

**$\psi - \phi$ CONTRACTION ON SUZUKI TYPE UNIQUE
COMMON COUPLED FIXED POINT THEOREM IN
PARTIALLY ORDERED MULTIPLICATIVE METRIC SPACES**

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Abstract: In this paper, we obtain a Suzuki type unique common coupled fixed point theorem by using $\psi - \phi$ contraction in partially ordered multiplicative metric spaces. We also give an example to illustrate our main theorem.

AMS Subject Classification: 54H25, 47H10, 54E50

Key Words: multiplicative metric space, w -compatible maps, Suzuki type contraction

1. Introduction

The notion of multiplicative metric was introduced by Bashirov et al. [3] in 2008. After that Ozavsar and Cevikel[8] investigated its topological properties and proved some fixed point theorems. For more works on fixed, common fixed

Received: May 10, 2016

Revised: July 22, 2016

Published: September 30, 2016

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point theorems in Multiplicative metric spaces, we refer [5, 2, 6, 9].

The Coupled fixed point is introduced by Bhaskar and Lakshmikantham [4]. Later some of authors proved coupled fixed and coupled common fixed point theorems (See [1, 7, 10, 11, 12]).

The aim of this paper is to prove Suzuki type unique common coupled fixed point theorem for Jungck type maps by using $\psi - \phi$ contraction condition in partially ordered multiplicative metric spaces.

First we give the following theorem of Suzuki [13].

Theorem 1.1. (See [13]): Let (X, d) be a complete metric space and let T be a mapping on X . Define a non-increasing function $\theta : [0, 1) \rightarrow (\frac{1}{2}, 1]$ by

$$\theta(r) = \begin{cases} 1 & \text{if } 0 \leq r \leq \frac{(\sqrt{5}-1)}{2}, \\ (1-r)r^{-2} & \text{if } \frac{(\sqrt{5}-1)}{2} \leq r \leq 2^{-\frac{1}{2}}, \\ (1+r)^{-1} & \text{if } 2^{-\frac{1}{2}} \leq r < 1. \end{cases}$$

Assume that there exists $r \in [0, 1)$ such that

$$\theta(r)d(x, Tx) \leq d(x, y) \Rightarrow d(Tx, Ty) \leq rd(x, y)$$

for all $x, y \in X$. Then there exists a unique fixed point z of T . Moreover $\lim_{n \rightarrow \infty} T^n x = z$ for all $x \in X$.

Now we recall some basic definitions and examples in multiplicative metric spaces.

Definition 1.2. (See[3]) Multiplicative metric on a nonempty set X is a mapping $d : X \times X \rightarrow R^+$ satisfying the following conditions:

$$(d_1) \quad d(x, y) \geq 1 \text{ for all } x, y \in X$$

$$(d_2) \quad d(x, y) = 1 \text{ if and only if } x = y,$$

$$(d_3) \quad d(x, y) = d(y, x),$$

$$(d_4) \quad d(x, y) \leq d(x, z).d(z, y) \text{ for all } x, y, z \in X.$$

The pair (X, d) is called a multiplicative metric space.

Example 1.3. (See[9]) Let R_+^n be the collection of all n - tuples of positive real numbers. And let $d^* : R_+^n \times R_+^n \rightarrow R$ be defined as

$$d^*(x, y) = \left| \frac{x_1}{y_1} \right|^* \cdot \left| \frac{x_2}{y_2} \right|^* \cdots \left| \frac{x_n}{y_n} \right|^*$$

where $x = (x_1, x_2 \cdots x_n), y = (y_1, y_2 \cdots y_n) \in R_+^n$ and $|\cdot|^* : R_+ \rightarrow R_+$ is defined as follows

$$|a|^* = \begin{cases} a & \text{if } a \geq 1 \\ \frac{1}{a} & \text{if } a < 1 \end{cases}$$

Then clearly $d^*(x, y)$ is a multiplicative metric.

Example 1.4. (See[9]) Let $d : R \times R \rightarrow [1, \infty)$ be defined as $d(x, y) = a^{|x-y|}$ where $x, y \in R$ and $a > 1$. Then $d(x, y)$ is multiplicative metric.

Definition 1.5. (See[8]) Let (X, d) be a multiplicative metric space, x_0 an arbitrary point in X , and $\epsilon > 1$. A multiplicative open ball $B(x_0, \epsilon)$ of radius ϵ centered at x_0 is the set $\{z \in X : d(z, x_0) < \epsilon\}$.

A sequence $\{x_n\}$ in a multiplicative metric space (X, d) is said to be multiplicative convergent to some point $x \in X$ if, for any given $\epsilon > 1$, then there exists $n_0 \in N$ such that $x_n \in B(x, \epsilon)$ for all $n \geq n_0$. If $\{x_n\}$ converges to x , we write $x_n \rightarrow x$ as $n \rightarrow \infty$.

Definition 1.6. (See[8]) A sequence $\{x_n\}$ in a multiplicative metric space (X, d) is said to be multiplicative convergent to x in X if and only if $d(x_n, x) \rightarrow 1$ as $n \rightarrow \infty$.

Definition 1.7. (See [8]) Let (X, d_X) and (Y, d_Y) be two multiplicative metric space and x_0 an arbitrary but fixed element of X . A mapping $f : X \rightarrow Y$ is said to be multiplicative continuous at x_0 if and only if $x_n \rightarrow x_0$ in (X, d_X) implies that $f(x_n) \rightarrow f(x_0)$ in (Y, d_Y) . That is, given arbitrary $\epsilon > 1$, then there exists $\delta > 1$ which depends on x_0 and ϵ such that $d_Y(fx, fx_0) < \epsilon$ for all those x in X for which $d_X(x, x_0) < \delta$.

