

MINIMAL LIGHTLIKE MONGE HYPERSURFACES IN  
SEMI-EUCLIDEAN SPACES

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**Abstract:** We give the condition for a lightlike Monge hypersurface in the semi-Euclidean space to be minimal. Using the condition we discuss some examples of minimal lightlike Monge hypersurfaces in semi-Euclidean spaces.

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**Key Words:** lightlike hypersurface, Monge hypersurface, minimal, semi-Euclidean space

### 1. Introduction

A submanifold  $M$  in a semi-Riemannian manifold  $(\bar{M}, \bar{g})$  is called lightlike if the induced metric  $g = \bar{g}|_M$  is degenerate (cf. [3]). The study of lightlike submanifolds is much different from that of semi-Riemannian submanifolds. For a lightlike submanifold  $M$ , the tangent bundle  $TM$  and the normal bundle  $TM^\perp$  have a non-trivial intersection, which is called the radical distribution and denoted by  $\text{Rad}(TM)$ . Then we may choose a (non-unique) semi-Riemannian complementary distribution of  $\text{Rad}(TM)$  in  $TM$ , which is called the screen distribution and denoted by  $S(TM)$ .

In the case where  $M$  is a lightlike hypersurface, the normal bundle  $TM^\perp$  coincides with the radical distribution  $\text{Rad}(TM)$ , and there exists a canonical transversal vector bundle  $\text{tr}(TM)$  corresponding to the screen distribution  $S(TM)$ , which is called the lightlike transversal vector bundle.

In [3, Section 4.7] Duggal and Bejancu introduced the notion of minimal lightlike hypersurfaces in the 4-dimensional Minkowski space  $R_1^4$ . In [2] Burdujan defined minimal lightlike hypersurfaces in Lorentzian manifolds, and showed that a minimal lightlike Monge hypersurface in the Minkowski space is a part of a lightlike hyperplane. Recently, Bejan and Duggal [1] defined minimal lightlike submanifolds in semi-Riemannian manifolds.

In a previous paper [5], we give the necessary and sufficient condition for a lightlike hypersurface with integrable screen distribution in the 4-dimensional semi-Euclidean space  $R_2^4$  of index 2 to be minimal. Using the condition, we obtain a class of minimal lightlike hypersurfaces in  $R_2^4$  which are not totally geodesic. On the other hand, in [4], we show that a lightlike hypersurface with integrable screen distribution in a Lorentzian space form is minimal if and only if it is totally geodesic. As a corollary, we find that a lightlike hypersurface in the Minkowski space is minimal if and only if it is totally geodesic.

In this paper, we will give the condition for a lightlike Monge hypersurface in the semi-Euclidean space to be minimal, which is a generalization of [3, Chapter 4, Theorem 7.1] and [2].

Let  $R_q^{m+2}$  be the  $(m+2)$ -dimensional semi-Euclidean space of index  $q$  ( $1 \leq q \leq m+1$ ) with standard coordinate system  $x = (x_0, x_1, \dots, x_{m+1})$  and semi-Euclidean metric

$$\bar{g}(x, y) = - \sum_{i=0}^{q-1} x_i y_i + \sum_{j=q}^{m+1} x_j y_j.$$

Let  $M$  be a Monge hypersurface in  $R_q^{m+2}$  defined by

$$x_0 = F(x_1, \dots, x_{m+1}), \quad (x_1, \dots, x_{m+1}) \in D \subset R_{q-1}^{m+1}, \quad (1)$$

where  $F : D \rightarrow R$  is a smooth function. It is known that  $M$  is lightlike if and only if

$$1 + \sum_{i=1}^{q-1} F_{x_i}^2 = \sum_{j=q}^{m+1} F_{x_j}^2 \quad (2)$$

(cf. [3, Chapter 4, Theorem 6.3]). Set  $\varepsilon_i = -1$  if  $1 \leq i \leq q-1$ , and  $\varepsilon_i = 1$  if  $q \leq i \leq m+1$ . The Laplacian  $\Delta$  on  $R_{q-1}^{m+1}$  is defined by

$$\Delta = \sum_{i=1}^{m+1} \varepsilon_i \frac{\partial^2}{\partial x_i^2}.$$

Now we state the result as follows:

**Theorem.** *A lightlike Monge hypersurface  $M$  in  $R_q^{m+2}$  given by (1) with*

(2) is minimal if and only if  $F$  is a harmonic function on  $D \subset R_{q-1}^{m+1}$ , that is,  $\Delta F = 0$ .

