PARAMETER-DEPENDENT CORRECTED SIMPSON’S RULE

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Abstract: We revisit the analysis of the endpoint corrected Simpson’s quadrature rule. We present a parameter-dependent family of Euler-Maclaurin like formulae associated to Simpson’s rule. Using Taylor’s expansions and Peano’s kernels we obtain optimal truncation error bounds. The parameter can be used to increase the order of the truncation error. The process can be applied to any interpolatory quadrature formulae.

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1. Introduction

Any definite integral can be transformed as follows
\[
\int_a^b F(x)dx = \int_{-h}^h f(x)dx,
\]
where \( h = \frac{b-a}{2} \), and \( f(x) = F\left(\frac{a+b}{2} + x\right) \), so we will consider the integral
\[
Q_0(f; h) := \frac{1}{h} \int_{-h}^h f(x)dx
\]
(1)
to be approximated by quadrature rules. More precisely in this paper we start with the Simpson’s rule and present a parameter-dependent family of Euler-
Maclaurin like formulae

\[
\int_{-h}^{h} f(x) \, dx =
\]

\[
h \left[ \left( \frac{1}{3} - 2\lambda \right) f(-h) + \left( \frac{4}{3} + 4\lambda \right) f(0) + \left( \frac{1}{3} - 2\lambda \right) f(h) \right] + \sum_{k=1}^{K} h^{2k} \gamma_{2k}(\lambda) \left[ f^{(2k-1)}(h) - f^{(2k-1)}(-h) \right] + o(h^{n(2K,\lambda)+1})
\]

where \( \lambda \) is a real valued parameter. Moreover \( \lambda \) can be choosen to encrease the degree of accuracy \( n(2K, \lambda) \) of the process. More precisely \( n(2K, \lambda) = 2K + 1 \) for any values of \( \lambda \), except for one value \( \lambda = \lambda_{2K} \) for which \( n(2K, \lambda_{2K}) = 2K + 3 \).

The method we propose to obtain these formulae is based on the degree of accuracy of the processes. We extend the approach proposed in [5, 7]. Our results include those presented in [2, 8], and the method could be extended and applied to other interpolatory quadrature rules [7]. Let us remark that corrected quadrature rules using derivatives at the endpoints of the interval of integration were studied before and are related to Euler-Maclaurin like formulae, see [2, 4, 6, 8, 9] and references therein.

2. Preliminaries

2.1. A Family of Integrals

The basic integral we want to compute is

\[
Q_0(f; h) := \frac{1}{h} \int_{-h}^{h} f(x) \, dx,
\]

and the endpoint correcting terms we are going to use are

\[
Q_{2k}(f; h) := h^{2k-1} \left[ f^{(2k-1)}(h) - f^{(2k-1)}(-h) \right]
\]

\[
= h^{2k-1} \int_{-h}^{h} f^{(2k)}(x) \, dx
\]

for \( k = 1, 2, 3, \ldots \) These expressions share the property

\[
Q_{2k}(x^l; h) = h^l Q_{2k}(x^l; 1)
\]
for $k = 0, 1, 2, \ldots$, and $l = 0, 1, 2, \ldots$ Hence we have

\[ Q_0(1; 1) = 2, \]

and, for $k \geq 1$ and $f(x) = x^l$,

\[ Q_{2k}(x^l; 1) = 0 \]

for $l = 0, 1, 2, \ldots, 2k - 1$. Also, for $l \geq 2k \geq 0$ we have

\[ Q_{2k}(x^l; 1) = \begin{cases} \frac{(2k)!}{l+1} \left( \frac{l+1}{2k} \right) \left[ 1 + (-1)^{l-2k} \right] & \text{for odd } l - 2k, \\ \frac{2(2k)!}{l+1} \left( \frac{l+1}{2k} \right) & \text{for even } l - 2k, \end{cases} \]  

(5)

where we used the notation

\[ \binom{m}{n} = \frac{m!}{n!(m-n)!} \text{ for } 0 \leq n \leq m. \]  