Definition 1.8. (See[8]) A sequence $\{x_n\}$ in a multiplicative metric space (X, d) is said to be multiplicative Cauchy sequence if, for any $\epsilon > 1$, there exists $n_0 \in N$ such that $d(x_m, x_n) < \epsilon$ for all $m, n \geq n_0$.

Definition 1.9. (See[8]) A multiplicative metric space (X, d) is said to be complete if every multiplicative Cauchy sequence $\{x_n\}$ in X is multiplicative convergent in X .

Definition 1.10. (See [2]) Let Ψ be the set of all control functions $\varphi : [1, \infty) \rightarrow [1, \infty)$ such that

- (i) φ is continuous and non - decreasing.
- (ii) $\varphi(t) = 1$ if and only if $t = 1$.

Definition 1.11. [4] An element $(x, y) \in X \times X$ is called a coupled fixed point of mapping $F : X \times X \rightarrow X$ if $x = F(x, y)$ and $y = F(y, x)$.

Definition 1.12. [1] An element $(x, y) \in X \times X$ is called (g_1) a coupled coincident point of mappings $F : X \times X \rightarrow X$ and $f : X \rightarrow X$ if $fx = F(x, y)$ and $fy = F(y, x)$.

(g_2) a common coupled fixed point of mappings $F : X \times X \rightarrow X$ and $f : X \rightarrow X$ if $x = fx = F(x, y)$ and $y = fy = F(y, x)$.

Definition 1.13. [1] The mappings $F : X \times X \rightarrow X$ and $f : X \rightarrow X$ are called w - compatible if $f(F(x, y)) = F(fx, fy)$ and $f(F(y, x)) = F(fy, fx)$ whenever $fx = F(x, y)$ and $fy = F(y, x)$.

2. Main Result

Theorem 2.1. Let (X, d, \preceq) be partially ordered multiplicative metric space and let $T : X \times X \rightarrow X$ and $g : X \rightarrow X$ be mappings satisfying

$$(2.1.1) \quad \frac{1}{2} \min\{d(gx, T(x, y)), d(gu, T(u, v))\} \leq \max\{d(gx, gu), d(gy, gv)\}$$

implies that $\psi(d(T(x, y), T(u, v))) \leq \frac{\psi(M(x, y, u, v))}{\phi(M(x, y, u, v))}$, for all x, y, u, v in X , with $gx \preceq gu$ and $gy \succeq gv$ where $\psi, \phi \in \Psi$ and

$$M(x, y, u, v) = \max \left\{ \begin{array}{l} d(gx, gu), d(gy, gv), d(gx, T(x, y)), \\ d(gy, T(y, x)), d(gu, T(u, v)), d(gv, T(v, u)), \\ \sqrt{d(gx, T(u, v)) \cdot d(gu, T(x, y))}, \\ \sqrt{d(gy, T(v, u)) \cdot d(gv, T(y, x))} \end{array} \right\},$$

(2.1.2) $T(X \times X) \subseteq g(X)$ and $g(X)$ is a complete subspaces of X ,

(2.1.3) T has a mixed g - monotone property

(2.1.4) (a) If a non- decreasing sequence $\{x_n\} \rightarrow x$ then $x_n \preceq x$ for all n ,

(b) If a non- increasing sequence $\{y_n\} \rightarrow y$ then $y \preceq y_n$ for all n .

If there exist $x_0, y_0 \in X$ such that $gx_0 \preceq T(x_0, y_0)$ and $gy_0 \succeq T(y_0, x_0)$, then T and g have a coupled coincidence point in $X \times X$.

Proof. Let $x_0, y_0 \in X$ such that $gx_0 \preceq T(x_0, y_0)$ and $gy_0 \succeq T(y_0, x_0)$.

Since $T(X \times X) \subseteq g(X)$, we choose $x_1, y_1 \in X$ such that

$$gx_0 \preceq T(x_0, y_0) = gx_1$$

and

$$gy_0 \succeq T(y_0, x_0) = gy_1$$

and choose $x_2, y_2 \in X$ such that $gx_2 = T(x_1, y_1)$ and $gy_2 = T(y_1, x_1)$.

Since T has mixed g - monotone property, we obtain $gx_0 \preceq gx_1 \preceq gx_2$ and $gy_0 \succeq gy_1 \succeq gy_2$.

Continuing this process , we can construct the sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$gx_{n+1} = T(x_n, y_n) \quad \text{and} \quad gy_{n+1} = T(y_n, x_n), \quad n = 0, 1, 2, \dots$$

with

$$gx_0 \preceq gx_1 \preceq gx_2 \dots$$

and

$$gy_0 \succeq gy_1 \succeq gy_2 \dots$$

Case (a) : If $gx_m = gx_{m+1}$ and $gy_m = gy_{m+1}$ for some m .

Then (x_m, y_m) is coupled coincidence point in $X \times X$.

Case (b): Assume $gx_n \neq gx_{n+1}$ or $gy_n \neq gy_{n+1}$ for all n .