Using the theorem we discuss some examples of minimal lightlike Monge hypersurfaces in semi-Euclidean spaces.

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### 2. Preliminaries

In this section, following [3, Chapter 4] and [1], we recall some basic facts on lightlike hypersurfaces.

Let  $\bar{M}$  be a semi-Riemannian manifold with metric  $\bar{g}$  and Levi-Civita connection  $\bar{\nabla}$ . Let  $M$  be a lightlike hypersurface in  $\bar{M}$ , so that the induced metric  $g = \bar{g}|_M$  is degenerate. Then the normal bundle  $TM^\perp$  coincides with the radical distribution  $\text{Rad}(TM)$ , defined by

$$\text{Rad}(T_x M) = \{ \xi \in T_x M \mid g(\xi, X) = 0, \quad X \in T_x M \},$$

where  $\dim(\text{Rad}(T_x M)) = 1$ . We may choose a (non-unique) semi-Riemannian complementary distribution of  $\text{Rad}(TM)$  in  $TM$ , which is called the screen distribution and denoted by  $S(TM)$ . So we have

$$TM = S(TM) \perp \text{Rad}(TM) = S(TM) \perp TM^\perp.$$

By [3, Chapter 4, Theorem 1.1], for a screen distribution  $S(TM)$ , there exists a unique vector bundle  $\text{tr}(TM)$  of rank 1 such that, for any non-zero local section  $\xi$  of  $TM^\perp$  on  $U$  there is a unique section  $N$  of  $\text{tr}(TM)|_U$  satisfying

$$\bar{g}(\xi, N) = 1, \quad \bar{g}(N, N) = \bar{g}(N, W) = 0$$

for any  $W \in \Gamma(S(TM)|_U)$ . This vector bundle  $\text{tr}(TM)$  is called the lightlike transversal vector bundle with respect to  $S(TM)$ . Then we have the following decomposition

$$T\bar{M}|_M = TM \oplus \text{tr}(TM).$$

We choose a non-zero local section  $\xi$  of  $\text{Rad}(TM)$ . From the above decomposition, we have the Gauss formula

$$\bar{\nabla}_X Y = \nabla_X Y + h(X, Y),$$

where  $X, Y \in \Gamma(TM)$ . Then  $\nabla$  is a torsion-free linear connection on  $M$ , and  $h$  is a symmetric  $C^\infty(M)$ -bilinear form on  $\Gamma(TM)$  with values in  $\Gamma(\text{tr}(TM))$ . The form  $h$  is called the second fundamental form of  $M$ . Locally on  $U$ , we may

write

$$h(X, Y) = B(X, Y)N.$$

The form  $B$  is called the local second fundamental form of  $M$ , which is independent of the choice of  $S(TM)$ . When  $B = 0$ ,  $M$  is called totally geodesic.

By Definition 2 of [1] in the case of lightlike hypersurfaces, we say that  $M$  is minimal if  $\text{trace}(B) = 0$ , where the trace is written with respect to  $g$  restricted to  $S(TM)$ . Noting that  $B(\xi, X) = 0$  for any  $X \in \Gamma(TM|_U)$  (cf. [3, Chapter 4, Corollary 2.1]), we can see that the above minimality condition is independent of the choice of  $S(TM)$  and  $\xi$ .

### 3. Proof of Theorem and Examples

First, following [3, Section 4.6], we recall some basic facts on lightlike Monge hypersurfaces in semi-Euclidean spaces.

Let  $M$  be a Monge hypersurface in  $R_q^{m+2}$  given by (1). We consider the parametrization of  $M$  by

$$p = (F(u_1, \dots, u_{m+1}), u_1, \dots, u_{m+1}),$$

and the frame field on  $M$  by

$$p_{u_i} = F_{u_i} \frac{\partial}{\partial x_0} + \frac{\partial}{\partial x_i}, \quad 1 \leq i \leq m + 1.$$