(6)

Hence $Q_{2k}(x^{2l+1}; h) = 0$ for $l = 0, 1, 2, \ldots$

### 2.2. Quadrature Rules

To approximate $Q_{2k}(f; h)$, we consider symmetric quadrature rules of the form

\[ Q_{2k}^{Sim}(f; h) = a(k)f(-h) + b(k)f(0) + a(k)f(h), \]

which have the following properties

\[ Q_{2k}^{Sim}(x^l; h) = h^l Q_{2k}^{Sim}(x^l; 1), \]

and

\[ Q_{2k}^{Sim}(x^{2l+1}; 1) = 0. \]
3. Simpson’s Rules for $Q_0(f; h)$

3.1. Basic Rule

We use the Simpson’s rule

$$Q_0^{Sim}(f; h) := \frac{1}{3} [f(-h) + 4f(0) + f(h)]$$

to approximate $Q_0(f; h)$. The truncation error associated to this process is

$$R_0^{Sim}(f; h) := Q_0(f; h) - Q_0^{Sim}(f; h) = \frac{1}{h} \int_{-h}^{h} f(x)dx - \frac{1}{3} [f(-h) + 4f(0) + f(h)].$$

From the preceding properties, $R_0^{Sim}(x^l; 1) = h^l R_0^{Sim}(x^l; 1)$. By linearity with respect to $f(x)$, the rule is exact for polynomials of degree $\leq 3$ since $R_0^{Sim}(x^l; 1) = 0$ for $l = 0, 1, 2, 3$. For $l \geq 4$, we also have

$$R_0^{Sim}(x^l; 1) = (1 + (-1)^l) \left[ \frac{1}{l+1} - \frac{1}{3} \right]$$

$$= \begin{cases} 
0 & \text{for odd } \ l, \\
2 \left[ \frac{1}{l+1} - \frac{1}{3} \right] & \text{for even } \ l.
\end{cases} \quad (7)$$

3.2. Corrected Rule

Let us define the corrected Simpson’s rule as follows. For $K = 0$ let $Q_{0,0}^{Sim}(f; h) := Q_0^{Sim}(f; h)$, and for $K = 1, 2, \ldots$, let

$$Q_{0,2K}^{Sim}(f; h) := Q_{0,2(K-1)}^{Sim}(f; h) + \sum_{k=1}^{K} \gamma_{0,2k} Q_{2k}(f; h)$$

$$= Q_{0,2(K-1)}^{Sim}(f; h) + \gamma_{0,2K} Q_{2K}(f; h)$$

Its truncation error $R_{0,2K}^{Sim}(f; h)$ is then defined by $R_{0,0}^{Sim}(f; h) := R_0^{Sim}(f; h)$ for $K = 0$, and by

$$R_{0,2K}^{Sim}(f; h) := R_0^{Sim}(f; h) - \sum_{k=1}^{K} \gamma_{0,2k} Q_{2k}(f; h) \quad (8)$$
PARAMETER-DEPENDENT CORRECTED SIMPSON’S RULE

\[ R_{0.2(K-1)}^{Sim}(f; h) = R_{0.2K}^{Sim}(f; h) - \gamma_{0,2K} Q_{2K}(f; h) \]

for \( K = 1, 2, 3, \ldots \) The coefficients \( \gamma_{0,2K} \) are recursively determined by

\[ \gamma_{0,2K} = \frac{R_{0.2(K-1)}^{Sim}(x^{2K}; h)}{Q_{2K}(x^{2}h)} = \frac{R_{0.2(K-1)}^{Sim}(x^{2K}; 1)}{2(2K)!}, \quad (9) \]

in such a way that the corrected method is exact for polynomials of degree \( 2K \). Moreover, since we have \( R_{0,2K}^{Sim}(x^{2l+1}; h) = 0 \) for \( l \geq 0 \), the method is also exact for polynomials of degree \( \leq 2K + 1 \).