Since $gx_n \preceq gx_{n+1}$ and $gy_n \succeq gy_{n+1}$, clearly we have

$$\begin{aligned} \frac{1}{2}d(gx_n, T(x_n, y_n)) &\leq d(gx_n, gx_{n+1}) \\ &\leq \max \left\{ \begin{array}{l} d(gx_n, gx_{n+1}), \\ d(gy_n, gy_{n+1}) \end{array} \right\}. \end{aligned}$$

Thus

$$\frac{1}{2} \min \left\{ \begin{array}{l} d(gx_n, T(x_n, y_n)), \\ d(gx_{n+1}, T(x_{n+1}, y_{n+1})) \end{array} \right\} \leq \max \left\{ \begin{array}{l} d(gx_n, gx_{n+1}), \\ d(gy_n, gy_{n+1}) \end{array} \right\}.$$

From (2.1.1) , we get

$$\psi (d(T(x_n, y_n), T(x_{n+1}, y_{n+1}))) \leq \frac{\psi(M(x_n, y_n, x_{n+1}, y_{n+1}))}{\phi(M(x_n, y_n, x_{n+1}, y_{n+1}))},$$

where

$$\begin{aligned} &M(x_n, y_n, x_{n+1}, y_{n+1}) \\ &= \max \left\{ \begin{array}{l} d(gx_n, gx_{n+1}), d(gy_n, gy_{n+1}), \\ d(gx_n, T(x_n, y_n)), d(gy_n, T(y_n, x_n)), \\ d(gx_{n+1}, T(x_{n+1}, y_{n+1})), d(gy_{n+1}, T(y_{n+1}, x_{n+1})), \\ \sqrt{d(gx_n, T(x_{n+1}, y_{n+1})).d(gx_{n+1}, T(x_n, y_n))}, \\ \sqrt{d(gy_n, T(y_{n+1}, x_{n+1})).d(gy_{n+1}, T(y_n, x_n))} \end{array} \right\} \end{aligned}$$

$$\begin{aligned}
&= \max \left\{ \begin{array}{l} d(gx_n, gx_{n+1}), d(gy_n, gy_{n+1}), \\ d(gx_n, gx_{n+1}), d(gy_n, gy_{n+1}), \\ d(gx_{n+1}, gx_{n+2}), d(gy_{n+1}, gy_{n+2}), \\ \sqrt{d(gx_n, gx_{n+2}) \cdot d(gx_{n+1}, gx_{n+2})}, \\ \sqrt{d(gy_n, gy_{n+2}) \cdot d(gy_{n+1}, gy_{n+2})} \end{array} \right\} \\
&= \max \left\{ \begin{array}{l} d(gx_n, gx_{n+1}), d(gy_n, gy_{n+1}), \\ d(gx_{n+1}, gx_{n+2}), d(gy_{n+1}, gy_{n+2}), \\ \sqrt{d(gx_n, gx_{n+2})}, \sqrt{d(gy_n, gy_{n+2})} \end{array} \right\}.
\end{aligned}$$

But

$$\begin{aligned}
\sqrt{d(gx_n, gx_{n+2})} &\leq \sqrt{d(gx_n, gx_{n+1}) \cdot d(gx_{n+1}, gx_{n+2})} \\
&\leq \max \{d(gx_n, gx_{n+1}), d(gx_{n+1}, gx_{n+2})\}.
\end{aligned}$$

Similarly

$$\sqrt{d(gy_n, gy_{n+2})} \leq \max \{d(gy_n, gy_{n+1}), d(gy_{n+1}, gy_{n+2})\}.$$

Therefore

$$M(x_n, y_n, x_{n+1}, y_{n+1}) = \max \left\{ \begin{array}{l} d(gx_n, gx_{n+1}), d(gy_n, gy_{n+1}), \\ d(gx_{n+1}, gx_{n+2}), d(gy_{n+1}, gy_{n+2}) \end{array} \right\}.$$

Put $R_n = \max \{d(gx_n, gx_{n+1}), d(gy_n, gy_{n+1})\}$.

Hence

$$\psi(d(gx_{n+1}, gx_{n+2})) \leq \frac{\psi(\max\{R_n, R_{n+1}\})}{\phi(\max\{R_n, R_{n+1}\})}.$$

Similarly

$$\psi(d(gy_{n+1}, gy_{n+2})) \leq \frac{\psi(\max\{R_n, R_{n+1}\})}{\phi(\max\{R_n, R_{n+1}\})}.$$

Now

$$\begin{aligned}
\psi(R_{n+1}) &= \psi(\max\{d(gx_{n+1}, gx_{n+2}), d(gy_{n+1}, gy_{n+2})\}) \\
&= \max\{\psi(d(gx_{n+1}, gx_{n+2})), \psi(d(gy_{n+1}, gy_{n+2}))\} \\
&\leq \frac{\psi(\max\{R_n, R_{n+1}\})}{\phi(\max\{R_n, R_{n+1}\})}.
\end{aligned}$$

If R_{n+1} is maximum, we get

$$\psi(R_{n+1}) \leq \frac{\psi(R_{n+1})}{\phi(R_{n+1})} < \psi(R_{n+1})$$

which is a contradiction.

Hence R_n is a maximum

$$\begin{aligned} \psi(R_{n+1}) &\leq \frac{\psi(R_n)}{\phi(R_n)} \\ &< \psi(R_n). \end{aligned} \tag{1}$$

Since ψ is non - decreasing, we obtain

$$R_{n+1} \leq R_n.$$

Thus $\{R_n\}$ is non- increasing sequence of non- negative real number and must converges to a real number $r \geq 1$ (say).

Suppose $r > 1$.

Letting $n \rightarrow \infty$ in (1), we get

$$\psi(r) \leq \frac{\psi(r)}{\phi(r)} < \psi(r)$$

which is a contradiction.

Hence $r = 1$. Thus

$$\lim_{n \rightarrow \infty} \max\{d(gx_n, gx_{n+1}), d(gy_n, gy_{n+1})\} = 1$$

which implies that

$$\lim_{n \rightarrow \infty} d(gx_n, gx_{n+1}) = 1 = \lim_{n \rightarrow \infty} d(gy_n, gy_{n+1}). \tag{2}$$

Now we prove that $\{gx_n\}$ and $\{gy_n\}$ are multiplicative Cauchy sequences.

On contrary suppose that $\{gx_n\}$ or $\{gy_n\}$ are not multiplicative Cauchy sequences.