Then

$$\xi = \frac{\partial}{\partial x_0} - \sum_{i=1}^{q-1} F_{u_i} \frac{\partial}{\partial x_i} + \sum_{j=q}^{m+1} F_{u_j} \frac{\partial}{\partial x_j}$$

spans  $TM^\perp$ . So we can see that  $M$  is lightlike if and only if

$$1 + \sum_{i=1}^{q-1} F_{u_i}^2 = \sum_{j=q}^{m+1} F_{u_j}^2.$$

If  $F_{u_{m+1}} \neq 0$ , the natural lightlike transversal vector bundle  $\text{tr}^*(TM)$  and the natural screen distribution  $S^*(TM)$  are spanned by

$$N = -\frac{\partial}{\partial x_0} + \frac{1}{2}\xi = \frac{1}{2} \left( -\frac{\partial}{\partial x_0} - \sum_{i=1}^{q-1} F_{u_i} \frac{\partial}{\partial x_i} + \sum_{j=q}^{m+1} F_{u_j} \frac{\partial}{\partial x_j} \right),$$

and

$$W_i = F_{u_{m+1}} \frac{\partial}{\partial x_i} - F_{u_i} \frac{\partial}{\partial x_{m+1}} = F_{u_{m+1}} p_{u_i} - F_{u_i} p_{u_{m+1}}$$

$$= p_* \left( F_{u_{m+1}} \frac{\partial}{\partial u_i} - F_{u_i} \frac{\partial}{\partial u_{m+1}} \right), \quad 1 \leq i \leq m,$$

respectively.

*Proof of Theorem.* We may assume that  $F_{u_{m+1}} \neq 0$ . Restricted to the natural screen distribution  $S^*(TM)$ , we have

$$\hat{g}_{ij} := \bar{g}(W_i, W_j) = F_{u_{m+1}}^2 \varepsilon_i \delta_{ij} + F_{u_i} F_{u_j}, \quad 1 \leq i, j \leq m.$$

Noting that

$$\sum_{j=1}^m \varepsilon_j F_{u_j}^2 = 1 - F_{u_{m+1}}^2,$$

we find that

$$\hat{g}^{jk} = \frac{1}{F_{u_{m+1}}^2} \varepsilon_j (\delta_{jk} - \varepsilon_k F_{u_j} F_{u_k}), \quad 1 \leq j, k \leq m$$

are the components of the inverse matrix of  $(\hat{g}_{ij})_{1 \leq i, j \leq m}$ .

With respect to the local second fundamental form  $B$  of  $M$ , we have on  $S^*(TM)$ ,

$$\begin{aligned} \hat{B}_{ij} &:= B(W_i, W_j) = \bar{g}(\bar{\nabla}_{W_i} W_j, \xi) \\ &= -F_{u_{m+1}}^2 F_{u_i u_j} + F_{u_j} F_{u_{m+1}} F_{u_i u_{m+1}} + F_{u_i} F_{u_{m+1}} F_{u_j u_{m+1}} - F_{u_i} F_{u_j} F_{u_{m+1} u_{m+1}}, \end{aligned}$$

where  $1 \leq i, j \leq m$  and  $\bar{\nabla}$  is the flat connection on  $R_q^{m+2}$ .

By the definition,  $M$  is minimal if and only if

$$\sum_{i,j=1}^m \hat{B}_{ij} \hat{g}^{ji} = 0.$$

We may compute that

$$\begin{aligned} F_{u_{m+1}}^2 \sum_{i,j=1}^m \hat{B}_{ij} \hat{g}^{ji} &= -F_{u_{m+1}}^2 \sum_{i=1}^m \varepsilon_i F_{u_i u_i} + F_{u_{m+1}}^2 \sum_{i,j=1}^m \varepsilon_i \varepsilon_j F_{u_i} F_{u_j} F_{u_i u_j} \\ &+ 2F_{u_{m+1}} \sum_{i=1}^m \varepsilon_i F_{u_i} F_{u_i u_{m+1}} - 2F_{u_{m+1}} \sum_{i=1}^m \varepsilon_i F_{u_i} F_{u_i u_{m+1}} \sum_{j=1}^m \varepsilon_j F_{u_j}^2 \\ &- F_{u_{m+1} u_{m+1}} \sum_{i=1}^m \varepsilon_i F_{u_i}^2 + F_{u_{m+1} u_{m+1}} \sum_{i=1}^m \varepsilon_i F_{u_i}^2 \sum_{j=1}^m \varepsilon_j F_{u_j}^2. \end{aligned}$$