We observe that \( \gamma_{0,2} = 0 \) because \( R_{0,0}^{Sim}(x^{2}; 1) = 0 \). In fact, from (8) and (9), the \( \gamma_{0,2K} \)'s are recursively defined by the relation

\[ \frac{2}{3}(K - 1) = \sum_{k=1}^{K} (2k)! \left( \begin{array}{c} 2K + 1 \\ 2k \end{array} \right) \gamma_{0,2k}, \]

and are related to Bernoulli numbers as follows

\[ \gamma_{0,2k} = -\frac{4}{3} \left( \frac{4^{k-1} - 1}{(2k)!} \right) B_{2k} \]

for \( k = 1, 2, \ldots \), where \( B_{2k} \) is the \( 2k \)-th Bernoulli numbers [9]. Table 1 contains examples of values of \( \gamma_{0,2k} \).

So we get the following Euler-Maclaurin like formula for the Simpson’s rule

\[ \frac{1}{h} \int_{-h}^{h} f(x) dx = Q_{0.2K}^{Sim}(f; h) + o(h^{2K+1}), \quad (10) \]

where

\[ Q_{0.2K}^{Sim}(f; h) = \frac{1}{3} [f(-h) + 4f(0) + f(h)] \]

\[ + \sum_{k=2}^{K} h^{2k-1} \gamma_{0,2k} \left[ f^{(2k-1)}(h) - f^{(2k-1)}(-h) \right]. \quad (11) \]

Let us remark that this formula does not contain the endpoint values of the first derivatives, \( f^{(1)}(h) \) and \( f^{(1)}(-h) \), of \( f(x) \).
4. Simpson’s Like Rules for $Q_2(f; h)$

4.1. Basic Rule

In an attempt to include values of the first derivatives of $f(x)$ at the endpoints in the corrected formula, we consider the expression

$$Q_2(f; h) := h \left[ f^{(1)}(h) - f^{(1)}(-h) \right] = h \int_{-h}^{h} f^{(2)}(x) dx,$$

which we would like to approximate as we did for $Q_0(f; h)$ using the nodes of the Simpson’s rule. In fact we consider the rule

$$Q_{2}^{Sim}(f; h) := 2f(-h) - 4f(0) + 2f(h),$$

with its truncation error given by

$$R_{2}^{Sim}(f; h) := Q_2(f; h) - Q_{2}^{Sim}(f; h)$$

$$= h \left[ f^{(1)}(h) - f^{(1)}(-h) \right] - [2f(-h) - 4f(0) + 2f(h)].$$

We have $R_{2}^{Sim}(x^l; h) = h^l R_{2}^{Sim}(x^l; 1)$. By linearity with respect to $f(x)$, the rule is exact for polynomials of degree $\leq 3$ since $R_{2}^{Sim}(x^l; 1) = 0$ for $l = 0, 1, 2, 3$. For $l \geq 4$, we also have

$$R_{2}^{Sim}(x^l; 1) = \begin{cases} 0 & \text{for odd } l, \\ 2[l-2] & \text{for even } l. \end{cases} \quad (12)$$

4.2. Corrected Rule

Let $Q_{2,0}^{Sim}(f; h) := Q_{2}^{Sim}(f; h)$, and for $K = 1, 2, \ldots$, let

$$Q_{2,2K}^{Sim}(f; h) = Q_{2}^{Sim}(f; h) + \sum_{k=1}^{K} \gamma_{2,2k} Q_{2k}(f; h)$$

$$= Q_{2,2(K-1)}^{Sim}(f; h) + \gamma_{2,2K} Q_{2K}(f; h)$$

be the corrected rule.
The truncation error $R_{2,2K}^{Sim}(f; h)$ is then defined by $R_{2,0}^{Sim}(f; h) := R_{2}^{Sim}(f; h)$ for $K = 0$, and by