Then there exist an $\epsilon > 1$ and monotone increasing sequence of natural numbers $\{m_k\}$ and $\{n_k\}$ such that $n_k > m_k > k$,

$$\max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} \geq \epsilon \tag{3}$$

and

$$\max\{d(gx_{m_k}, gx_{n_{k-1}}), d(gy_{m_k}, gy_{n_{k-1}})\} < \epsilon. \tag{4}$$

From (3) and (4), we have

$$\begin{aligned} \epsilon &\leq \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} \\ &\leq \max\{d(gx_{m_k}, gx_{n_{k-1}}).d(gx_{n_{k-1}}, gx_{n_k}), d(gy_{m_k}, gy_{n_{k-1}}).d(gy_{n_{k-1}}, gy_{n_k})\}. \end{aligned}$$

Letting $k \rightarrow \infty$, we have

$$\epsilon \leq \lim_{k \rightarrow \infty} \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} \leq \epsilon.$$

Thus

$$\lim_{k \rightarrow \infty} \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} = \epsilon. \quad (5)$$

Form (3), we have

$$\begin{aligned} \epsilon &\leq \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} \\ &\leq \max\{d(gx_{m_k}, gx_{n_{k+1}}).d(gx_{n_{k+1}}, gx_{n_k}), d(gy_{m_k}, gy_{n_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k})\} \\ &\leq \max \left\{ \begin{array}{l} (d(gx_{m_k}, gx_{n_k}).d(gx_{n_k}, gx_{n_{k+1}}).d(gx_{n_{k+1}}, gx_{n_k})), \\ d(gy_{m_k}, gy_{n_k}).d(gy_{n_k}, gy_{n_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k}) \end{array} \right\}. \end{aligned}$$

Letting $k \rightarrow \infty$, we have

$$\lim_{k \rightarrow \infty} \max\{d(gx_{m_k}, gx_{n_{k+1}}), d(gy_{m_k}, gy_{n_{k+1}})\} = \epsilon. \quad (6)$$

From (3), we have

$$\begin{aligned} \epsilon &\leq \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} \\ &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{m_{k+1}}).d(gx_{m_{k+1}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{m_{k+1}}).d(gy_{m_{k+1}}, gy_{n_k}) \end{array} \right\} \\ &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{m_{k+1}}).d(gx_{m_{k+1}}, gx_{n_{k+2}}).d(gx_{n_{k+2}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{m_{k+1}}).d(gy_{m_{k+1}}, gy_{n_{k+2}}).d(gy_{n_{k+2}}, gy_{n_k}) \end{array} \right\} \\ &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{m_{k+1}}).d(gx_{m_{k+1}}, gx_{n_{k+2}}).d(gx_{n_{k+2}}, gx_{n_{k+1}}).d(gx_{n_{k+1}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{m_{k+1}}).d(gy_{m_{k+1}}, gy_{n_{k+2}}).d(gy_{n_{k+2}}, gy_{n_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k}) \end{array} \right\} \quad (7) \\ &\leq \max \left\{ \begin{array}{l} (d(gx_{m_k}, gx_{m_{k+1}}))^2.d(gx_{m_k}, gx_{n_k}).(d(gx_{n_{k+2}}, gx_{n_{k+1}}))^2.(d(gx_{n_{k+1}}, gx_{n_k}))^2, \\ (d(gy_{m_k}, gy_{m_{k+1}}))^2.d(gy_{m_k}, gy_{n_k}).(d(gy_{n_{k+2}}, gy_{n_{k+1}}))^2.(d(gy_{n_{k+1}}, gy_{n_k}))^2 \end{array} \right\}. \end{aligned}$$

Letting $k \rightarrow \infty$, using (2), (5) and (7), we have

$$\lim_{k \rightarrow \infty} \max\{d(gx_{m_{k+1}}, gx_{n_{k+2}}), d(gy_{m_{k+1}}, gy_{n_{k+2}})\} = \epsilon. \quad (8)$$

Also from (3), we have

$$\epsilon \leq \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\}$$

$$\begin{aligned}
 &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{n_{k+2}}).d(gx_{n_{k+2}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{n_{k+2}}).d(gy_{n_{k+2}}, gy_{n_k}) \end{array} \right\} \\
 &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{n_{k+2}}).d(gx_{n_{k+2}}, gx_{n_{k+1}}).d(gx_{n_{k+1}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{n_{k+2}}).d(gy_{n_{k+2}}, gy_{n_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k}) \end{array} \right\} \quad (9) \\
 &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{n_k}).(d(gx_{n_{k+2}}, gx_{n_{k+1}}))^2.(d(gx_{n_{k+1}}, gx_{n_k}))^2, \\ d(gy_{m_k}, gy_{n_k}).(d(gy_{n_{k+2}}, gy_{n_{k+1}}))^2.(d(gy_{n_{k+1}}, gy_{n_k}))^2 \end{array} \right\}.
 \end{aligned}$$

Letting $k \rightarrow \infty$, from (2),(5) and (9)

$$\lim_{k \rightarrow \infty} \max\{d(gx_{m_k}, gx_{n_{k+2}}), d(gy_{m_k}, gy_{n_{k+2}})\} = \epsilon. \quad (10)$$

Again from (3), we have

$$\begin{aligned}
 \epsilon &\leq \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} \\
 &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{m_{k+1}}).d(gx_{m_{k+1}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{m_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k}) \end{array} \right\} \\
 &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{m_{k+1}}).d(gx_{m_{k+1}}, gx_{n_{k+1}}).d(gx_{n_{k+1}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{m_{k+1}}).d(gy_{m_{k+1}}, gy_{n_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k}) \end{array} \right\} \quad (11) \\
 &\leq \max \left\{ \begin{array}{l} (d(gx_{m_k}, gx_{m_{k+1}}))^2.d(gx_{m_k}, gx_{n_k}).(d(gx_{n_{k+1}}, gx_{n_k}))^2, \\ (d(gy_{m_k}, gy_{m_{k+1}}))^2.d(gy_{m_k}, gy_{n_k}).(d(gy_{n_{k+1}}, gy_{n_k}))^2 \end{array} \right\}.
 \end{aligned}$$