Noting that

$$\sum_{i=1}^m \varepsilon_i F_{u_i u_i} = \Delta F - F_{u_{m+1} u_{m+1}}, \quad \sum_{i=1}^m \varepsilon_i F_{u_i}^2 = 1 - F_{u_{m+1}}^2,$$

and

$$\sum_{i=1}^m \varepsilon_i F_{u_i} F_{u_i u_a} = -F_{u_{m+1}} F_{u_{m+1} u_a}, \quad 1 \leq a \leq m + 1,$$

we have

$$\begin{aligned} F_{u_{m+1}}^2 \sum_{i,j=1}^m \hat{B}_{ij} \hat{g}^{ji} &= -F_{u_{m+1}}^2 (\Delta F - F_{u_{m+1} u_{m+1}}) + F_{u_{m+1}}^4 F_{u_{m+1} u_{m+1}} \\ &\quad - 2F_{u_{m+1}}^2 F_{u_{m+1} u_{m+1}} + 2F_{u_{m+1}}^2 (1 - F_{u_{m+1}}^2) F_{u_{m+1} u_{m+1}} \\ &\quad - (1 - F_{u_{m+1}}^2) F_{u_{m+1} u_{m+1}} + (1 - F_{u_{m+1}}^2)^2 F_{u_{m+1} u_{m+1}} \\ &= -F_{u_{m+1}}^2 \Delta F. \end{aligned}$$

From this equation, we find that  $M$  is minimal if and only if  $F$  is a harmonic function on  $D \subset R_{q-1}^{m+1}$ . Thus we get the conclusion.  $\square$

Using the theorem, let us consider some examples. When the ambient space is the Minkowski space  $R_1^{m+2}$ , we have the following corollary.

**Corollary.** (cf. [2]) *A lightlike Monge hypersurface  $M$  in  $R_1^{m+2}$  given by (1) with (2) is minimal if and only if  $F$  is a linear function.*

It was shown by Burdujan [2] using spherical harmonics. Here we give a simpler proof.

*Proof of Corollary.* By the theorem,  $M$  is minimal if and only if  $\Delta F = 0$  and  $\|\text{grad}(F)\|^2 = 1$  on  $D \subset R_0^{m+1} = R^{m+1}$ . Noting the formula

$$\frac{1}{2} \Delta \|\text{grad}(F)\|^2 = \|\text{Hess}(F)\|^2 + \bar{g}(\text{grad}(F), \text{grad}(\Delta F)),$$

we can see that  $M$  is minimal if and only if  $F$  is a linear function.  $\square$

**Remark.** The corollary is also a spacial case of the result in [4].

**Example 1.** Let  $Q_1(t), \dots, Q_r(t)$  be smooth functions, and set

$$F(x_1, \dots, x_{2r+1}) = \sum_{i=1}^r Q_i(x_i + x_{r+i}) + x_{2r+1}.$$

Then  $F$  satisfies

$$1 + \sum_{i=1}^r F_{x_i}^2 = \sum_{j=r+1}^{2r+1} F_{x_j}^2, \quad \sum_{i=1}^r F_{x_i x_i} = \sum_{j=r+1}^{2r+1} F_{x_j x_j}.$$

By the theorem, the Monge hypersurface  $M$  in  $R_{r+1}^{2r+2}$  given by

$$x_0 = \sum_{i=1}^r Q_i(x_i + x_{r+i}) + x_{2r+1}$$

is lightlike and minimal. By the computation in the proof of the theorem, we

have

$$\hat{B}_{ii} = -Q_i''(x_i + x_{r+i}), \quad 1 \leq i \leq r.$$

So, choosing  $Q_i(t)$  nonlinear, we get minimal lightlike Monge hypersurfaces which are not totally geodesic.

**Example 2.** Let  $M$  be a Monge hypersurface in  $R_2^4$  given by

$$x_0 = F(x_1, x_2, x_3),$$

where  $F(x_1, x_2, x_3)$  is a quadratic function on  $R_1^3$ . Then the lightlike and minimal conditions are

$$1 + F_{x_1}^2 = F_{x_2}^2 + F_{x_3}^2, \quad F_{x_1x_1} = F_{x_2x_2} + F_{x_3x_3}.$$

By the second condition and a suitable choice of the coordinate system, we may assume that

$$F(x_1, x_2, x_3) = \frac{1}{2}(a_1 + a_2)x_1^2 + \frac{1}{2}a_1x_2^2 + \frac{1}{2}a_2x_3^2 \\ + a_3x_1x_2 + a_4x_1x_3 + a_5x_1 + a_6x_2 + a_7x_3,$$

and  $a_1 > 0$ ,  $a_3 \geq 0$ ,  $a_7 \geq 0$ . By the first condition, we can get

$$a_2 = a_4 = 0, \quad a_3 = a_1, \quad a_5 = a_6, \quad a_7 = 1.$$

Thus we have

$$F(x_1, x_2, x_3) = \frac{1}{2}a_1(x_1 + x_2)^2 + a_5(x_1 + x_2) + x_3,$$

which is a spacial case of Example 1.

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