$$R_{2,2K}^{Sim}(f; h) := R_{2}^{Sim}(f; h) - \sum_{k=1}^{K} \gamma_{2,2k}Q_{2k}(f; h)$$

for $K = 1, 2, 3, \ldots$. The coefficients $\gamma_{2,2k}^{Sim}$ are recursively defined by

$$\gamma_{2,2K}^{Sim} = \frac{R_{2,2(2K-1)}^{Sim}(x^{2K}; h)}{Q_{2K}(x^{2K}; h)} = \frac{R_{2,2(K-1)}^{Sim}(x^{2K-1}; 1)}{2(2K)!},$$

and the corrected method is exact for polynomials of degree $\leq 2K$. We also have $R_{2,2K}^{Sim}(x^{2l+1}; h) = 0$ for $l \geq 0$, and form (13) and (14), the method is exact for polynomial of degree $\leq 2K + 1$.

We observe that $\gamma_{2,2} = 0$ because $R_{2,0}^{Sim}(x^2; 1) = 0$, and the $\gamma_{2,2k}$’s are recursively defined by the relation

$$K - 1 = \frac{1}{2} \sum_{k=1}^{K} \frac{(2k)!}{2K + 1} \left( \frac{2K + 1}{2k} \right) \gamma_{2,2k}.$$

Table 1 contains examples of values of $\gamma_{2,2k}$.

Hence we obtain an Euler-Maclaurin like formula for $Q_2(f; h)$ and $Q_{2K}^{Sim}(f; h)$

$$h \left[ f^{(1)}(h) - f^{(1)}(-h) \right] = Q_{2,2K}^{Sim}(f; h) + o(h^{2K+1}),$$

where

$$Q_{2,2K}^{Sim}(f; h) = 2f(-h) - 4f(0) + 2f(h)$$

$$+ \sum_{k=2}^{K} h^{2k-1} \gamma_{2,2k} \left[ f^{(2k-1)}(h) - f^{(2k-1)}(-h) \right].$$

## 5. A Combination

### 5.1. A Family of Parameter-Dependent Formulae

We get a family of parameter-dependent formulae by taking a combination of (8) and (13) as follows

$$\hat{R}_{2K,\lambda}^{Sim}(f; h) := R_{2,2K}^{Sim}(f; h) - \lambda R_{0,2K}^{Sim}(f; h),$$

where $\lambda$ is a parameter.

\[
\begin{array}{|c|c|c|c|}
\hline
2K & 2 & 4 & 6 \\
\hline
\gamma_{0,2K} & 0 & \frac{1}{180} & \frac{1}{1512} \\
\gamma_{2,2K} & 0 & \frac{1}{12} & -\frac{1}{120} \\
\hline
\end{array}
\]

Table 1: Examples of \(\gamma_{0,2K}\) and \(\gamma_{2,2K}\).

which is exact for polynomials of degree up to \(2K + 1\) for any \(\lambda\). We get the parameter-dependent Euler-Maclaurin like formula

\[
\frac{1}{h} \int_{-h}^{h} f(x) dx = \hat{Q}_{2K,\lambda}^{\text{Sim}}(f, h) + o(h^{2K+1}),
\]

where

\[
\hat{Q}_{2K,\lambda}^{\text{Sim}}(f, h) = Q_{0,2K}^{\text{Sim}}(f, h) + \lambda R_{2,2K}^{\text{Sim}}(f; h)
\]

\[
= \left[ \left( \frac{1}{3} - 2\lambda \right) f(-h) + \left( \frac{4}{3} + 4\lambda \right) f(0) + \left( \frac{1}{3} - 2\lambda \right) f(h) \right] \\
+ \sum_{k=1}^{K} h^{2k-1} \hat{\gamma}_{2k}(\lambda) \left[ f^{(2k-1)}(h) - f^{(2k-1)}(-h) \right],
\]

and

\[
\hat{\gamma}_{2k}(\lambda) = \begin{cases} 
\lambda & \text{for } k = 1, \\
\gamma_{0,2k} - \lambda \gamma_{2,2k} & \text{for } k = 2, \ldots, K.
\end{cases}
\]

5.2. Increasing Error Order

To increase the error order we can select \(\lambda\) in such a way that (17) be exact also for polynomials of degree up to \(2K + 3\). The new expression will contain the endpoint values of the first derivatives \(f^{(1)}(x)\) of \(f(x)\), \(f^{(1)}(-h)\) and \(f^{(1)}(h)\), without adding new endpoint values of higher order derivatives of \(f(x)\).

