - \alpha)\varepsilon, \end{aligned}$$

which yields that

$$d(x_{n+1}, x_{n+2}) \leq \alpha d(x_n, x_{n+1}) + \alpha\varepsilon. \quad (3.4)$$

Suppose that  $d(x_n, x_{n+1}) > d(x_{n+1}, x_{n+2})$ . (3.3) means that

$$\begin{aligned} d(x_{n+1}, x_{n+2}) & \leq \alpha d(x_n, x_{n+1}) + \alpha(1 - \alpha)\varepsilon \\ & \leq \alpha d(x_n, x_{n+1}) + \alpha\varepsilon, \end{aligned}$$

that is, (3.4) holds. In terms of (3.4), we see that

$$\begin{aligned} d(x_{n+1}, x_{n+2}) & \leq \alpha[\alpha^n d(x_0, x_1) + n\alpha^n \varepsilon] + \alpha\varepsilon \\ & = \alpha^{n+1}d(x_0, x_1) + (n + 1)\alpha^{n+1}\varepsilon. \end{aligned}$$

Therefore (3.2) holds for  $n + 1$ . Consequently, (3.2) holds for every  $n \geq 0$ . For any  $m \geq 1$  and  $p \geq 1$ , by (3.2) we infer that

$$\begin{aligned} d(x_m, x_{m+p}) &\leq \sum_{n=m}^{p-1} d(x_n, x_{n+1}) \leq \sum_{n=m}^{p-1} [\alpha^n d(x_0, x_1) + n\alpha\varepsilon] \\ &\leq \frac{\alpha^m}{1-\alpha} d(x_0, x_1) + \varepsilon \sum_{n=m}^{p-1} n\alpha^n. \end{aligned}$$

Notice that  $\alpha \in [0, 1)$  and

$$\lim_{m \rightarrow \infty} \left[ \frac{\alpha^m}{1-\alpha} d(x_0, x_1) + \varepsilon \sum_{n=m}^{\infty} n\alpha^n \right] = 0.$$

Hence  $\{x_n\}_{n \geq 0}$  is a Cauchy sequence and there exists some  $z \in X$  with  $\lim_{n \rightarrow \infty} x_n = z$  by completeness of  $X$ .

Now we prove that  $z$  is the fixed point of  $T$ . In fact, by (3.1), Lemma 2.1 and Lemma 2.3, we infer that

$$\begin{aligned} d(z, Tz) &\leq d(z, x_n) + d(x_n, Tx_n) + H_-(Tx_n, Tz) \\ &\leq d(z, x_n) + d(x_n, x_{n+1}) + \alpha \max\{d(x_n, z), d(x_n, Tx_n), d(z, Tz), \\ &\quad \frac{1}{2}[d(x_n, Tz) + d(z, Tx_n)], \frac{[1 + d(z, Tz)]d(z, Tx_n)}{1 + d(x_n, Tx_n)}\} \\ &\leq d(z, x_n) + d(x_n, x_{n+1}) + \alpha \max\{d(x_n, z), d(x_n, x_{n+1}), d(z, Tz), \\ &\quad \frac{1}{2}[d(x_n, z) + d(z, Tz) + d(z, x_{n+1})], [1 + d(z, Tz)]d(z, x_{n+1})\} \end{aligned}$$

for all  $n \geq 0$ . Letting  $n \rightarrow \infty$  in the above inequalities, we conclude that

$$\begin{aligned} d(z, Tz) &\leq \alpha \max\left\{0, 0, d(z, Tz), \frac{1}{2}[0 + d(z, Tz) + 0], 0\right\} \\ &= \alpha d(z, Tz), \end{aligned}$$

which implies that  $z \in Tz$ . This completes the proof.  $\square$

**Remark 3.1.** Theorem 5 of Nadler [10] and Theorem 2.4 of Wang [11] are special cases of Theorem 3.1. The following examples reveal that Theorem 3.1 extends properly these results of Nadler [10] and Wang [11].