Letting $k \rightarrow \infty$, from (2),(5) and (11), we have that

$$\lim_{k \rightarrow \infty} \max\{d(gx_{m_{k+1}}, gx_{n_{k+1}}), d(gy_{m_{k+1}}, gy_{n_{k+1}})\} = \epsilon. \quad (12)$$

Now from (3), we get

$$\begin{aligned}
 \epsilon &\leq \max\{d(gx_{m_k}, gx_{n_k}), d(gy_{m_k}, gy_{n_k})\} \\
 &\leq \max\{d(gx_{m_k}, gx_{n_{k+1}}).d(gx_{n_{k+1}}, gx_{n_k}), d(gy_{m_k}, gy_{n_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k})\} \\
 &\leq \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{m_{k+1}}).d(gx_{m_{k+1}}, gx_{n_{k+2}}).d(gx_{n_{k+2}}, gx_{n_{k+1}}).d(gx_{n_{k+1}}, gx_{n_k}), \\ d(gy_{m_k}, gy_{m_{k+1}}).d(gy_{m_{k+1}}, gy_{n_{k+2}}).d(gy_{n_{k+2}}, gy_{n_{k+1}}).d(gy_{n_{k+1}}, gy_{n_k}) \end{array} \right\}.
 \end{aligned}$$

Letting $k \rightarrow \infty$, using (2), we obtain that

$$\epsilon \leq \lim_{k \rightarrow \infty} \max\{d(gx_{m_{k+1}}, gx_{n_{k+2}}), d(gy_{m_{k+1}}, gy_{n_{k+2}})\}.$$

By property of ψ , (5), (6) and (8), we have

$$\psi(\epsilon) \leq \lim_{k \rightarrow \infty} \psi \left(\max\{d(gx_{m_{k+1}}, gx_{n_{k+2}}), d(gy_{m_{k+1}}, gy_{n_{k+2}})\} \right)$$

$$= \lim_{k \rightarrow \infty} \max \{ \psi (d(gx_{m_k+1}, gx_{n_k+2})), \psi (d(gy_{m_k+1}, gy_{n_k+2})) \}. \quad (13)$$

Now we will show that

$$\frac{1}{2} \min \left\{ \begin{array}{l} d(gx_{m_k}, T(x_{m_k}, y_{m_k})), \\ d(gx_{n_k+1}, T(x_{n_k+1}, y_{n_k+1})) \end{array} \right\} \\ \leq \max \{ d(gx_{m_k}, gx_{n_k+1}), d(gy_{m_k}, gx_{n_k+1}) \}.$$

On contrary suppose that

$$\max \{ d(gx_{m_k}, gx_{n_k+1}), d(gy_{m_k}, gx_{n_k+1}) \} \\ < \frac{1}{2} \min \left\{ \begin{array}{l} d(gx_{m_k}, T(x_{m_k}, y_{m_k})), \\ d(gx_{n_k+1}, T(x_{n_k+1}, y_{n_k+1})) \end{array} \right\}.$$

Letting $k \rightarrow \infty$, we have

$$\epsilon \leq \frac{1}{2} \min \{1, 1\} = \frac{1}{2}$$

which is a contradiction.

Hence

$$\frac{1}{2} \min \left\{ \begin{array}{l} d(gx_{m_k}, T(x_{m_k}, y_{m_k})), \\ d(gx_{n_k+1}, T(x_{n_k+1}, y_{n_k+1})) \end{array} \right\} \\ \leq \max \{ d(gx_{m_k}, gx_{n_k+1}), d(gy_{m_k}, gx_{n_k+1}) \}.$$

Similarly

$$\frac{1}{2} \min \left\{ \begin{array}{l} d(gy_{m_k}, T(y_{m_k}, x_{m_k})), \\ d(gy_{n_k+1}, T(y_{n_k+1}, x_{n_k+1})) \end{array} \right\} \\ \leq \max \{ d(gx_{m_k}, gx_{n_k+1}), d(gy_{m_k}, gx_{n_k+1}) \}.$$

Now from (2.1.1), we get

$$\psi (d(T(x_{m_k}, y_{m_k}), T(x_{n_k+1}, y_{n_k+1}))) \leq \frac{\psi (M(x_{m_k}, y_{m_k}, x_{n_k+1}, y_{n_k+1}))}{\phi (M(x_{m_k}, y_{m_k}, x_{n_k+1}, y_{n_k+1}))} \quad (14)$$

where

$$M(x_{m_k}, y_{m_k}, x_{n_k+1}, y_{n_k+1})$$

$$\begin{aligned}
 &= \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{n_{k+1}}), d(gy_{m_k}, gy_{n_{k+1}}), \\ d(gx_{m_k}, T(x_{m_k}, y_{m_k})), d(gy_{m_k}, T(y_{m_k}, x_{m_k})), \\ d(gx_{n_{k+1}}, T(x_{n_{k+1}}, y_{n_{k+1}})), d(gy_{n_{k+1}}, T(y_{n_{k+1}}, x_{n_{k+1}})), \\ \sqrt{d(gx_{m_k}, T(x_{n_{k+1}}, y_{n_{k+1}})) \cdot d(gx_{n_{k+1}}, T(x_{m_k}, y_{m_k}))}, \\ \sqrt{d(gy_{m_k}, T(y_{n_{k+1}}, x_{n_{k+1}})) \cdot d(gy_{n_{k+1}}, T(y_{m_k}, x_{m_k}))} \end{array} \right\} \\
 &= \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{n_{k+1}}), d(gy_{m_k}, gy_{n_{k+1}}), \\ d(gx_{m_k}, gx_{m_{k+1}}), d(gy_{m_k}, gy_{m_{k+1}}), \\ d(gx_{n_{k+1}}, gx_{n_{k+2}}), d(gy_{n_{k+1}}, gy_{n_{k+2}}), \\ \sqrt{d(gx_{m_k}, gx_{n_{k+2}}) \cdot d(gx_{n_{k+1}}, gx_{m_{k+1}})}, \\ \sqrt{d(gy_{m_k}, gy_{n_{k+2}}) \cdot d(gy_{n_{k+1}}, gy_{m_{k+1}})} \end{array} \right\}.
 \end{aligned}$$