Indeed let us consider \(\lambda = \lambda_{2K}\) given by

\[
\lambda_{2K} = \frac{R_{0,2K}^{\text{Sim}}(x^{2(K+1)}; h)}{R_{2,2K}^{\text{Sim}}(x^{2(K+1)}; h)} = \frac{R_{0,2K}^{\text{Sim}}(x^{2(K+1)}; 1)}{R_{2,2K}^{\text{Sim}}(x^{2(K+1)}; 1)}.
\]
This value is well defined if
\[ R_{2,2K}^{Sim}(x^{2(K+1)}; h) = h^{2(K+1)} R_{2,2K}^{Sim}(x^{2(K+1)}; 1) \neq 0. \]

But it is easy to show that there exists a polynomial \( p_{2K+2}(x) \) of degree \( 2K+2 \) such that
\[
\begin{cases}
    p_{2K+2}(-1) = p_{2K+2}(0) = p_{2K+2}(1) = 0, \\
    p_{2K+2}^{(1)}(-1) = -p_{2K+2}^{(1)}(1) = 1, \\
    p_{2K+2}^{(2k-1)}(-1) = -p_{2K+2}^{(2k-1)}(1) = 0 \quad \text{for} \quad k = 2, 3, 4, \ldots, K,
\end{cases}
\]
from which we get \( R_{2,2K}^{Sim}(p_{2K+2}(x); 1) = 2 \neq 0 \). This fact implies that
\[ R_{2,2K}^{Sim}(x^{2(K+1)}; 1) \neq 0. \]

Finally we obtain the Euler-Maclaurin like formula
\[
\frac{1}{h} \int_{-h}^{h} f(x) \, dx = \hat{Q}_{2K,\lambda_{2K}}^{Sim}(f, h) + o(h^{2K+3}).
\]

Examples of values of \( \lambda_{2K} \) are given in Table 2. The corresponding coefficients of the 3-points quadrature rule are given in Table 3, and the corresponding \( \hat{\gamma}_{2k}(\lambda) \) are given in Table 4.

<table>
<thead>
<tr>
<th>2K</th>
<th>2</th>
<th>4</th>
<th>6</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>( R_{0,2K}^{Sim}(x^{2(K+1)}; 1) )</td>
<td>-4/15</td>
<td>20/21</td>
<td>28/5</td>
<td>1700/33</td>
</tr>
<tr>
<td>( R_{2,2K}^{Sim}(x^{2(K+1)}; 1) )</td>
<td>4</td>
<td>-12</td>
<td>68</td>
<td>-620</td>
</tr>
<tr>
<td>( \lambda_{2K} )</td>
<td>-1/15</td>
<td>-5/63</td>
<td>7/85</td>
<td>-85/1023</td>
</tr>
</tbody>
</table>

Table 2: Examples of values to compute \( \lambda_{2K} \).
\[
\begin{array}{|c|c|c|c|c|}
\hline
2K & \lambda_{2K} & \frac{1}{3} - 2\lambda_{2K} & \frac{4}{3} + 4\lambda_{2K} & \frac{1}{3} - 2\lambda_{2K} \\
\hline
2 & -\frac{1}{15} & \frac{7}{15} & \frac{16}{15} & \frac{7}{15} \\
4 & -\frac{5}{63} & \frac{31}{63} & \frac{64}{63} & \frac{31}{63} \\
6 & -\frac{7}{85} & \frac{127}{255} & \frac{256}{255} & \frac{127}{255} \\
8 & -\frac{85}{1023} & \frac{1533}{3069} & \frac{3072}{3069} & \frac{1533}{3069} \\
\hline
\end{array}
\]