**Example 3.1.** Let  $X = [0, 1]$  with the usual metric and define a multi-valued mapping  $T : X \rightarrow CL(X)$  by

$$Tx = \begin{cases} \{0, \frac{x}{5}\} & \text{for } x \in [0, \frac{1}{2}), \\ \{0, \frac{x}{6}\} & \text{for } x \in [\frac{1}{2}, 1]. \end{cases}$$

It is clear that the multi-valued mapping  $T$  satisfies (3.1) with  $\alpha = \frac{7}{10}$ . Thus Theorem 3.1 guarantees that  $T$  has a fixed point in  $X$ . Note that for  $x \in [0, \frac{1}{2})$ ,

$$\begin{aligned} H\left(Tx, T\frac{1}{2}\right) &= H\left(\left\{0, \frac{x}{5}\right\}, \left\{0, \frac{1}{12}\right\}\right) \\ &= \max\left\{\min\left\{\frac{x}{5}, \left|\frac{x}{5} - \frac{1}{12}\right|\right\}, \min\left\{\frac{1}{12}, \left|\frac{x}{5} - \frac{1}{12}\right|\right\}\right\}. \end{aligned}$$

This implies that  $\lim_{x \rightarrow (\frac{1}{2})^-} H(Tx, T\frac{1}{2}) = \frac{1}{60} \neq 0$ . It follows that  $T$  is not continuous at  $\frac{1}{2}$ . Consequently,  $T$  is not a multi-valued contraction mapping and therefore, Theorem 5 in [10] is not applicable.

**Example 3.2.** Let  $X = \{1, 2, 3, 8\}$  with the usual metric. Define a multi-valued mapping  $T : X \rightarrow CL(X)$  by  $T2 = \{8\}, Tx = \{3, 8\}$  for  $x \in \{1, 3, 8\}$ . It is easy to check the multi-valued mapping  $T$  satisfies (3.1) with  $\alpha = \frac{6}{7}$ . Thus Theorem 3.1 guarantees that  $T$  has a fixed point in the complete metric space  $X$ . But we do not invoke Theorem 2.4 in [11] to show that  $T$  possesses a fixed point in  $X$  since

$$\begin{aligned} H_-(T1, T2) &= 5 > 4 \geq (\alpha + 2\beta) \max\left\{d(2, 1), \frac{1}{2}[d(2, T2) + d(1, T1)]\right\} \\ &\geq \alpha d(2, 1) + \beta[d(2, T2) + d(1, T1)] \end{aligned}$$

for any nonnegative constants  $\alpha, \beta$  with  $\alpha + 2\beta < 1$ .

**Theorem 3.2.** Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow C(X)$  be a continuous multi-valued mapping such that for any different  $x, y \in X$ , at least one of the following conditions is fulfilled:

$$\begin{aligned} &\max\left\{d(x, y), d(x, Tx), \frac{d(y, Tx)d(x, Ty)}{d(x, y)}, \frac{d(y, Tx)d(x, Tx)}{d(x, y)}\right\} \\ &> a \min\left\{d(x, Tx), d(y, Ty), \frac{d^2(x, Tx)}{d(x, y)}, \frac{d(x, Tx)d(y, Ty)}{d(x, y)}\right\} \quad (3.5) \\ &+ bH_-(Tx, Ty), \end{aligned}$$

where  $a, b$  are nonnegative constants with  $a + b = 1$ ;

$$\begin{aligned} & \max\{d^2(x, y), d(y, Tx)d(x, Ty), d(y, Tx)d(x, Tx), d(x, y)d(x, Tx)\} \\ & > a \min\{d^2(x, Tx), d^2(y, Ty), d(x, Tx)H_-(Tx, Ty), \\ & \quad d(y, Ty)H_-(Tx, Ty)\} + bH_-^2(Tx, Ty), \end{aligned} \quad (3.6)$$

where  $a, b$  are nonnegative constants with  $a + b = 1$ ;

$$\begin{aligned} & \max\{d^2(x, y), d^2(y, Ty), d(x, y)d(x, Tx)\} \\ & > a \min\{d^2(x, Tx), d(x, y)d(y, Ty), d(y, Tx)d(x, Ty)\} + H_-^2(Tx, Ty), \end{aligned} \quad (3.7)$$

where  $a$  is a constant in  $(-\infty, +\infty)$ ;

$$\begin{aligned} H_-(Tx, Ty) < \max \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{1}{2}[d(x, Ty) + d(y, Tx)], \right. \\ \left. \frac{[1 + d(y, Ty)]d(y, Tx)}{1 + d(x, Tx)} \right\}. \end{aligned} \quad (3.8)$$

Assume that there exists a sequence  $\{x_n\}_{n \geq 0} \subset X$  with

$$d(x_n, x_{n+1}) = d(x_n, Tx_n), \quad x_{n+1} \in Tx_n, \quad \forall n \geq 0 \quad (3.9)$$

and the sequence has a cluster point  $z \in X$ . Then  $z$  is a fixed point of  $T$ .