But

$$\begin{aligned}
 &\max \left\{ \begin{array}{l} \sqrt{d(gx_{m_k}, gx_{n_{k+2}}) \cdot d(gx_{n_{k+1}}, gx_{m_{k+1}})}, \\ \sqrt{d(gy_{m_k}, gy_{n_{k+2}}) \cdot d(gy_{n_{k+1}}, gy_{m_{k+1}})} \end{array} \right\} \\
 &= \max \left\{ \begin{array}{l} \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{n_{k+2}}), \\ d(gx_{n_{k+1}}, gx_{m_{k+1}}) \end{array} \right\}, \\ \max \left\{ \begin{array}{l} d(gy_{m_k}, gy_{n_{k+2}}), \\ d(gy_{n_{k+1}}, gy_{m_{k+1}}) \end{array} \right\} \end{array} \right\} \\
 &= \max \left\{ \begin{array}{l} d(gx_{m_k}, gx_{n_{k+2}}), \\ d(gx_{n_{k+1}}, gx_{m_{k+1}}), \\ d(gy_{m_k}, gy_{n_{k+2}}), \\ d(gy_{n_{k+1}}, gy_{m_{k+1}}) \end{array} \right\} \\
 &\rightarrow \epsilon \text{ as } k \rightarrow \infty.
 \end{aligned}$$

So that

$$\lim_{k \rightarrow \infty} M(x_{m_k}, y_{m_k}, x_{n_{k+1}}, y_{n_{k+1}}) = \epsilon.$$

Hence letting $k \rightarrow \infty$ in (14), we have that

$$\lim_{k \rightarrow \infty} \psi(d(gx_{m_{k+1}}, gx_{n_{k+2}})) \leq \frac{\psi(\epsilon)}{\phi(\epsilon)}.$$

Similarly

$$\lim_{k \rightarrow \infty} \psi(d(gy_{m_{k+1}}, gy_{n_{k+2}})) \leq \frac{\psi(\epsilon)}{\phi(\epsilon)}.$$

From (13), we have

$$\begin{aligned}\psi(\epsilon) &\leq \frac{\psi(\epsilon)}{\phi(\epsilon)} \\ &< \psi(\epsilon)\end{aligned}$$

which is a contradiction.

Hence $\{gx_n\}$ and $\{gy_n\}$ are Cauchy sequences in the multiplicative metric space (X, d) .

Hence we have

$$\lim_{n,m \rightarrow \infty} d(gx_n, gx_m) = 1 = \lim_{n,m \rightarrow \infty} d(gy_n, gy_m).$$

Suppose $g(X)$ is a complete subspace of X .

Since $\{gx_n\}$ and $\{gy_n\}$ are Cauchy sequence in the multiplicative metric space $(g(X), d)$.

It follows that $\{gx_n\}$ and $\{gy_n\}$ convergent to some α and β in $g(X)$.

Thus

$$\lim_{n \rightarrow \infty} d(gx_n, \alpha) = 1$$

and

$$\lim_{n \rightarrow \infty} d(gy_n, \beta) = 1.$$

Since $\alpha, \beta \in g(X)$, there exist $x, y \in X$ such that $\alpha = gx$ and $\beta = gy$.

Since $\{gx_n\}$ is non - decreasing sequence and $\{gx_n\} \rightarrow \alpha = gx$. It follows that $gx_{n+1} \preceq gx = \alpha$.

Also $\{gy_n\}$ is non - increasing sequence and $\{gy_n\} \rightarrow \beta = gy$. It follows that $gy_{n+1} \succeq gy = \beta$.

Now we claim that for each $n \geq 1$, at least one of the following holds

$$\frac{1}{2} \min \{ d(gx_n, gx_{n+1}), d(gx, T(x, y)) \} \leq \max \{ d(gx_n, gx), d(gy_n, gy) \}$$

or

$$\begin{aligned}\frac{1}{2} \min \{ d(gx_{n+1}, gx_{n+2}), d(gx, T(x, y)) \} \\ \leq \max \{ d(gx_{n+1}, gx), d(gy_{n+1}, gy) \}.\end{aligned}$$

On contrary suppose that

$$\frac{1}{2} \min \{ d(gx_n, gx_{n+1}), d(gx, T(x, y)) \} > \max \{ d(gx_n, gx), d(gy_n, gy) \}$$

and

$$\frac{1}{2} \min \{ d(gx_{n+1}, gx_{n+2}), d(gx, T(x, y)) \} > \max \{ d(gx_{n+1}, gx), d(gy_{n+1}, gy) \}.$$

Now

$$\begin{aligned} d(gx_n, gx_{n+1}) &\leq d(gx_n, gx) \cdot d(gx, gx_{n+1}) \\ &< \frac{1}{2} d(gx_n, gx_{n+1}) \cdot \frac{1}{2} d(gx_{n+1}, gx_{n+2}) \\ &= \frac{1}{4} d(gx_n, gx_{n+1}) \cdot d(gx_{n+1}, gx_{n+2}). \end{aligned}$$

Letting $n \rightarrow \infty$ and using (2), we have

$$1 \leq \frac{1}{4}$$

which is a contradiction.