Table 3: Values of $\lambda_{2K}$ and the corresponding coefficients of the 3-points quadrature rule.

\[
\gamma_{2k}(\lambda_{2K}) \text{ for } k = 1, \ldots, K
\]

\[
\begin{array}{|c|c|c|c|}
\hline
2k & 2 & 4 & 6 \\
\hline
2K & 2 & 4 & 6 & 8 \\
\hline
2 & -\frac{1}{15} & & & \\
4 & -\frac{5}{63} & \frac{1}{945} & & \\
6 & -\frac{7}{85} & \frac{1}{765} & -\frac{2}{80325} & \\
8 & -\frac{85}{1023} & \frac{7}{5115} & -\frac{2}{64449} & \frac{1}{1611225} \\
\hline
\end{array}
\]

Table 4: Values of $\tilde{\gamma}_{2k}(\lambda_{2K})$. 
6. Truncation Error and Taylor’s Expansion

In this section we establish optimal error bounds for appropriate function spaces which allow Taylor’s expansions.

6.1. Function Spaces

Let $p$ and $q$ be two real numbers such that $1 \leq p, q \leq \infty$ and $\frac{1}{p} + \frac{1}{q} = 1$. For an interval $E \subseteq \mathbb{R}$, let $C^l(E)$ be the set of continuously differentiable functions up to order $l$ on $E$, and $L^p(E)$ be the set of $p$-integrable functions on $E$. Let $AC^{l+1,p}(E)$ be the set of absolutely continuous functions on $E$ defined by:

\[ f \in AC^{l+1,p}(E) \text{ if and only if } f \in C^l(E) \]

and

\[
\begin{cases} 
(a) & f^{(l+1)} \in L^p(E), \quad \text{and} \\
(b) & f^{(l)}(s) = f^{(l)}(r) + \int_r^s f^{(l+1)}(\xi) d\xi, \quad \forall r, s \in E.
\end{cases}
\]

6.2. Taylor’s Expansion

Let $I_h = [-h, h]$, for $h = 1$ we will simply use $I = [-1, 1]$. Taylor’s expansion of $f(x) \in AC^{l+1,p}(I_h)$ around $x = 0$ of order $l + 1$ is

\[ f(x) = \sum_{j=0}^{l} \frac{f^{(j)}(0)}{j!} x^j + \int_{-h}^{h} f^{(l+1)}(y) K_{T,l}(x, y; h) dy, \]

where $K_{T,l}(x, y; h)$ is the kernel

\[ K_{T,l}(x, y; h) = \frac{1}{l!} \left[ (x-y)^l \mathbf{1}_{[0,h]}(y) + (-1)^{l+1}(y-x)^l \mathbf{1}_{[-h,0]}(y) \right], \]

for any $x, y$ in $I_h$ (see [3, 10]). This kernel is a piecewise polynomial function of degree $l$. If we set $x = h\xi$, and $y = h\eta$, then the kernel becomes

\[ K_{T,l}(x, y; h) = K_{T,l}(h\xi, h\eta; h) = h^l K_{T,l}(\xi, \eta; 1), \]

for any $\xi, \eta$ in $I$.