*Proof.* We claim that  $x_n \neq x_{n+1}$  for each  $n \geq 0$ . Otherwise there exists some  $k \geq 0$  such that  $x_k = x_{k+1}$ . Consequently,  $x_k = x_{k+1} \in Tx_k$  and  $d(x_{k+1}, x_{k+2}) = d(x_{k+1}, Tx_{k+1}) = 0$ , which gives that  $x_k = x_{k+1} = x_{k+2}$ . It is easy to see that  $x_n = x_k$  for any  $n > k$ . Thus  $\{x_n\}_{n \geq 0}$  does not have a cluster point, which is impossible.

We now assert that

$$d(x_{n+1}, x_{n+2}) < d(x_n, x_{n+1}), \quad \forall n \geq 0. \quad (3.10)$$

Let  $n$  be a nonnegative integer. We have to consider the following cases:

Case 1. Suppose that (3.5) holds for  $x_n$  and  $x_{n+1}$ . It follows from (3.5) and



(3.9) that

$$\begin{aligned}
 & d(x_n, x_{n+1}) \\
 &= \max \left\{ d(x_n, x_{n+1}), d(x_n, Tx_n), \frac{d(x_{n+1}, Tx_n)d(x_n, Tx_{n+1})}{d(x_n, x_{n+1})}, \right. \\
 &\quad \left. \frac{d(x_{n+1}, Tx_n)d(x_n, Tx_n)}{d(x_n, x_{n+1})} \right\} \\
 &> a \min \left\{ d(x_n, Tx_n), d(x_{n+1}, Tx_{n+1}), \frac{d^2(x_n, Tx_n)}{d(x_n, x_{n+1})}, \right. \\
 &\quad \left. \frac{d(x_n, Tx_n)d(x_{n+1}, Tx_{n+1})}{d(x_n, x_{n+1})} \right\} + bH_-(Tx_n, Tx_{n+1}) \\
 &\geq a \min \{ d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2}), d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2}) \} \\
 &\quad + bd(x_{n+1}, Tx_{n+1}) \\
 &= a \min \{ d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2}) \} + bd(x_{n+1}, x_{n+2}).
 \end{aligned} \tag{3.11}$$

If  $d(x_n, x_{n+1}) \leq d(x_{n+1}, x_{n+2})$ , it follows from (3.11) that

$$d(x_n, x_{n+1}) > ad(x_n, x_{n+1}) + bd(x_{n+1}, x_{n+2}),$$

which yields that

$$(1 - a)d(x_n, x_{n+1}) > bd(x_{n+1}, x_{n+2}) \geq (1 - a)d(x_n, x_{n+1}),$$

which is a contradiction. Hence  $d(x_{n+1}, x_{n+2}) < d(x_n, x_{n+1})$ ;

Case 2. Suppose that (3.6) holds for  $x_n$  and  $x_{n+1}$ . By virtue of (3.6) and (3.9) we see that

$$\begin{aligned}
 & d^2(x_n, x_{n+1}) \\
 &= \max \{ d^2(x_n, x_{n+1}), d(x_{n+1}, Tx_n)d(x_n, Tx_{n+1}), \\
 &\quad d(x_{n+1}, Tx_n)d(x_n, Tx_n), d(x_n, x_{n+1})d(x_n, Tx_n) \} \\
 &> a \min \{ d^2(x_n, Tx_n), d^2(x_{n+1}, Tx_{n+1}), d(x_n, Tx_n)H_-(Tx_n, Tx_{n+1}), \\
 &\quad d(x_{n+1}, Tx_{n+1})H_-(Tx_n, Tx_{n+1}) \} + bH_-^2(Tx_n, Tx_{n+1}) \\
 &\geq a \min \{ d^2(x_n, x_{n+1}), d^2(x_{n+1}, x_{n+2}), d(x_n, x_{n+1})d(x_{n+1}, Tx_{n+1}), \\
 &\quad d(x_{n+1}, x_{n+2})d(x_{n+1}, Tx_{n+1}) \} + bd^2(x_{n+1}, Tx_{n+1}) \\
 &= a \min \{ d^2(x_n, x_{n+1}), d^2(x_{n+1}, x_{n+2}) \} + bd^2(x_{n+1}, x_{n+2}).
 \end{aligned} \tag{3.12}$$