Hence claim holds.

Sub case (i) : Suppose

$$\frac{1}{2} \min \{ d(gx_n, T(x_n, y_n)), d(gx, T(x, y)) \} \leq \max \{ d(gx_n, gx), d(gy_n, gy) \}.$$

Now we prove that $T(x, y) = \alpha, T(y, x) = \beta$.

From (2.1.1), we get that

$$\psi(d(T(x_n, y_n), T(x, y))) \leq \frac{\psi(M(x_n, y_n, x, y))}{\phi(M(x_n, y_n, x, y))},$$

where

$$\begin{aligned} M(x_n, y_n, x, y) &= \max \left\{ \begin{array}{l} d(gx_n, gx), d(gy_n, gy), d(gx_n, T(x_n, y_n)), \\ d(gy_n, T(y_n, x_n)), d(gx, T(x, y)), d(gy, T(y, x)), \\ \sqrt{d(gx_n, T(x, y)) \cdot d(gx, T(x_n, y_n))}, \\ \sqrt{d(gy_n, T(y, x)) \cdot d(gy, T(y_n, x_n))} \end{array} \right\} \\ &= \max \left\{ \begin{array}{l} d(gx_n, \alpha), d(gy_n, \beta), d(gx_n, T(x_n, y_n)), \\ d(gy_n, T(y_n, x_n)), d(\alpha, T(x, y)), d(\beta, T(y, x)), \\ \sqrt{d(gx_n, T(x, y)) \cdot d(\alpha, T(x_n, y_n))}, \\ \sqrt{d(gy_n, T(y, x)) \cdot d(\beta, T(y_n, x_n))} \end{array} \right\}. \end{aligned}$$

Letting $n \rightarrow \infty$, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} M(x_n, y_n, x, y) &= \max \left\{ 1, 1, 1, 1, d(\alpha, T(x, y)), d(\beta, T(y, x)), \right. \\ &\quad \left. \sqrt{d(\alpha, T(x, y))}, \sqrt{d(\beta, T(y, x))} \right\} \\ &= \max \{ d(\alpha, T(x, y)), d(\beta, T(y, x)) \}. \end{aligned}$$

Thus

$$\psi(d(\alpha, T(x, y))) \leq \frac{\psi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\})}{\phi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\})}.$$

Similarly we can show that

$$\psi(d(\beta, T(y, x))) \leq \frac{\psi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\})}{\phi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\})}.$$

Now consider

$$\begin{aligned} &\psi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\}) \\ &= \max\{\psi(d(\alpha, T(x, y))), \psi(d(\beta, T(y, x)))\} \\ &\leq \frac{\psi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\})}{\phi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\})}. \end{aligned}$$

Therefore

$$\phi(\max\{d(\alpha, T(x, y)), d(\beta, T(y, x))\}) \leq 1.$$

Thus $\alpha = T(x, y) = gx$ and $\beta = T(y, x) = gy$.

Therefore (x, y) is a coupled coincidence point of T and g .

There exist coupled coincidence point of T and g when

$$\begin{aligned} &\frac{1}{2} \min\{d(gx_{n+1}, gx_{n+2}), d(gx, T(x, y))\} \\ &\leq \max\{d(gx_{n+1}, gx), d(gy_{n+1}, gy)\} \end{aligned}$$

holds.

□

Theorem 2.2. *In addition to the hypothesis of Theorem 2.1, suppose that for every $(x, y), (x', y') \in X \times X$, there exists $(u, v) \in X \times X$ such that $(T(u, v), T(v, u))$ is comparable to $(T(x, y), T(y, x))$ and $(T(x', y'), T(y', x'))$.*

Moreover if (T, g) is w - compatible then T and g have a unique common coupled fixed point in $X \times X$.

Proof. From Theorem 2.1, there exists a coupled coincidence point $(x, y) \in X \times X$ of T and g .

Now let (x', y') be another coupled coincidence point of T and g .

That is

$$T(x', y') = gx' \text{ and } T(y', x') = gy'.$$

By additional assumption, there is $(u, v) \in X \times X$ such that $(T(u, v), T(v, u))$ is comparable to $(T(x, y), T(y, x))$ and $(T(x', y'), T(y', x'))$.

Let $u_0 = u, v_0 = v, x_0 = x, y_0 = y, x'_0 = x'$ and $y'_0 = y'$.

Since $T(X \times X) \subseteq g(X)$, we can construct the sequences $\{gu_n\}$, $\{gv_n\}$, $\{gx_n\}$, $\{gy_n\}$, $\{gx'_n\}$ and $\{gy'_n\}$ such that

$$\begin{aligned} gu_{n+1} &= T(u_n, v_n), gv_{n+1} = T(v_n, u_n), \\ gx_{n+1} &= T(x_n, y_n), gy_{n+1} = T(y_n, x_n), \\ gx'_{n+1} &= T(x'_n, y'_n) \text{ and } gy'_{n+1} = T(y'_n, x'_n), n = 0, 1, 2, \dots \end{aligned}$$

Since $(gx, gy) = (T(x, y), T(y, x)) = (gx_1, gy_1)$ and $(T(u, v), T(v, u)) = (gu_1, gv_1)$ are comparable, then $gx \preceq gu_1$, and $gy \succeq gv_1$.

One can show that $gx \preceq gu_n$, and $gy \succeq gv_n$ for all n .

As in the Theorem 2.1, we conclude that $\{gu_{n+1}\} \rightarrow gx$ $\{gv_{n+1}\} \rightarrow gy$.