6.3. Best Error Bounds

We can now obtain best bounds for these processes.
Theorem 1. Let us assume that \( f(x) \in AC^{n(2K,\lambda)+1,p}(I_h) \), where \( n(2K, \lambda) \geq 2K \) is the degree of accuracy of \( \hat{R}_{2K,\lambda}^{Sim}(f;h) \). Then there exists a constant \( C_{2K}^{Sim}(\lambda) \) such that
\[
\left| \hat{R}_{2K,\lambda}^{Sim}(f;h) \right| \leq h^{n(2K,\lambda)+1-\frac{1}{p}} C_{2K}^{Sim}(\lambda) \left\| f^{(n(2K,\lambda)+1)} \right\|_{p,I_h}. \tag{19}
\]

Proof. Since the process is exact for polynomials of degree \( \leq n(2K, \lambda) \), using a Taylor’s expansion of order \( n(2K, \lambda) + 1 \), we obtain
\[
\hat{R}_{2K,\lambda}^{Sim}(f;h) = \int_{-h}^{h} f^{(n(2K,\lambda)+1)}(y) \hat{K}_{2K,\lambda}^{Sim}(y;h) dy,
\]
where the Peano’s kernel \( \hat{K}_{2K,\lambda}^{Sim}(y;h) = \hat{K}_{2K,\lambda}^{Sim}(K_{T,n(2K,\lambda)}(\cdot, y;h);h) \). We observe that
\[
\hat{K}_{2K,\lambda}^{Sim}(y;h) = h^{n(2K,\lambda)} \hat{K}_{2K,\lambda}^{Sim}(\eta;1).
\]
So
\[
\left\| \hat{K}_{2K,\lambda}^{Sim}(y;h) \right\|_{q,I_h} = h^{n(2K,\lambda)+1-\frac{1}{p}} \left\| \hat{K}_{2K,\lambda}^{Sim}(\eta;1) \right\|_{q,I},
\]
and we get (19) where
\[
C_{2K}^{Sim}(\lambda) = \left\| \hat{K}_{2K,\lambda}^{Sim}(\eta;1) \right\|_{q,I} \tag{20}
\]
does not depend on \( h \).
\[ \square \]

Since we have
\[
\lim_{h \to 0} \left\| f^{(n(2K,\lambda)+1)} \right\|_{p,I_h} = \begin{cases} 0 & \text{for } 1 \leq p < \infty, \\ C & \text{for } p = \infty, \end{cases}
\]
this result says that
\[
\hat{R}_{2K,\lambda}^{Sim}(f;h) = \begin{cases} o \left( h^{n(2K,\lambda)+1-\frac{1}{p}} \right) & \text{for } 1 \leq p < \infty, \\ O \left( h^{n(2K,\lambda)+1} \right) & \text{for } p = \infty, \end{cases} \tag{21}
\]
Since an \( o \left( h^{n(2K,\lambda)+1-\frac{1}{p}} \right) \) or an \( O \left( h^{n(2K,\lambda)+1} \right) \) is an \( o \left( h^{n(2K,\lambda)} \right) \), (21) means that \( \hat{R}_{2K,\lambda}^{Sim}(f;h) = o \left( h^{n(2K,\lambda)} \right) \).

Remark 2. Using a standard construction [1, 5], it can be shown that the bounds given by (19) and (20) are the best bounds.
7. Application to other Quadrature Rules

7.1. Simpson’s 3/8 Rule

As an example of application to other methods, we can consider the Simpson’s 3/8 rule given by

\[ Q^{Sim}_0(f; h) := \frac{1}{4} \left[ f(-h) + 3f(-h/3) + 3f(h/3) + f(h) \right], \]

and its corresponding expression for the correcting term \( Q^2_2(f; h) \)

\[ Q^{Sim}_2(f; h) := \frac{9}{4} \left[ f(-h) - f(-h/3) + f(h/3) + f(h) \right]. \]

Both expressions are exact for polynomials of degree \( \leq 3 \), and the approach of this paper can be applied directly (see also [2]).

7.2. Interpolatory Quadrature Rules

Simpson’s rules are examples of Newton-Cotes formula which are themself examples of interpolatory symmetric quadrature rules. It is clear that the preceding approach can be applied to any other quadrature formula of this type, and the correction might use not only one parameter and \( Q^2_2(f; h) \) but several parameters and expressions \( Q^{2k}_k(f; h) \) depending on the degree of accuracy of the basic formula used.

References