If  $d(x_n, x_{n+1}) \leq d(x_{n+1}, x_{n+2})$ , from (3.12) we deduce that

$$d^2(x_n, x_{n+1}) > ad^2(x_n, x_{n+1}) + bd^2(x_{n+1}, x_{n+2})$$

$$\geq (a + b)d^2(x_n, x_{n+1}) = d^2(x_n, x_{n+1}),$$

which is impossible and hence  $d(x_{n+1}, x_{n+2}) < d(x_n, x_{n+1})$ ;

Case 3. Suppose that (3.7) holds for  $x_n$  and  $x_{n+1}$ . Using (3.7) and (3.9), we have

$$\begin{aligned} & \max\{d^2(x_n, x_{n+1}), d^2(x_{n+1}, x_{n+2})\} \\ &= \max\{d^2(x_n, x_{n+1}), d^2(x_{n+1}, Tx_{n+1}), d(x_n, x_{n+1})d(x_n, Tx_n)\} \\ &> a \min\{d^2(x_n, Tx_n), d(x_n, x_{n+1})d(x_{n+1}, Tx_{n+1}), \\ &\quad d(x_{n+1}, Tx_n)d(x_n, Tx_{n+1})\} + H_-^2(Tx_n, Tx_{n+1}) \\ &\geq a \min\{d^2(x_n, x_{n+1}), d(x_n, x_{n+1})d(x_{n+1}, x_{n+2}), 0\} + d^2(x_{n+1}, x_{n+2}) \\ &= d^2(x_{n+1}, x_{n+2}), \end{aligned}$$

which implies that  $d(x_{n+1}, x_{n+2}) < d(x_n, x_{n+1})$ ;

Case 4. Suppose that (3.8) holds for  $x_n$  and  $x_{n+1}$ . It follows from (3.8) and (3.9) that

$$\begin{aligned} & H_-(Tx_n, Tx_{n+1}) \\ &< \max\left\{d(x_n, x_{n+1}), d(x_n, Tx_n), d(x_{n+1}, Tx_{n+1}), \right. \\ &\quad \left. \frac{1}{2}[d(x_n, Tx_{n+1}) + d(x_{n+1}, Tx_n)], \frac{[1 + d(x_{n+1}, Tx_{n+1})]d(x_{n+1}, Tx_n)}{1 + d(x_n, Tx_n)}\right\} \\ &= \max\left\{d(x_n, x_{n+1}), d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2}), \frac{1}{2}[d(x_n, x_{n+2}) + 0], 0\right\} \\ &= \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\}, \end{aligned}$$

which implies that

$$\begin{aligned} d(x_{n+1}, x_{n+2}) &= d(x_{n+1}, Tx_{n+1}) \leq H_-(Tx_n, Tx_{n+1}) \\ &< \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_{n+2})\}, \end{aligned}$$

that is,  $d(x_{n+1}, x_{n+2}) < d(x_n, x_{n+1})$ .

Hence (3.10) holds for  $n \geq 0$ . It follows that  $\{d(x_n, x_{n+1})\}_{n \geq 0}$  is a strictly decreasing sequence and it converges to some  $r \geq 0$ . Since  $\{x_n\}_{n \geq 0}$  has a cluster point  $z$ , there exists a subsequence  $\{x_{n_i}\}_{i \geq 1}$  of  $\{x_n\}_{n \geq 0}$  such that  $\lim_{i \rightarrow \infty} x_{n_i} = z$ . It follows from Lemma 2.3 that

$$\begin{aligned} |d(x_{n_i}, Tx_{n_i}) - d(x_{n_i}, Tz)| &\leq H(Tx_{n_i}, Tz) \rightarrow 0 \quad \text{as } i \rightarrow \infty, \\ |d(x_{n_i}, Tz) - d(z, Tz)| &\leq d(x_{n_i}, z) \rightarrow 0 \quad \text{as } i \rightarrow \infty, \end{aligned}$$

which imply that

$$d(x_{n_i}, x_{n_i+1}) = d(x_{n_i}, Tx_{n_i}) \rightarrow d(z, Fz) = r \quad \text{as } i \rightarrow \infty. \quad (3.13)$$