Analogously, we can show that $\{gu_{n+1}\} \rightarrow gx'$ $\{gv_{n+1}\} \rightarrow gy'$ in $(g(X), d)$.

Since $g(X)$ is complete and $\{gu_{n+1}\}$ converges to gx and gx' , we get $gx = gx'$.

Similarly $gy = gy'$.

Thus if (x, y) and (x', y') are coupled coincidence points of T and g , then

$$T(x, y) = gx = gx' = T(x', y') = \alpha, \text{ say} \quad (15)$$

and

$$T(y, x) = gy = gy' = T(y', x') = \beta, \text{ say.} \quad (16)$$

Since (T, g) is w - compatible, then

$$g\alpha = g(gx) = g(T(x, y)) = T(gx, gy) = T(\alpha, \beta)$$

and

$$g\beta = g(gy) = g(T(y, x)) = T(gy, gx) = T(\beta, \alpha).$$

Hence the pair (α, β) is also coupled coincidence point of T and g .

Thus we have

$$g\alpha = gx \text{ and } g\beta = gy.$$

Therefore

$$\alpha = gx = g\alpha = T(\alpha, \beta) \text{ and } \beta = gy = g\beta = T(\beta, \alpha).$$

Thus (α, β) is a common coupled fixed point of T and g .

Suppose (α^1, β^1) is another common coupled fixed point of T and g .

Then $\alpha^1 = T(\alpha^1, \beta^1) = g\alpha^1$ and $\beta^1 = T(\beta^1, \alpha^1) = g\beta^1$.

Since (α, β) and (α^1, β^1) are coupled coincidence points of T and g , it follows from (15) and (16) that $g\alpha = g\alpha^1$ and $g\beta = g\beta^1$ which implies that $\alpha = \alpha^1$ and $\beta = \beta^1$. Thus (α, β) is the unique common coupled fixed point of T and g . □

Example 2.3. Let $X = [0, 1]$ and $d(x, y) = e^{|x-y|}$ for all $x, y \in X$ then (X, d, \preceq) is a partially ordered complete multiplicative metric space. The ordering \preceq is defined by $x \preceq y \iff x \leq y$. Let $T : X \times X \rightarrow X$ and $g : X \rightarrow X$ be defined by $T(x, y) = \frac{x+y}{2}$ and $g(x) = x$. Then T and g satisfies all the conditions of Theorem 2.1 and Theorem 2.2. Clearly $(0, 0)$ is the unique common coupled fixed point of T and g .

Corollary 2.4. Let (X, d, \preceq) be partially ordered complete multiplicative metric space and let $T : X \times X \rightarrow X$ be mapping satisfying

$$(2.4.1) \quad \frac{1}{2} \min\{d(x, T(x, y)), d(u, T(u, v))\} \leq \max\{d(x, u), d(y, v)\}$$

implies that

$$d(T(x, y), T(u, v)) \leq \max \left\{ \begin{array}{l} d(x, u), d(y, v), d(x, T(x, y)), \\ d(y, T(y, x)), d(u, T(u, v)), d(v, T(v, u)), \\ \sqrt{d(x, T(u, v)) \cdot d(u, T(x, y))}, \\ \sqrt{d(y, T(v, u)) \cdot d(v, T(y, x))} \end{array} \right\}^\lambda,$$

for all $x, y, u, v \in X$, with $x \preceq u, y \succeq u$ and $\lambda \in (0, \frac{1}{2})$

- (2.4.2) (a) If a non- decreasing sequence $\{x_n\} \rightarrow x$ then $x_n \preceq x$ for all n ,
 (b) If a non- increasing sequence $\{y_n\} \rightarrow y$ then $y \preceq y_n$ for all n
 If there exist $x_0, y_0 \in X$ such that $x_0 \preceq T(x_0, y_0)$ and $y_0 \succeq T(y_0, x_0)$, then T have a unique coupled fixed point in $X \times X$.

Proof. The proof of this corollary follows from Theorem 2.1 by taking $\psi(t) = t, \phi(t) = t^{1-\lambda}$ and $g(x) = x$. □

Example 2.5. Let $X = [0, 1]$ and $d(x, y) = 2^{|x-y|}$ for all $x, y \in X$ then (X, d, \preceq) is a partially ordered complete multiplicative metric space. The

ordering \preceq is defined by $x \preceq y \iff x \leq y$. Let $T : X \times X \rightarrow X$ be defined by $T(x, y) = \frac{x+y}{4}$ and $\lambda = \frac{1}{4} \in (0, \frac{1}{2})$. Consider

$$\begin{aligned} d(T(x, y), T(u, v)) &= 2^{\left| \frac{x+y}{4} - \frac{u+v}{4} \right|} \\ &= 2^{\left| \frac{x-u}{4} - \frac{v-y}{4} \right|} \\ &\leq \max \left\{ 2^{\left| \frac{x-u}{4} \right|}, 2^{\left| \frac{y-v}{4} \right|} \right\} \\ &= \max \left\{ 2^{\frac{1}{4}|x-u|}, 2^{\frac{1}{4}|y-v|} \right\} \\ &= \max \left\{ 2^{|x-u|}, 2^{|y-v|} \right\}^{\frac{1}{4}} = \max \{d(x, u), d(y, v)\}^\lambda \\ &\leq \max \left\{ \begin{array}{l} d(x, u), d(y, v), d(x, T(x, y)), \\ d(y, T(y, x)), d(u, T(u, v)), d(v, T(v, u)), \\ \sqrt{d(x, T(u, v)).d(u, T(x, y))}, \\ \sqrt{d(y, T(v, u)).d(v, T(y, x))} \end{array} \right\}^\lambda. \end{aligned}$$

Clearly $(0, 0)$ is the unique coupled fixed point of T .

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