Notice that the continuity of  $T$  guarantees that

$$d(x_{n_i+1}, Tz) \leq H_-(Tx_{n_i}, Tz) \leq H(Tx_{n_i}, Tz) \rightarrow 0 \quad \text{as } i \rightarrow \infty. \quad (3.14)$$

From  $Tz \in C(X)$ , we can select a sequence  $\{z_{n_i}\}_{i \geq 1} \subset Tz$  such that  $d(x_{n_i+1}, z_{n_i}) = d(x_{n_i+1}, Tz)$  for each  $i \geq 1$ . The compactness of  $Tz$  ensures that there exists a subsequence  $\{z_{n_{i_k}}\}_{k \geq 1}$  of  $\{z_{n_i}\}_{i \geq 1}$  with  $\lim_{k \rightarrow \infty} z_{n_{i_k}} = z_1 \in Tz$ . It is to easy see that

$$d(x_{n_{i_k}+1}, z_1) \leq d(x_{n_{i_k}+1}, z_{n_{i_k}}) + d(z_{n_{i_k}}, z_1) \rightarrow 0 \quad \text{as } k \rightarrow \infty. \quad (3.15)$$

From Lemma 2.3, we conclude that

$$\begin{aligned} |d(x_{n_{i_k}+1}, Tx_{n_{i_k}+1}) - d(x_{n_{i_k}+1}, Tz_1)| &\leq H(Tx_{n_{i_k}+1}, Tz_1) \rightarrow 0 \quad \text{as } k \rightarrow \infty, \\ |d(x_{n_{i_k}+1}, Tz_1) - d(z_1, Tz_1)| &\leq d(x_{n_{i_k}+1}, z_1) \rightarrow 0 \quad \text{as } k \rightarrow \infty, \end{aligned}$$

which imply that

$$d(x_{n_{i_k}+1}, x_{n_{i_k}+2}) = d(x_{n_{i_k}+1}, Tx_{i_k+1}) \rightarrow d(z_1, Tz_1) = r \quad \text{as } k \rightarrow \infty. \quad (3.16)$$

In light of (3.11) and (3.13) we derive that

$$d(x_{n_{i_k}}, z_1) \leq d(x_{n_{i_k}}, x_{n_{i_k}+1}) + d(x_{n_{i_k}+1}, z_1) \rightarrow r \quad \text{as } k \rightarrow \infty,$$

that is,  $d(z, z_1) = r$ . It follows from (3.13)-(3.16) that

$$r = d(z, z_1) = d(z_1, Tz_1) = d(z, Tz). \quad (3.17)$$

Next we show that  $z = z_1$ . Suppose that  $z \neq z_1$ . We have to consider the following cases:

Case 1. Suppose that (3.5) holds for  $z$  and  $z_1$ . It follows from (3.5) and (3.17) that

$$\begin{aligned} r &= \max \left\{ d(z, z_1), d(z, Tz), \frac{d(z_1, Tz)d(z, Tz_1)}{d(z, z_1)}, \frac{d(z_1, Tz)d(z, Tz)}{d(z, z_1)} \right\} \\ &> a \min \left\{ d(z, Tz), d(z_1, Tz_1), \frac{d^2(z, Tz)}{d(z, z_1)}, \frac{d(z, Tz)d(z_1, Tz_1)}{d(z, z_1)} \right\} \\ &\quad + bH_-(Tz, Tz_1) \geq a \min\{r, r, r, r\} + br = r, \end{aligned}$$

which is a contradiction;

Case 2. Suppose that (3.6) holds for  $z$  and  $z_1$ . From (3.6) and (3.17) we infer immediately that

$$\begin{aligned} r^2 &= \max\{d^2(z, z_1), d(z_1, Tz)d(z, Tz_1), d(z_1, Tz)d(z, Tz), d(z, z_1)d(z, Tz)\} \\ &> a \min\{d^2(z, Tz), d^2(z_1, Tz_1), d(z, Tz)H_-(Tz, Tz_1), \\ &\quad d(z_1, Tz_1)H_-(Tz, Tz_1)\} + bH_-^2(Tz, Tz_1) \\ &\geq a \min\{r^2, r^2, rd(z_1, Tz_1), rd(z_1, Tz_1)\} + bd^2(z_1, Tz_1) = r^2, \end{aligned}$$

which is impossible;

Case 3. Suppose that (3.7) holds for  $z$  and  $z_1$ . By virtue of (3.7) and (3.17) we obtain easily that

$$\begin{aligned} r^2 &= \max\{d^2(z, z_1), d^2(z_1, Tz_1), d(z, z_1)d(z, Tz)\} \\ &> a \min\{d^2(z, Tz), d(z, z_1)d(z_1, Tz_1), d(z_1, Tz)d(z, Tz_1)\} + H_-^2(Tz, Tz_1) \\ &\geq a \min\{r^2, r^2, 0\} + r^2 = r^2, \end{aligned}$$

which is a contradiction;

Case 4. Suppose that (3.8) holds for  $z$  and  $z_1$ . In view of (3.8) and (3.17) we get that

$$\begin{aligned} r &= d(z_1, Tz_1) \leq H_-(Tz, Tz_1) \\ &< \max\left\{d(z, z_1), d(z, Tz), d(z_1, Tz_1), \frac{1}{2}[d(z, Tz_1) + d(z_1, Tz)], \right. \\ &\quad \left. \frac{[1 + d(z_1, Tz_1)]d(z_1, Tz)}{1 + d(z, Tz)}\right\} \leq \max\{r, r, r, r, 0\} = r, \end{aligned}$$

which is impossible.

Hence  $z = z_1$  and  $z \in Fz$  by (3.17). This completes the proof.  $\square$

**Theorem 3.3.** *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow C(X)$  be a continuous multi-valued mapping such that for any different  $x, y \in X$ , one of the following conditions is satisfied:*

$$d(x, y) > a \min\{d(x, Tx), d(y, Ty)\} + bH_-(Tx, Ty), \quad (3.18)$$

where  $a, b$  are nonnegative constants with  $a + b = 1$ ;

$$d(x, y) > a[d(x, Tx) + d(y, Ty)] + bH_-(Tx, Ty), \quad (3.19)$$

where  $a, b$  are nonnegative constants with  $2a + b = 1$ . Assume that there exists a sequence  $\{x_n\}_{n \geq 0} \subset X$  such that (3.9) holds and the sequence has a cluster point  $z$  in  $X$ . Then  $z$  is a fixed point of  $T$ .

*Proof.* Note that (3.19) implies that (3.18), which, in turn, implies (3.5). Thus Theorem 3.3 follows from Theorem 3.2. This completes the proof.  $\square$

#### 4. Fixed Point Stability

In this section, we shall study the stability of fixed points for the multi-valued contractive type mapping (3.1) in a complete metric space.

**Lemma 4.1.** *Let  $(X, d)$  be a complete metric space. Suppose that  $T_1$  and  $T_2 : X \rightarrow CL(X)$  satisfy (3.1) with a common constant  $\alpha \in [0, 1)$ . Then*

$$H_-(F(T_1), F(T_2)) \leq \frac{1}{1 - \alpha} \sup_{x \in X} H_-(T_1x, T_2x).$$

*Proof.* Put  $K = \sup_{x \in X} H_-(T_1x, T_2x)$ . Without loss of generality we may assume that  $K < +\infty$ . It follows from Theorem 3.1 that  $F(T_1) \neq \emptyset$ . Let  $\varepsilon > 0$  be arbitrary and  $x_0 \in F(T_1)$ . Lemma 2.2 ensures that there exists a point  $x_1 \in T_2x_0$  with  $d(x_0, x_1) < H_-(T_1x_0, T_2x_0) + \varepsilon \leq K + \varepsilon$ . Similarly, there exists  $x_2 \in T_2x_1$  with  $d(x_1, x_2) \leq H_-(T_2x_0, T_2x_1) + \alpha(1 - \alpha)\varepsilon$ . As in the proof of Theorem 3.1, we conclude that there exists a sequence  $\{x_n\}_{n \geq 0} \subset X$  with  $x_n \in T_2x_{n-1}$  and  $d(x_n, x_{n+1}) \leq \alpha^n d(x_0, x_1) + n\alpha^n \varepsilon, n \geq 0$ . Furthermore, we derive that

$$\sum_{n=m}^{p-1} d(x_n, x_{n+1}) \leq \frac{\alpha^m}{1 - \alpha} d(x_0, x_1) + \varepsilon \sum_{n=m}^{p-1} n\alpha^n, \quad \forall m \geq 1, p \geq 1,$$

which implies that  $\{x_n\}_{n \geq 0}$  is a Cauchy sequence with  $\lim_{n \rightarrow \infty} x_n = \bar{x} \in X$  by completeness of  $X$ . By Lemmas 2.1 and 2.3, we obtain that

$$\begin{aligned} d(\bar{x}, T_2\bar{x}) &\leq d(\bar{x}, x_n) + d(x_n, T_2x_n) + H_-(T_2x_n, T_2\bar{x}) \\ &\leq d(\bar{x}, x_n) + d(x_n, x_{n+1}) + \alpha \max\{d(x_n, \bar{x}), d(x_n, T_2x_n)\}, \\ d(\bar{x}, T_2\bar{x}), \frac{1}{2}[d(x_n, T_2\bar{x}) + d(\bar{x}, T_2x_n)], &\frac{[1 + d(\bar{x}, T_2\bar{x})]d(\bar{x}, T_2x_n)}{1 + d(x_n, T_2x_n)} \} \\ &\leq d(\bar{x}, x_n) + d(x_n, x_{n+1}) + \alpha \max\{d(x_n, \bar{x}), d(x_n, x_{n+1})\}, \\ d(\bar{x}, T_2\bar{x}), \frac{1}{2}[d(x_n, \bar{x}) + d(\bar{x}, T_2x_n) + d(\bar{x}, x_{n+1})], & \\ [1 + d(\bar{x}, T_2\bar{x})]d(\bar{x}, T_2x_n) \} &\rightarrow \alpha d(\bar{x}, T_2\bar{x}) \quad \text{as } n \rightarrow \infty, \end{aligned}$$

which implies that  $\bar{x} \in T_2\bar{x}$  by  $\alpha \in [0, 1)$ . It follows that

$$\begin{aligned}
d(x_0, \bar{x}) &\leq \sum_{n=0}^{\infty} d(x_n, x_{n+1}) \leq \frac{d(x_0, x_1)}{1-\alpha} + \varepsilon \sum_{n=0}^{\infty} n\alpha^n \\
&= \frac{d(x_0, x_1)}{1-\alpha} + \frac{\varepsilon\alpha^2}{1-\alpha} \leq \frac{d(x_0, x_1) + \varepsilon}{1-\alpha} \leq \frac{K + 2\varepsilon}{1-\alpha}. \quad (4.1)
\end{aligned}$$

Letting  $\varepsilon \rightarrow 0^+$  in (4.1), we have

$$d(x_0, F(T_2)) \leq d(x_0, \bar{x}) \leq \frac{K}{1-\alpha},$$

which implies that

$$H_-(F(T_1), F(T_2)) \leq \frac{1}{1-\alpha} \sup_{x \in X} H_-(T_1, T_2)$$

by the arbitrariness of  $x_0$ . This completes the proof.  $\square$

**Theorem 4.1.** *Let  $(X, d)$  be a complete metric space and  $\{T_i\}_{i \geq 0}$  be a sequence of multi-valued contractive type mappings from  $X$  into  $CL(X)$  satisfying (3.1) with a common constant  $\alpha \in [0, 1)$  for each  $i \geq 0$ . If  $\lim_{i \rightarrow \infty} H_-(T_i x, T_0 x) = 0$  uniformly for all  $x \in X$ , then*

$$\lim_{i \rightarrow \infty} H_-(F(T_i), F(T_0)) = 0.$$

*Proof.* For  $\varepsilon > 0$ , choose  $N$  such that

$$\sup_{x \in X} H_-(T_i x, T_0 x) < (1-\alpha)\varepsilon, \quad \forall i \geq N,$$

which implies that

$$H_-(F(T_i), F(T_0)) < \varepsilon, \quad \forall i \geq N$$

by Theorem 4.1. This completes the proof.  $\square$

**Remark 4.1.** Theorem 3.2 of Wang [11] is a special case of Theorem 4.2.

### Acknowledgments

This research was financially supported by the Science Research Foundation of Educational Department of Liaoning Province (2006).

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